A canonical treatment of line bundles over general projective spaces

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Abstract

Projective spaces for finite-dimensional vector spaces over general fields are considered. The geometry of these spaces and the theory of line bundles over these spaces is presented. Particularly, the space of global regular sections of these bundles is examined. Care is taken in two directions: (1) places where algebraic closedness of the field are important are pointed out; (2) basis free constructions are used exclusively.

1. Introduction

Line bundles over projective space provide an easy venue to explore the relationships between geometry and algebra. In this note we present this theory in a general way, working with projective spaces over arbitrary fields and using basis-independent constructions. We also think carefully about the spaces of sections of these line bundles, paying attention to the rôle of regularity and algebraic closedness. We see that there are no nontrivial global sections of the negative degree line bundles over projective spaces for algebraically closed fields. However, for real projective space, the negative degree line bundles do have nontrivial global sections. This character mirrors the differences in complex and real line bundles in the holomorphic and real analytic categories, respectively. Specifically, while there are few or no holomorphic sections of line bundles over complex projective space, the space of real analytic sections of line bundles over real projective space is large, guaranteed by the real analytic version of Cartan’s Theorem A [Cartan 1957].

Throughout this note, we shall use differential geometric language such as “vector bundle” and “section,” even though we are not in the setting of differential geometry. This should not cause confusion, as a quick mental translation into the real or complex case should make all such statements seem reasonable, or at least understandable.

Some of the topics we discuss concerning affine and projective spaces are dealt with nicely in the book of Berger [1987].

2. Affine space

Intuitively, an affine space is a “vector space without an origin.” In an affine space, one can add a vector to an element, and one can take the difference of two elements to get a vector. But one cannot add two elements. Precisely, we have the following definition.
2.1 Definition: Let $F$ be a field and let $V$ be an $F$-vector space. An affine space modelled on $V$ is a set $A$ and a map $\phi: V \times A \to A$ with the following properties:

(i) for every $x, y \in A$ there exists an $v \in V$ such that $y = \phi(v, x)$ (transitivity);
(ii) $\phi(v, x) = x$ for every $x \in A$ implies that $v = 0$ (faithfulness);
(iii) $\phi(0, x) = x$, and
(iv) $\phi(u + v, x) = \phi(u, \phi(v, x))$.

The notation $x + v$ if often used for $\phi(v, x)$ and, for $x, y \in A$, we denote by $y - x \in V$ the unique vector such that $\phi(y - x, x) = y$. 

An affine space is “almost” a vector space. The following result says that, if one chooses any point in an affine space as an “origin,” then the affine space becomes a vector space.

2.2 Proposition: Let $A$ be an affine space modelled on the $F$-vector space $V$. For $x_0 \in A$ define vector addition on $A$ by

$$x_1 + x_2 = x_0 + ((x_1 - x_0) + (x_2 - x_0))$$

and scalar multiplication on $A$ by

$$ax = x_0 + (a(x - x_0)).$$

These operations make $A$ into an $F$-vector space and the map $x \mapsto x - x_0$ is an isomorphism of this $F$-vector space with $V$.

Proof: The boring verification of the satisfaction of the vector space axioms we leave to the reader. To verify that the map $x \mapsto x - x_0$ is a vector space isomorphism, compute

$$(x_1 + x_2) - x_0 = (x_0 + ((x_1 - x_0) + (x_2 - x_0))) - x_0 = (x_1 - x_0) + (x_2 - x_0)$$

and

$$ax - x_0 = (x_0 + (a(x - x_0))) - x_0 = a(x - x_0),$$

as desired. 

Let us denote by $A_{x_0}$ the set $A$ with the vector space structure obtained by taking $x_0$ as the origin, and let $\Phi_{x_0}: A_{x_0} \to V$ be the isomorphism defined in Proposition 2.2. Note that we have

$$\Phi_{x_0}(x) = x - x_0, \quad \Phi_{x_0}^{-1}(v) = x_0 + v.$$

We shall use these formulae below. We have the notion of an affine subspace of an affine space.

2.3 Definition: Let $V$ be an $F$-vector space and let $A$ be an affine space modelled on $V$ with $\phi: V \times A \to A$ the map defining the affine structure. A subset $B$ of $A$ is an affine subspace if there is a subspace $U$ of $V$ with the property that $\phi|\{(U \times B)\}$ takes values in $B$. 

Let us give a list of alternative characterisations of affine subspaces.
2.4 Proposition: Let $A$ be an affine space modelled on the $F$-vector space $V$ and let $B \subset A$. The following statements are equivalent:

(i) $B$ is an affine subspace of $A$;
(ii) there exists a subspace $U$ of $V$ such that, for each $x_0 \in B$, $B = \{x_0 + u \mid u \in U\}$;
(iii) if $x_0 \in B$ then $\{y - x_0 \mid y \in B\} \subset V$ is a subspace.

Proof: (i) $\Rightarrow$ (ii) Let $B \subset A$ be an affine subspace and let $U \subset V$ be a subspace for which $\phi|(U \times B)$ takes values in $B$. Let $x_0 \in B$. For $y \in B$ there exists a unique $u \in V$ such that $y = x_0 + u$. Since $\phi|(U \times B)$ takes values in $B$ it follows that $u \in U$. Therefore,

$$B \subset \{x_0 + u \mid u \in U\},$$

and so giving this part of the result.

(ii) $\Rightarrow$ (iii) Let $U \subset V$ be a subspace for which, for each $x_0 \in B$, $B = \{x_0 + u \mid u \in U\}$. Obviously, $\{y - x_0 \mid y \in B\} = U$ and so this part of the result follows.

(iii) $\Rightarrow$ (i) Let $x_0 \in B$ and denote $U = \{y - x_0 \mid y \in B\}$; by hypothesis, $U$ is a subspace. Moreover, for $u \in U$ and $y \in B$ we have

$$\phi(u, y) = \phi(u, x_0 + (y - x_0)) = x_0 + (u + y - x_0) \in B,$$

giving the result.

We have the notion of a map between affine spaces.

2.5 Definition: If $A$ and $B$ are affine spaces modelled on $F$-vector spaces $V$ and $U$, respectively, a map $\phi: A \to B$ is an affine map if, for some $x_0 \in A$, $\phi$ is a linear map between the vector spaces $A_{x_0}$ and $B_{\phi(x_0)}$.

Associated with an affine map is an induced linear map between the corresponding vector spaces.

2.6 Proposition: Let $V$ and $U$ be $F$-vector spaces, let $A$ and $B$ be affine spaces modelled on $V$ and $U$, respectively, and let $\phi: A \to B$ be an affine map. Let $x_0 \in A$ be such that $\phi \in \text{Hom}_F(A_{x_0}; B_{\phi(x_0)})$. Then the map $L(\phi): V \to U$ defined by

$$L(\phi)(v) = \phi(x_0 + v) - \phi(x_0)$$

is linear. Moreover,

(i) if $x_1, x_2 \in A$ are such that $x_2 = x_1 + v$, then $L(\phi)(v) = \phi(x_2) - \phi(x_1)$ and
(ii) if $x'_0 \in A$ then $\phi(x) = \phi(x'_0) + L(\phi)(x - x'_0)$ for every $x \in V$.

Proof: Note that $L(\phi) = \Phi_{\phi(x_0)} \circ \phi \circ \Phi_{x_0}^{-1}$. Linearity of $L(\phi)$ follows since all maps in the composition are linear.

(i) Now let $x_1, x_2 \in A$ and denote $v = x_2 - x_1$. Write $x_1 = x_0 + v_1$ and $x_2 = x_0 + v_2$ for $v_1, v_2 \in V$. Then

$$v_2 - v_1 = (x_0 + v_2) - (x_0 + v_1) = x_2 - x_1 = v,$$
and so
\[
\phi(x_2) - \phi(x_1) = \phi(x_0 + v_2) - \phi(x_0 + v_1) \\
= (\phi(x_0) + \phi(x_0 + v_2)) - (\phi(x_0) + \phi(x_0 + v_1)) \\
= (\phi(x_0 + v_2) - \phi(x_0)) - (\phi(x_0 + v_1) - \phi(x_0)) \\
= \Phi \phi(x_0) \circ \phi \circ \Phi^{-1}(v_2) - \Phi \phi(x_0) \circ \phi \circ \Phi^{-1}(v_1) \\
= L(\phi)(v_2 - v_1) = L(\phi)(v),
\]
as desired.

(ii) By the previous part of the result,
\[
L(\phi)(x - x'_0) = \phi(x) - \phi(x'_0),
\]
from which the result follows by rearrangement.

The linear map \(L(\phi)\) is called the \textit{linear part} of \(\phi\). The last assertion of the proposition says that an affine map is determined by its linear part and what it does to a single element in its domain.

It is possible to give a few equivalent characterisations of affine maps.

\textbf{2.7 Proposition:} Let \(V\) and \(U\) be \(F\)-vector spaces, let \(A\) and \(B\) be affine spaces modelled on \(U\) and \(V\), respectively, and let \(\phi : A \to B\) be a map. Then the following statements are equivalent:

(i) \(\phi\) is an affine map;

(ii) \(\phi \in \text{Hom}_F(A_{x_0}; B_{\phi(x_0)})\) for every \(x_0 \in A\);

(iii) \(\Phi \phi(x_0) \circ \phi \circ \Phi^{-1} \in \text{Hom}_F(V; U)\) for some \(x_0 \in V\);

(iv) \(\Phi \phi(x_0) \circ \phi \circ \Phi^{-1} \in \text{Hom}_F(V; U)\) for all \(x_0 \in V\).

\textbf{Proof:} (i) \(\implies\) (ii) By Proposition 2.6 we have
\[
\phi(x) = \phi(x_0) + L(\phi)(x - x_0)
\]
for every \(x, x_0 \in A\), and from this the result follows.

(ii) \(\implies\) (iii) This follows immediately from Proposition 2.6.

(iii) \(\implies\) (iv) This also follows immediately from Proposition 2.6.

(iv) \(\implies\) (i) Let \(x_0 \in A\). Define a linear map \(L(\phi) = \Phi \phi(x_0) \circ \phi \circ \Phi^{-1}\). Then
\[
\phi(x) = \phi(x_0) + L(\phi)(x - x_0).
\]
Clearly, then, \(\phi\) is an affine map.

\section{Projective space}

We let \(F\) be a field and \(V\) a finite-dimensional \(F\)-vector space. A \textit{line} in \(V\) is a one-dimensional subspace, typically denoted by \(L\). By \(\mathbb{P}(V)\) we denote the set of lines in \(V\). Equivalently, \(\mathbb{P}(V)\) is the set of equivalence classes in \(V \setminus \{0\}\) under the equivalence relation \(v_1 \sim v_2\) if \(v_2 = av_1\) for \(a \in F \setminus \{0\}\). We call \(\mathbb{P}(V)\) the \textit{projective space} of \(V\). If \(v \in V \setminus \{0\}\)
we denote by \([v]\) the line generated by \(v\). We can thus denote a point in \(\mathbb{P}(V)\) in two ways: (1) by \([v]\) when we wish to emphasise that a line is a line through a point in \(V\); (2) by \(L\) when we wish to emphasise that a line is a vector space.

We will study a family \(\mathcal{O}_{\mathbb{P}(V)}(d), \ d \in \mathbb{Z}\), of line bundles over \(\mathbb{P}(V)\). We shall refer to the index \(d\) as the \textit{degree} of the line bundles. The simplest of these line bundles occurs for \(d = 0\), in which case we have the trivial bundle

\[
\mathcal{O}_{\mathbb{P}(V)}(0) = \mathbb{P}(V) \times F.
\]

We have the obvious projection

\[
\pi_{\mathbb{P}(V)}^{(0)} : \mathcal{O}_{\mathbb{P}(V)}(0) \to \mathbb{P}(V) \quad \quad ([v], a) \mapsto [v].
\]

The study of the line bundles of nonzero degree in a comprehensive and elegant way requires some development of projective geometry.

### 3.1. The affine structure of projective space minus a projective hyperplane.

At a few points in this note we shall make use of a particular affine structure, and in this section we describe this. The discussion is initiated with the following lemma.

**3.1 Lemma:** If \(F\) is a field, if \(V\) is an \(F\)-vector space, and if \(U \subset V\) is a subspace of codimension 1, then the set \(\mathbb{P}(V) \setminus \mathbb{P}(U)\) is an affine space modelled on \(\text{Hom}_F(V/U; U)\).

**Proof:** Let \(\pi_U : V \to V/U\) be the canonical projection. For \(v + U \in V/U\), \(\pi_U^{-1}(v + U)\) is an affine subspace of the affine space \(V\) modelled on \(U\), as is easily checked. Moreover, if \(L\) is a complement to \(U\), then \(\pi_U|L\) is an isomorphism. Now, if \(v + U \in V/U\) and if \(L_1\) and \(L_2\) are two complements to \(U\), note that

\[
(\pi_U|L_1)^{-1}(v + U) - (\pi_U|L_2)^{-1}(v + U) \in U
\]

since

\[
\pi_U((\pi_U|L_1)^{-1}(v + U) - (\pi_U|L_2)^{-1}(v + U)) = (v + U) - (v + U) = 0.
\]

Moreover, the map

\[
V/U \ni v + U \mapsto (\pi_U|L_1)^{-1}(v + U) - (\pi_U|L_2)^{-1}(v + U) \in U \quad (3.1)
\]

is in \(\text{Hom}_F(V/U; U)\). We, therefore, define the affine structure on \(\mathbb{P}(V) \setminus \mathbb{P}(U)\) by defining subtraction of elements of \(\mathbb{P}(V) \setminus \mathbb{P}(U)\) as elements of the model vector space by taking \(L_1 - L_2\) to be the element of \(\text{Hom}_F(V/U; U)\) given in (3.1). It is now a simple exercise to verify that this gives the desired affine structure.

To make the lemma more concrete and to connect it with standard constructions in the treatment of projective spaces, in the setting of the lemma, we let \(O \in \mathbb{P}(V) \setminus \mathbb{P}(U)\), let \(e_O \in O \setminus \{0\}\), and, for \(v \in V\), write \(v = v_O e_O + v_U\) for \(v_O \in F\) and \(v_U \in U\). With this notation, we have the following result.
3.2 Lemma: The map
\[ \phi_{U,O} : \mathbb{P}(V) \setminus \mathbb{P}(U) \to U \]
\[ [v] \mapsto v_O^{-1}v_U \]
is an affine space isomorphism mapping \( O \) to zero.

Proof: Let \( [v] \in \mathbb{P}(V) \setminus \mathbb{P}(U) \) and write \( e_O \) in its \([v]\)- and \( U\)-components:
\[ e_O = \alpha(v_O e_O + v_U) + v'_U, \]
for \( v'_U \in U \). Evidently, \( \alpha = v_O^{-1} \) and \( v'_U = v_O^{-1}v_U \). According to the proof of Lemma 3.1, if \( w + U \in V/U \), then
\[ ([v] - O)(w + U) = ([v_O e_O + v_U] - [e_O])(w_O e_O + U) \]
\[ = (w_O e_O)_{[v]} - w_O e_O \]
\[ = w_O(e_O + v_O^{-1}v_U) - w_O e_O \]
\[ = w_O v_O^{-1}v_U, \]
where \((w_O e_O)_{[v]}\) denotes the \([v]\)-component of \( w_O e_O \).

We now verify that \( \phi_{U,O} \) is affine by using Proposition 2.7. Let \([v_1], [v_2] \in \mathbb{P}(V) \setminus \mathbb{P}(U) \). Then, for \( w + U \in V/U \),
\[ (([v_1] - O) + ([v_2] - O))(w + U) = w_O(v_{1,O}^{-1}v_{1,U} - v_{2,O}^{-1}(v_{2,U})) \]
and so
\[ O + (([v_1] - O) + ([v_2] - O)) = [e_O + v_{1,O}^{-1}v_{1,U} + v_{2,O}^{-1}v_{2,U}] \].
Thus, using the vector space structure on \( \mathbb{P}(V) \setminus \mathbb{P}(U) \) determined by the origin \( O \),
\[ \phi_{U,O}([v_1] + [v_2]) = \phi_{U,O}(O + ([v_1] - O) + ([v_2] - O)) \]
\[ = v_{1,O}^{-1}v_{1,U} + v_{2,O}^{-1}v_{2,U} \]
\[ = \phi_{U,O}([v_1]) + \phi_{U,O}([v_2]). \]
Also,
\[ a([v] - O) = w_O a v_O^{-1}v_U \]
which gives
\[ O + a([v] - O) = [v_O e_O + av_U]. \]
Therefore,
\[ \phi_{U,O}(a[v]) = \phi_{U,O}(O + a([v] - O)) = av_O^{-1}v_U = a\phi_{U,O}([v]), \]
showing that \( \phi_{U,O} \) is indeed a linear map from \( \mathbb{P}(V) \setminus \mathbb{P}(U) \) to \( U \) with origins \( O \) and 0, respectively.

Finally, we show that \( \phi_{U,O} \) is an isomorphism. Suppose that \( \phi_{U,O}([v]) = 0 \), meaning that \( v_O^{-1}v_U = 0 \). This implies that \( v_U = 0 \) and so \( v \in O \), showing that \( \phi_{U,O} \) is injective. Since the dimensions of the domain and codomain of \( \phi_{U,O} \) agree, the result follows. ■

Next let us see how, if we exclude two distinct hyperplanes, one can compare the two affine structures.
3.3 Lemma: Let $F$ be a field, let $V$ be a finite-dimensional $F$-vector space, and let $U_1, U_2 \subset V$ be distinct codimension 1 subspaces, let $O_j \in \mathbb{P}(V) \setminus \mathbb{P}(U_j)$, $j \in \{1, 2\}$, let $e_{O_j} \in O_j \setminus \{0\}$, and let $\phi_{U_j, O_j} : \mathbb{P}(V) \setminus \mathbb{P}(U_j) \to U_j$, $j \in \{1, 2\}$, be the isomorphisms of Lemma 3.2. Then

$$\phi_{U_2, O_2} \circ \phi_{U_1, O_1}^{-1}(u_1) = (e_{O_1} + u_1)_{O_2}^{-1}(e_{O_1} + u_1)u_2,$$

where $(e_{O_1} + u_1)_{O_2}$ is the $O_2$-component and $(e_{O_1} + u_1)_{U_2}$ is the $U_2$-component, respectively, of $e_{O_1} + u_1$.

If, furthermore, $O_1 \in \mathbb{P}(U_2)$ and $O_2 \in \mathbb{P}(U_1)$, then the formula simplifies to

$$\phi_{U_2, O_2} \circ \phi_{U_1, O_1}^{-1}(u_1) = u_1^{-1}(e_{O_1} + u_1)_{U_2}, \quad u_1 \in \phi_{U_1, O_1}(\mathbb{P}(V) \setminus \mathbb{P}(U_2)),$$

where $u_1_{U_2}$ is the $O_2$-component and $u_1_{U_2}$ is the $U_2$-component, respectively, of $u_1$.

Proof: This follows by direct computation using the definitions. ■

Let us consider an important special case of the preceding developments to the standard covering of projective space by affine open sets.

3.4 Example: We let $V = F^{n+1}$ and denote a point in $V$ by $(a_0, a_1, \ldots, a_n)$. We follow the usual convention and denote by $[a_0 : a_1 : \cdots : a_n]$ the line through $(a_0, a_1, \ldots, a_n)$. For $j \in \{0, 1, \ldots, n\}$ we denote by $U_j$ the subspace

$$U_j = \{(a_0, a_1, \ldots, a_n) \in V \mid a_j = 0\}.$$

Note that $U_j$ is isomorphic to $F^n$ in a natural way, and we make this identification without explicit mention. For each $j \in \{0, 1, \ldots, n\}$ we denote $O_j = \text{span}_F(e_j)$, $j \in \{0, 1, \ldots, n\}$, where $e_j$ is the $j$th (according to our numbering system starting with “0”) standard basis vector for $V$. Note that $O_j \subset U_k$ for $j \neq k$, as prescribed by the hypotheses of Lemma 3.3.

With this as buildup, we then have

$$\phi_{U_j, O_j}([a_0 : a_1 : \cdots : a_n]) = a_j^{-1}(a_0, a_1, \ldots, a_{j-1}, a_{j+1}, \ldots, a_n).$$

We can also verify that, if $j, k \in \{0, 1, \ldots, n\}$ satisfy $j < k$, then we have

$$\phi_{U_j, O_j} \circ \phi_{U_k, O_k}^{-1}(a_1, \ldots, a_n) = \left(\frac{a_1}{a_{j+1}}, \ldots, \frac{a_j}{a_{j+1}}, \frac{a_{j+2}}{a_{j+1}}, \ldots, \frac{a_k}{a_{j+1}}, \frac{1}{a_{j+1}}, \frac{a_{k+1}}{a_{j+1}}, \ldots, \frac{a_n}{a_{j+1}}\right),$$

which agrees with the usual overlap maps for the affine covering of projective space. ■

3.2. The affine structure of projective space with a point removed. In order to study below the line bundles $O_{\mathbb{P}(V)}(d)$ for $d \in \mathbb{Z}_{>0}$, we need to further explore affine structures coming from projective spaces. We let $U$ be an $F$-vector space and let $W \subset U$ be a subspace. We then have a natural identification of $\mathbb{P}(W)$ with a subset of $\mathbb{P}(U)$ by considering lines in $W$ as being lines in $U$. Note that we also have the canonical projection $\pi_W \in \text{Hom}_F(U; U/W)$ and so an induced map

$$\mathbb{P}(\pi_W) : \mathbb{P}(U) \setminus \mathbb{P}(W) \to \mathbb{P}(U/W),$$

$$L \mapsto (L + W)/W \subset U/W.$$

Note that we do require that this map not be evaluated on points in $\mathbb{P}(W)$ since these will not project to a line in $U/W$. The same line of thinking allows one to conclude that $\mathbb{P}(\pi_W)$ is surjective. The following structure of this projection is of value.
3.5 Lemma: If $F$ is a field, if $U$ is an $F$-vector space, if $W \subseteq U$ is a subspace, and if $L \in \mathcal{P}(U/W)$ then $\mathcal{P}(\pi_W^{-1}(L))$ is an affine space modelled on $\text{Hom}_F(\pi_W^{-1}(L)/W; W)$.

Proof: If $L \subseteq U/W$ is a line, then there exists $u \in U \setminus W$ such that
$$L = \{au + W \mid a \in F\} = \{au + w + W \mid a \in F\} = (M + W)/W,$$
where $M = [u]$ and so $M \cap W = \{0\}$. Therefore, we can denote
$$A_L = \{M \in \mathcal{P}(U) \setminus \mathcal{P}(W) \mid (M + W)/W = L\}.$$
We claim that
$$A_L = \{M \in \mathcal{P}(U) \setminus \mathcal{P}(W) \mid M + W = \pi_W^{-1}(L)\};$$
that is, $A_L$ is the set of complements to $W$ in $\pi_W^{-1}(L)$. To see this, first note that any such complement will necessarily have dimension 1 by the Rank–Nullity Theorem. Next let $M$ be such a complement. Then
$$L = \pi_W(\pi_W^{-1}(L)) = \pi_W(M + W),$$
which is exactly the condition $M \in A_L$. Next suppose that $(M + W)/W = L$. This means that
$$\pi_W(M + W) = L.$$
By the Rank–Nullity Theorem, it follows that $M$ is a complement to $W$ in $\pi_W^{-1}(L)$. The result now follows from Lemma 3.1.

For us, the most important application of the preceding lemma is the following corollary.

3.6 Corollary: Let $F$ be a field, let $V$ be an $F$-vector space, and consider the map
$$\mathcal{P}(\text{pr}_2): \mathcal{P}(F \oplus V) \setminus \mathcal{P}(F \oplus 0) \to \mathcal{P}(V).$$
For $L \in \mathcal{P}(V)$, $\mathcal{P}(\text{pr}_2)^{-1}(L)$ has a canonical identification with $L^*$.

Proof: We apply the lemma in a particular setting. We take $U = F \oplus V$ and $W = F \oplus 0$. We have a natural isomorphism $\iota_V: V \to U/F$ defined by $\iota_V(v) = 0 \oplus v + F$. If we let $\text{pr}_2: U \to V$ be projection onto the second factor, then we have the diagram
$$0 \to W \to U \to U/W \to 0$$
with
$$0 \to F \to F \oplus V \to V \to 0$$
which is commutative with exact rows. Note that $\text{pr}_2^{-1}(L) = F \oplus L \subseteq F \oplus V$. Therefore, $\text{pr}_2^{-1}(L)/F \simeq L$. By the lemma and by the commutative diagram (3.2), $\mathcal{P}(\text{pr}_2)^{-1}(L)$ is an affine space modelled on $\text{Hom}_F(\text{pr}_2^{-1}(L)/F; F) \simeq \text{Hom}_F(L; F) = L^*$.

Since $0 \oplus L \in \mathcal{P}(\text{pr}_2)^{-1}(L)$ for every $L \in \mathcal{P}(V)$, the affine space $\mathcal{P}(\text{pr}_2)^{-1}(L)$ has a natural distinguished origin, and so this establishes a natural identification of $\mathcal{P}(\text{pr}_2)^{-1}(L)$ with $L^*$, as desired. Explicitly, this identification is given by assigning to $[a \oplus v] \in \mathcal{P}(F \oplus V) \setminus \mathcal{P}(F \oplus 0)$ the element $a \in [v]^*$ determined by $\alpha(v) = a$. ■
4. Functions and maps to and from projective spaces

In order to intelligently talk about objects defined on projective space, e.g., spaces of sections of line bundles over projective space, we need to have at hand a notion of regularity for such mappings. We shall discuss this only in the most elementary setting, as this is all we need here. For example, we talk only about maps whose domain and codomain are either a vector space or a projective space. More generally, one would wish to talk about domains and codomains that are affine or projective varieties, or, more generally, quasi-projective varieties. But we simply do not need this level of generality. We refer to any basic algebraic geometry text, e.g., [Shafarevich 1994], for a more general discussion.

Caveat: We do not follow some of the usual conventions in algebraic geometry because we do not work exclusively with algebraically closed fields. Thus some of our definitions are not standard. We do not care to be fussy about how we handle this. At points where it is appropriate, we point out where algebraic closedness leads to the usual definitions.

4.1. Functions on vector spaces. First, let us talk about functions on a vector space $V$ taking values in $F$. We wish to use polynomial functions as our starting point. A polynomial function of homogeneous degree $d$ on $V$ is a function of the form $v \mapsto A(v, \ldots, v)$, for $A \in S^d(V^*)$. A general (i.e., not necessarily homogeneous) polynomial function is then a sum of its homogeneous components, and so identifiable with an element of $S(V^*)$. Any element of $S(V^*)$ can be written as $A_0 + A_1 + \cdots + A_d$ where $d \in \mathbb{Z}_{\geq 0}$ and $A_j \in S^j(V^*)$, $j \in \{0, 1, \ldots, d\}$. Justified by the proposition, we shall sometimes abuse notation slightly and write “$f \in S(V^*)$” if $f$ is a polynomial function. When we wish to be explicit about the relationship between the function and the tensor, we shall write $f_A$, where $A = A_0 + A_1 + \cdots + A_d$. If we wish to consider general polynomial functions taking values in an $F$-vector space $U$, these will then be identifiable with elements of $S(V^*) \otimes U$.

We will need to go beyond polynomial functions, and this we do as follows.

4.1 Definition: Let $F$ be a field, let $U$ and $V$ be finite-dimensional $F$-vector spaces, and let $S \subset V$. A map $f: V \to U$ is regular on $S$ if there exists $N \in S(V^*) \otimes U$ and $D \in S(V^*)$ such that

(i) $\{v \in S \mid f_D(v) = 0\} = \emptyset$ and

(ii) $f(v) = \frac{f_N(v)}{f_D(v)}$ for all $v \in V$.

If $f$ is regular on $V$, we shall often say $f$ is simply regular.

In some cases regular functions take a simpler form.

4.2 Proposition: If $F$ is an algebraically closed field and if $U$ and $V$ are finite-dimensional $F$-vector spaces, then $f: V \to U$ is regular on $V$ if and only if there exists $A \in S(V^*) \otimes U$ such that $f = f_A$.

Proof: The “if” assertion is clear. For the “only if” assertion, it is sufficient to show that, in the definition of a regular function, $D$ can be taken to have degree zero. To see this, we suppose that $D$ has (not necessarily homogeneous) degree $d \in \mathbb{Z}_{\geq 0}$ and show that $f_D(v) = 0$
for some nonzero $v$. Write $D = D_0 + D_1 + \cdots + D_d$ where $D_k \in S^k(V^*)$ for $k \in \{0, 1, \ldots, d\}$. Let $(e_1, \ldots, e_n)$ be a basis for $V$, fix $a_2, \ldots, a_n \in F \setminus \{0\}$, and consider the function

$$F \ni a \mapsto f_D(ae_1 + a_2 e_2 + \cdots + a_n e_n) \in F.$$  

(4.1)

Note that

$$f_D(ae_1 + a_2 e_2 + \cdots + a_n e_n) = \sum_{k=0}^{d} \sum_{j=0}^{k} \binom{k}{j} D_k(\overbrace{ae_1, \ldots, ae_1}^{j \text{ times}}, \overbrace{a_2 e_2 + \cdots + a_n e_n}^{k-j \text{ times}}),$$

and so the function (4.1) is a polynomial function of (not necessarily homogeneous) degree $d$. If

$$\sum_{k=0}^{d} D_k(a_2 e_2 + \cdots + a_n e_n, \ldots, a_2 e_2 + \cdots + a_n e_n) = 0$$

then $f_D$ is zero at the nonzero point $a_2 e_2 + \cdots + a_n e_n$ and our claim follows. Otherwise, the function (4.1) is a scalar polynomial function of positive degree with nonzero constant term. Since $F$ is algebraically closed, there is a nonzero root $a_1$ of this function, and so $f_D$ is zero at $a_1 e_1 + a_2 e_2 + \cdots + a_n e_n$, giving our assertion.

The following example shows that the assumption of algebraic closedness is essential in the lemma.

4.3 Example: The function $x \mapsto \frac{1}{1+x}$ from $\mathbb{R}$ to $\mathbb{R}$ is a regular function that is not polynomial.

4.2. Functions on projective space. Note that if $f \in S^d(V^*)$, then $f(\lambda v) = \lambda^d f(v)$, and so $f$ will not generally give rise to a well-defined function on $P(V)$ since its value on lines will not be constant. However, this does suggest the following definition.

4.4 Definition: Let $F$ be a field and let $V$ and $U$ be $F$-vector spaces. A map $f: P(V) \to U$ is regular if there exists $d \in \mathbb{Z}_{\geq 0}$ and $N \in S^d(V^*) \otimes U$ and $D \in S^d(V^*)$ such that

(i) $\{v \in V \mid f_D(v) = 0\} = \{0\}$ and

(ii) $f([v]) = \frac{f_N(v)}{f_D(v)}$ for all $[v] \in P(V)$.

Let us investigate this class of regular functions.

4.5 Proposition: If $F$ is an algebraically closed field, if $V$ is a finite-dimensional $F$-vector spaces, and if $f: P(V) \to F$ is regular, then $f$ is a constant function on $P(V)$.

Proof: Suppose that $f(v) = \frac{f_N(v)}{f_D(v)}$ for $N, D \in S^d(V^*)$ where $f_D$ does not vanish on $V \setminus \{0\}$. Since $F$ is algebraically closed, the same argument as was used in the proof of Proposition 4.2 shows that $f_D$ is constant, i.e., of degree 0. Thus $f_D$ is a nonzero constant function. It follows that $f_N$ is also a constant function since we have $N \in S^0(V^*)$, and so $f$ is constant.

The following example shows that algebraic closedness of $F$ is essential.
4.6 Example: We let $F = \mathbb{R}$ and $V = \mathbb{R}^{n+1}$, denoting a point in $V$ by $(a_0, a_1, \ldots, a_n)$. Of course, $\mathbb{P}(V) = \mathbb{RP}^n$. We define a regular function $f$ on $\mathbb{RP}^n$ by

$$f([a_0 : \cdots : a_n]) = \frac{f_N(a_0, a_1, \ldots, a_n)}{a_0^2 + a_1^2 + \cdots + a_n^2},$$

where $f_N$ is a nonzero polynomial function of homogeneous degree 2, e.g.,

$$f_N(a_0, a_1, \ldots, a_n) = a_0a_1 + a_1a_2 + \cdots + a_{n-1}a_n.$$

This gives a nonconstant regular function, as desired.

4.3. Mappings between projective spaces. Next let us consider a natural class of maps between projective spaces.

4.7 Definition: Let $F$ be a field and let $U$ and $V$ be finite-dimensional $F$-vector spaces. A morphism of the projective spaces $\mathbb{P}(V)$ and $\mathbb{P}(U)$ is a map $\Phi: \mathbb{P}(V) \to \mathbb{P}(U)$ for which there exist $d_N, d_D \in \mathbb{Z}_{\geq 0}$, $N \in S^{d_N}(V^*)$, and $D \in S^{d_D}(V^*) \otimes U$ such that

(i) $\{v \in V \mid f_N(v) = 0\} = \{0\}$,

(ii) $\{v \in V \mid f_D(v) = 0\} = \{0\}$,

(iii) $\Phi([v]) = \left[\frac{f_N(v)}{f_D(v)}\right]$ for all $[v] \in \mathbb{P}(V)$.

Let us give a couple of examples of morphisms of projective space.

4.8 Examples: 1. If $A \in \text{Hom}_F(V; U)$ is a homomorphism of vector spaces, then the induced map $\mathbb{P}(A): \mathbb{P}(V) \to \mathbb{P}(U)$ given by $\mathbb{P}(A)([v]) = [A(v)]$ is well-defined if and only $\ker(A) = \{0\}$. If $\ker(A) \neq \{0\}$, then $\mathbb{P}(A)([v])$ can only be defined for $[v] \not\in \ker(A)$, i.e., we have a map

$$\mathbb{P}(A): \mathbb{P}(V) \setminus \mathbb{P}(\ker(A)) \to \mathbb{P}(U),$$

which puts us in a setting similar to that of Section 3.2.

2. Let $V$ be an $F$-vector space. Let us consider the map

$$V \ni v \mapsto v^{\otimes d} \in S^d(V).$$

This is a polynomial function of homogeneous degree $d$, i.e., an element of

$$S^d(V^*) \otimes S^d(V) \simeq \text{End}_F(S^d(V));$$

indeed, one sees that the mapping corresponds to the identity endomorphism. This mapping vanishes only at $v = 0$, and, therefore, we have an induced mapping

$$\vartheta_d: \mathbb{P}(V) \to \mathbb{P}(S^d(V))$$

$$[v] \mapsto [v^{\otimes d}],$$

which is called the Veronese embedding.
3. Let $U$ and $V$ be $F$-vector spaces and consider the map $\hat{\sigma}_{U,V} : U \times V \to U \otimes V$ defined by $\hat{\sigma}_{U,V}(u,v) = u \otimes v$. Note that

$$\hat{\sigma}(\lambda u, \mu v) = (\lambda \mu)\hat{\sigma}(u,v),$$

and from this we deduce that the map

$$\sigma_{U,V} : \mathbb{P}(U) \times \mathbb{P}(V) \to \mathbb{P}(U \otimes V)$$

$$([u],[v]) \mapsto [u \otimes v]$$

is well-defined. This is called the **Segre embedding**.

5. The tautological line bundle

Now we get to defining our various line bundles. In the case of $d = -1$, denote

$$O_{\mathbb{P}(V)}(-1) = \{([v],L) \in \mathbb{P}(V) \times \mathbb{P}(V) \mid v \in L\}$$

and

$$\pi_{\mathbb{P}(V)}^{-1} : O_{\mathbb{P}(V)}(-1) \to \mathbb{P}(V)$$

$$([v],L) \mapsto [v].$$

The way to think of $\pi_{\mathbb{P}(V)}^{-1} : O_{\mathbb{P}(V)}(-1) \to \mathbb{P}(V)$ is as a line bundle over $\mathbb{P}(V)$ for which the fibre over $[v]$ is the line generated by $v$. This is the **tautological line bundle** over $\mathbb{P}(V)$. In the case that $F = \mathbb{R}$, the result is the so-called **Möbius vector bundle** over $\mathbb{RP}^1 \simeq S^1$. This is a vector bundle with a one-dimensional fibre, and a “twist” as depicted in Figure 1.

![Figure 1](image-url)

**Figure 1.** A depiction of the Möbius vector bundle (imagine the fibres extending to infinity in both directions)

For $[v] \in \mathbb{P}(V)$, let us denote $Q_{V,[v]} = V/[v]$ and take

$$Q_{V} = \bigcup_{[v] \in \mathbb{P}(V)} Q_{V,[v]}.$$
We can think of $Q_V$ as being a vector bundle formed by the quotient of the trivial vector bundle $\mathbb{P}(V) \times V$ by the tautological line bundle. Note that we have an exact sequence

$$0 \longrightarrow O_{\mathbb{P}(V)}(-1) \longrightarrow \mathbb{P}(V) \times V \longrightarrow Q_V \longrightarrow 0$$

where all arrows are canonical, and where this is done for fibres over a fixed $[v] \in \mathbb{P}(V)$, i.e., the sequence is one of vector bundles. This is called the **tautological sequence**.

### 6. The degree $-d$ line bundles, $d \in \mathbb{Z}_{>0}$

For $d \in \mathbb{Z}_{>0}$ we define

$$O_{\mathbb{P}(V)}(-d) = \{([v], ([A], L)) \in \mathbb{P}(V) \times O_{\mathbb{P}(S^d(V))}(-1) \mid \vartheta_d([v]) = \pi^{(-1)}_{\mathbb{P}(S^d(V))}([A], L)\}$$

and

$$\pi^{(-d)}_{\mathbb{P}(V)} : O_{\mathbb{P}(V)}(-d) \to \mathbb{P}(V)$$

$$([v], ([A], L)) \mapsto [v].$$

The best way to think of $\pi^{(-d)}_{\mathbb{P}(V)} : O_{\mathbb{P}(V)}(-d) \to \mathbb{P}(V)$ is as the pull-back of the tautological line bundle over $\mathbb{P}(S^d(V))$ to $\mathbb{P}(V)$ by the Veronese embedding. The condition $\vartheta_d([v]) = \pi^{(-1)}_{\mathbb{P}(S^d(V))}([A], L)$ is phrased to emphasise this pull-back bundle interpretation of $O_{\mathbb{P}(V)}(-d)$, but is more succinctly expressed by the requirement that $[v^{\otimes d}] \in [A]$. In any case, $O_{\mathbb{P}(V)}(-d)$ is to be regarded as a vector bundle over $\mathbb{P}(V)$ whose fibre over $[v]$ is $[v^{\otimes d}]$.

Let us give a useful interpretation of $O_{\mathbb{P}(V)}(-d)$.

**6.1 Proposition:** For every $d \in \mathbb{Z}_{>0}$ we have a canonical isomorphism

$$O_{\mathbb{P}(V)}(-d) \simeq O_{\mathbb{P}(V)}(-1)^{\otimes d}$$

and a canonical inclusion

$$O_{\mathbb{P}(V)}(-d) \to \mathbb{P}(V) \times S^d(V),$$

both being vector bundle mappings over $id_{\mathbb{P}(V)}$.

**Proof:** For the isomorphism, consider the map

$$O_{\mathbb{P}(V)}(-1)^{\otimes d} \ni ([v], u^{\otimes d}) \mapsto ([v], ([v^{\otimes d}], u^{\otimes d})) \in O_{\mathbb{P}(V)}(-d) \subset O_{\mathbb{P}(S^d(V))}(-1).$$

Since $u \in [v]$, $u^{\otimes d} \in [v^{\otimes d}]$ from which one readily verifies that this map is indeed an isomorphism of vector bundles over $\mathbb{P}(V)$.

If we take the $d$-fold symmetric tensor product of the left half of the tautological sequence, we get the sequence

$$0 \longrightarrow O_{\mathbb{P}(V)}(-1)^{\otimes d} \longrightarrow \mathbb{P}(V) \times S^d(V)$$

which gives the inclusion when combined with the isomorphism from the first part of the proof. □
7. The hyperplane line bundle

We refer here to the constructions of Section 3.2. With these constructions in mind, let us define

\[ \mathcal{O}_{\mathbb{P}(V)}(1) = \mathbb{P}(F \oplus V) \setminus \mathbb{P}(F \oplus 0) \]

and take \( \pi_{\mathbb{P}(V)}^{(1)} = \mathbb{P}(pr_2) \), so that we have the vector bundle \( \pi_{\mathbb{P}(V)}^{(1)}: \mathcal{O}_{\mathbb{P}(V)}(1) \to \mathbb{P}(V) \) whose fibre over \( L \in \mathbb{P}(V) \) is canonically isomorphic to \( L^* \). Thus the fibres of \( \mathcal{O}_{\mathbb{P}(V)}(1) \) are linear functions on the fibres of the tautological line bundle. We call \( \mathcal{O}_{\mathbb{P}(V)}(1) \) the hyperplane line bundle of \( \mathbb{P}(V) \).

We have the following important attribute of the hyperplane line bundle.

7.1 Proposition: We have a surjective mapping

\[ \mathbb{P}(V) \times V^* \to \mathcal{O}_{\mathbb{P}(V)}(1) \]

as a vector bundle map over \( \text{id}_{\mathbb{P}(V)} \).

Proof: Let \( ([v], A) \in \mathbb{P}(V) \times S^d(V^*) \) and consider \( [A(v) \oplus v] \in \mathbb{P}(F \oplus V) \setminus \mathbb{P}(F \oplus 0) \). Since

\[ [A(av) \oplus (av)] = [A(v) \oplus v], \quad a \in F, \]

it follows that \( [A(v) \oplus v] \) is a well-defined function of \([v]\). Recalling from Lemma 3.2 that vector addition and scalar multiplication on \( \mathbb{P}(pr_2)^{-1}([v]) \) (with the origin \([0 \oplus v]\)) are given by

\[ [a \oplus v] + [b \oplus v] = [(a + b) \oplus v], \quad \alpha[a \oplus v] = [(\alpha a) \oplus v], \quad (7.1) \]

respectively, we see that the mapping \(( [v], A) \mapsto [A(v) \oplus v] \) is a vector bundle mapping. To see that the mapping is surjective, we need only observe that, if \([a \oplus v] \in \mathbb{P}(pr_2)^{-1}([v]) \), then, if we take \( A \in S^d(V^*) \) to satisfy \( A(v) = a \), we have \([A(v) \oplus v] = [a \oplus v] \), giving surjectivity.

If, for \([v] \in \mathbb{P}(V)\) we denote by \( K_{V,[v]} \) the kernel of the projection from \( \{[v]\} \times V^* \) onto \( \mathcal{O}_{\mathbb{P}(V)}(1)_{[v]} \), we have the following exact sequence,

\[ 0 \to K_V \to \mathbb{P}(V) \times V^* \to \mathcal{O}_{\mathbb{P}(V)}(1) \to 0 \]

which we call the hyperplane sequence. Note that \( K_{V,[v]} = \text{ann}([v]) \), where “ann” denotes the annihilator.

The following result gives an essential property of the hyperplane line bundle.

7.2 Proposition: We have an isomorphism

\[ \mathcal{O}_{\mathbb{P}(V)}(-1)^* \simeq \mathcal{O}_{\mathbb{P}(V)}(1) \]

as a vector bundle map over \( \text{id}_{\mathbb{P}(V)} \).

Proof: If we take the dual of the tautological sequence, we get the diagram

\[ \begin{array}{cccccc}
0 & \to & Q'_V & \to & \mathbb{P}(V) \times V^* & \to & \mathcal{O}_{\mathbb{P}(V)}(-1)^* & \to & 0 \\
& & \downarrow & & \downarrow & & \downarrow & & \downarrow \\
0 & \to & K_V & \to & \mathbb{P}(V) \times V^* & \to & \mathcal{O}_{\mathbb{P}(V)}(1) & \to & 0
\end{array} \]
thinking of each component as a vector bundle over $\mathbb{P}(V)$ and each arrow as a vector bundle mapping over the identity. The leftmost vertical arrow is the defined by the canonical isomorphism

$$Q^*_V[v] = (V/[v])^* \simeq \text{ann } [v] = K_{V,[v]}.$$ 

The dashed vertical arrow is then defined by taking a preimage of $\alpha[v] \in \mathcal{O}_{\mathbb{P}(V)}(-1)^*$ in $\mathbb{P}(V) \times V^*$ then projecting this to $\mathcal{O}_{\mathbb{P}(V)}(1)$. A routine argument shows that this mapping is a well-defined isomorphism. ■

8. The degree $d$ line bundles, $d \in \mathbb{Z}_{>0}$

For $d \in \mathbb{Z}_{>0}$ we define

$$\mathcal{O}_{\mathbb{P}(V)}(d) = \{(v,M) \in \mathbb{P}(V) \times \mathcal{O}_{\mathbb{P}(S^d(V))}(1) \mid \vartheta_d([v]) = \pi_{1}(\mathcal{O}_{\mathbb{P}(S^d(V))}(M))\}$$

and

$$\pi^{(d)}_{\mathbb{P}(V)} : \mathcal{O}_{\mathbb{P}(V)}(d) \to \mathbb{P}(V)$$

$$([v], M) \mapsto [v].$$

As with the negative degree line bundles, we think of this as the pull-back of $\mathcal{O}_{\mathbb{P}(S^d(V))}(1)$ to $\mathbb{P}(V)$ by the Veronese embedding. Note that the fibre over $L \in \mathbb{P}(V)$ is canonically isomorphic to $(S^d(L))^* \simeq S^d(L^*)$. Thus the fibres of $\mathcal{O}_{\mathbb{P}(V)}(d)$ are polynomial functions of degree $d$ on the fibres of the tautological line bundle. With this in mind, we have the following adaptation of Proposition 6.1.

8.1 Proposition: For $d \in \mathbb{Z}_{>0}$ we have a canonical isomorphism

$$\mathcal{O}_{\mathbb{P}(V)}(d) \simeq \mathcal{O}_{\mathbb{P}(V)}(1)^{\otimes d}$$

and a canonical surjective mapping

$$\mathbb{P}(V) \times S^d(V^*) \to \mathcal{O}_{\mathbb{P}(V)}(d),$$

both being vector bundle mappings over $\text{id}_{\mathbb{P}(V)}$.

Proof: Keeping in mind the vector bundle structure on $\mathcal{O}_{\mathbb{P}(V)}(1)$ given explicitly by (7.1), an element of $\mathcal{O}_{\mathbb{P}(V)}(1)^{\otimes d}$ can be written as $[a^d \oplus v]$ for $[v] \in \mathbb{P}(V)$ and $a \in F$. Thus consider the mapping

$$\mathcal{O}_{\mathbb{P}(V)}(1)^{\otimes d} \ni [a^d \oplus v] \mapsto ([v],[a^d \oplus v^{\otimes d}]) \in \mathcal{O}_{\mathbb{P}(S^d(V))}(1).$$

Another application of (7.1) to $\mathcal{O}_{\mathbb{P}(S^d(V))}(1)$ shows that the preceding map is a vector bundle map, and it is also clearly an isomorphism.

Now we can take the dual of the inclusion

$$\mathcal{O}_{\mathbb{P}(V)}(-d) \to \mathbb{P}(V) \times S^d(V)$$

from Proposition 6.1 to give the surjective mapping in the statement of the proposition. ■

9. The tangent bundle, the cotangent bundle, and the Euler sequence

To motivate our discussion of tangent vectors and the tangent bundle, we consider the case when $F = \mathbb{R}$ and so $V$ is a $\mathbb{R}$-vector space. In this case, we establish a lemma.
9.1 Lemma: If \( V \) is a \( \mathbb{R} \)-vector space, there exists a canonical isomorphism of \( T_v \mathbb{P}(V) \) with \( \text{Hom}_\mathbb{R}([v]; V/[v]) \) for every \([v] \in \mathbb{P}(V)\).

Proof: For \( L \in \mathbb{P}(V) \), the tangent space \( T_L \mathbb{P}(V) \) consists of tangent vectors to curves at \( L \). We define a map \( T_L \in \text{Hom}_\mathbb{R}(T_L \mathbb{P}(V); \text{Hom}_\mathbb{R}(L; V/L)) \) as follows. Let \( v \in T_L \mathbb{P}(V) \), let \( \gamma: I \to \mathbb{P}(V) \) be a smooth curve for which \( \gamma'(0) = v \). Let \( u \in L \) and let \( \sigma: I \to V \) be a smooth curve for which \( \sigma(0) = u \) and \( \gamma(t) = [\sigma(t)] \), and define \( T_L(v) \in \text{Hom}_\mathbb{R}(L; V/L) \) by

\[
T_L(v) \cdot u = \sigma'(0) + L.
\]

To see that \( T_L \) is well-defined, let \( \tau \) be another curve for which \( \tau(t) = u \) and \( \gamma(t) = [\tau(t)] \). Since \( \tau(0) - \sigma(0) = 0 \) we can write \( \tau(t) - \sigma(t) = t \rho(t) \) where \( \rho: I \to V \) satisfies \( \rho(t) \in \gamma(t) \). Therefore,

\[
\tau'(0) = \sigma'(0) + \rho(0) + L = \sigma'(0) + L,
\]

showing that \( T_L(v) \) is indeed well-defined. To show that \( T_L \) is injective, suppose that \( T_L(v) = 0 \). Thus \( T_L(v) \cdot u = 0 \) for every \( u \in L \). Let \( \gamma \) be a smooth curve on \( \mathbb{P}(V) \) for which \( \gamma'(0) = v \), let \( u \in L \), and let \( \sigma \) be a curve on \( V \) for which \( \sigma(0) = u \) and \( \gamma(t) = [\sigma(t)] \). Then

\[
0 = T_L(v) \cdot u = \sigma'(0) + L \implies \sigma'(0) \in L.
\]

Since \( \gamma(t) \) is the projection of \( \sigma(t) \) from \( V \setminus \{0\} \) to \( \mathbb{P}(V) \), it follows that \( \gamma'(0) \) is the derivative of this projection applied to \( \sigma'(0) \). But since \( \sigma'(0) \in L \) and since \( L \) is the kernel of the derivative of the projection, this implies that \( v = \gamma'(0) = 0 \). Since

\[
\text{dim}_\mathbb{R}(T_L \mathbb{P}(V)) = \text{dim}_\mathbb{R}(\text{Hom}_\mathbb{R}(L; V/L)),
\]

it follows that \( T_L \) is an isomorphism. \( \blacksquare \)

With the lemma as motivation, in the general algebraic setting we define the tangent space of \( \mathbb{P}(V) \) at \([v] \) to be

\[
T_v \mathbb{P}(V) = [v]^* \otimes V/[v].
\]

The tangent bundle is then, as usual, \( T \mathbb{P}(V) = \bigcup_{[v] \in \mathbb{P}(V)} T_v \mathbb{P}(V) \). Recalling the quotient vector bundle \( Q_V \) used in the construction of the tautological sequence and recalling the definition of the hyperplane line bundle, we clearly have

\[
T \mathbb{P}(V) = O_{\mathbb{P}(V)}(1) \otimes Q_V.
\]

We then also have the cotangent bundle

\[
T^* \mathbb{P}(V) = O_{\mathbb{P}(V)}(-1) \otimes K_V,
\]

noting that \( O_{\mathbb{P}(V)}(-1) \simeq O_{\mathbb{P}(V)}(1)^* \) and \( Q_V^* = K_V \).

We have the following result.
9.2 Proposition: We have a short exact sequence

\[
0 \longrightarrow \mathbb{P}(V) \times F \longrightarrow \mathbb{P}(V) \times (V \otimes \mathcal{O}_{\mathbb{P}(V)}(1)) \longrightarrow \mathcal{T}(\mathbb{P}(V)) \longrightarrow 0
\]

of vector bundles over \( \text{id}_{\mathbb{P}(V)} \), known as the Euler sequence.

Proof: This follows by taking the tensor product of the tautological sequence with \( \mathcal{O}_{\mathbb{P}(V)}(1) \), noting that

\[
\mathcal{O}_{\mathbb{P}(V)}(-1) \otimes \mathcal{O}_{\mathbb{P}(V)}(1) \simeq F
\]

by the isomorphism \( v \otimes \alpha \mapsto \alpha(v) \). This is indeed an isomorphism since the fibres of \( \mathcal{O}_{\mathbb{P}(V)}(-1) \) and its dual \( \mathcal{O}_{\mathbb{P}(V)}(1) \) are one-dimensional.

\[\blacksquare\]

Sometimes the dual

\[
0 \longrightarrow \mathcal{T}^* \mathbb{P}(V) \longrightarrow \mathbb{P}(V) \times (V^* \otimes \mathcal{O}_{\mathbb{P}(V)}(-1)) \longrightarrow \mathbb{P}(V) \times F^* \longrightarrow 0
\]

of the Euler sequence is referred to as the Euler sequence. In the more usual presentation of the Euler sequence one has \( V = F^{n+1} \) so the sequence reads

\[
0 \longrightarrow \mathbb{P}(F^{n+1}) \times F \longrightarrow \mathcal{O}_{\mathbb{P}(V)}(1)^{n+1} \longrightarrow \mathcal{T}(\mathbb{P}(F^{n+1})) \longrightarrow 0
\]

It is difficult to imagine that the Euler sequence can be of much importance from the manner in which it is developed here. But it has significance, for example, in commutative algebra where it is related to the so-called Koszul sequence [Eisenbud 1995, §17.5].

In case \( \dim(V) = 2 \), the tangent and cotangent bundles are line bundles, and have a simple representation in terms the line bundles we introduced above.

9.3 Proposition: If \( F \) is a field and if \( V \) is a two-dimensional \( F \)-vector space, then we have isomorphisms

\[
\mathcal{T}(\mathbb{P}(V)) \simeq \mathcal{O}_{\mathbb{P}(V)}(2), \quad \mathcal{T}^* \mathbb{P}(V) \simeq \mathcal{O}_{\mathbb{P}(V)}(-2).
\]

Proof: By a choice of basis, we can and do assume that \( V = F^2 \). We closely examine the Euler sequence. To do this, we first closely examine the tautological sequence in this case. The sequence is

\[
0 \longrightarrow \mathcal{O}_{\mathbb{P}(F^2)}(-1) \overset{I_1}{\longrightarrow} \mathbb{P}(F^2) \times F^2 \overset{P_1}{\longrightarrow} Q_{F^2} \longrightarrow 0
\]

and, explicitly, we have

\[
I_1([(x, y)], a(x, y)) = ([x, y], (ax, ay)), \quad P_1([(x, y)], (u, v) + [(x, y)]).
\]

The Euler sequence is obtained by taking the tensor product of this sequence with \( \mathcal{O}_{\mathbb{P}(F^2)}(1) \):

\[
0 \longrightarrow \mathcal{O}_{\mathbb{P}(F^2)}(-1) \otimes \mathcal{O}_{\mathbb{P}(F^2)}(1) \overset{I_1 \otimes \text{id}}{\longrightarrow} \mathbb{P}(F^2) \times F^2 \overset{P_1 \otimes \text{id}}{\longrightarrow} \mathcal{T}(\mathbb{P}(F^2)) \longrightarrow 0
\]

with id denoting the identity map on \( \mathcal{O}_{\mathbb{P}(F^2)}(1) \). Explicitly we have

\[
I_1 \otimes \text{id}([(x, y)], (a(x, y)) \otimes \alpha) = I_1([(x, y)], (ax, ay)) \otimes \alpha = (ax \alpha) \oplus (ay \alpha).
\]
Now let \([x, y]\) \in \mathbb{P}(F^2)\) so that \(x\) and/or \(y\) is nonzero. Obviously \((x, y)\) is a basis for \(L = [(x, y)]\). Let \((\xi(x, y), \eta(x, y))\) \in \mathbb{F}^2\) be such that \(((x, y), (\xi(x, y), \eta(x, y)))\) is a basis for \(\mathbb{F}^2\). For \((u, v) \in \mathbb{F}^2\) write
\[
(u, v) = a(x, y)(u, v)(x, y) + b(x, y)(u, v)(\xi(x, y), \eta(x, y)),
\]
uniquely defining \(a(x, y)(u, v), b(x, y)(u, v) \in \mathbb{F}\). Using this we write
\[
P_1 \otimes \text{id}([(x, y)], (u, v) \otimes \alpha) = ([((x, y), (b(x, y))(u, v)\xi(x, y), \eta(x, y)) + [(x, y)] \otimes \alpha).
\]
Now consider the map
\[
\phi: \mathcal{O}_{\mathbb{P}(F^2)}(1)^2 \to \mathcal{O}_{\mathbb{P}(F^2)}(2)
\]
\[
([x, y], \alpha \oplus \beta) \mapsto ([x, y], (\xi(x, y)\alpha) \otimes (\eta(x, y)\beta)).
\]
Making the identification \(\mathcal{O}_{\mathbb{P}(F^2)}(−1) \otimes \mathcal{O}_{\mathbb{P}(F^2)}(1) \simeq \mathbb{P}(F^2) \times \mathbb{F}\) as in the proof of Proposition 9.2, we have the commutative diagram
\[
\begin{array}{cccccc}
0 & \longrightarrow & \mathbb{P}(F^2) \times \mathbb{F} & \longrightarrow & \mathcal{O}_{\mathbb{P}(F^2)}(1)^2 & \longrightarrow & T\mathbb{P}(F^2) & \longrightarrow & 0 \\
\downarrow & & \downarrow & & & & \downarrow & \\
0 & \longrightarrow & \mathbb{P}(F^2) \times \mathbb{F} & \longrightarrow & \mathcal{O}_{\mathbb{P}(F^2)}(1)^2 & \longrightarrow & \mathcal{O}_{\mathbb{P}(F^2)}(2) & \longrightarrow & 0
\end{array}
\]
with exact rows. The dashed arrow is defined by taking a preimage of \(\nu_L \in T_L \mathbb{P}(F^2)\) in \(\mathcal{O}_{\mathbb{P}(F^2)}(2)\) and projecting this to \(\mathcal{O}_{\mathbb{P}(F^2)}(2)\). One verifies easily that this map is a well-defined isomorphism.

That \(T^* \mathbb{P}(V) \simeq \mathcal{O}_{\mathbb{P}(V)}(−2)\) follows from Propositions 7.2 and 8.1.

10. Global sections of the line bundles

Let us consider the global sections of \(\mathcal{O}_{\mathbb{P}(V)}(d)\) for \(d \in \mathbb{Z}\). The sections we consider are those that satisfy the sort of regularity conditions we introduced in Section 4. This takes a slightly different form, depending on the degree of the line bundle.

10.1 Definition: Let \(\mathbb{F}\) be a field, let \(V\) be a finite-dimensional \(\mathbb{F}\)-vector space, and let \(d \in \mathbb{Z}\). A section of \(\mathcal{O}_{\mathbb{P}(V)}(d)\) is a map \(\sigma: \mathbb{P}(V) \to \mathcal{O}_{\mathbb{P}(V)}(d)\) for which \(\pi_{\mathbb{P}(V)}^*(\sigma) = \text{id}_{\mathbb{P}(V)}\). A section \(\sigma\) is **regular** if
\begin{enumerate}[(i)]
\item \(d < 0\): \(\hat{\sigma}: \mathbb{P}(V) \to S^d(V)\) is regular in the sense of Definition 4.4, where \(\hat{\sigma}\) is defined by the requirement that
\[
\sigma([v]) = ([v], ([v]^{\otimes d}, \hat{\sigma}([v])));
\]
\item \(d = 0\): \(\hat{\sigma}: \mathbb{P}(V) \to \mathbb{F}\) is regular in the sense of Definition 4.4, where \(\hat{\sigma}\) is defined by the requirement that
\[
\sigma([v]) = ([v], \hat{\sigma}([v]));
\]
\item \(d > 0\): \(\hat{\sigma}: V \to \mathbb{F}\) is regular in the sense of Definition 4.1, where \(\hat{\sigma}\) is defined by the requirement that
\[
\sigma([v]) = ([v], [\hat{\sigma}(v) \oplus v^{\otimes d}]).
\]
\end{enumerate}
The set of regular sections of \(\mathcal{O}_{\mathbb{P}(V)}(d)\) we denote by \(\Gamma(\mathcal{O}_{\mathbb{P}(V)}(d))\).

With these definitions, we have the following result that gives a complete characterisation of the space of global sections in the algebraically closed case.
10.2 Proposition: If \( F \) is a field and if \( V \) is an \((n+1)\)-dimensional \( F \)-vector space, for \( d \geq 0 \) we have
\[
\dim_F(\Gamma(O_{\mathbb{P}(V)}(d))) \geq \binom{n+d}{n} = \frac{(n+d)!}{n!d!}.
\]
Moreover, if \( F \) is algebraically closed, then we have
\[
\dim_F(\Gamma(O_{\mathbb{P}(V)}(d))) = \begin{cases} 
0, & d < 0, \\
\binom{n+d}{n}, & d \geq 0.
\end{cases}
\]

Proof: Let \( d \geq 0 \). If \( A \in S^d(V^*) \) then there is a corresponding regular section \( \sigma_A \) of \( O_{\mathbb{P}(V)}(d) \) defined by
\[
\sigma_A([v]) = ([v], [A(v^{\otimes d}), v^{\otimes d}]).
\]
Thus we have a mapping from \( S^d(V^*) \) to \( \Gamma(O_{\mathbb{P}(V)}(d)) \). We claim that this map is injective. Indeed, if \( \sigma_A([v]) = 0 \) for every \([v] \in \mathbb{P}(V)\). This means that \( A(v^{\otimes d}) = 0 \) for every \( v \in V \) and so \( A = 0 \). The first statement then follows from the fact that
\[
\dim_F(S^d(V^*)) = \binom{n+d}{n}
\]
[Roman 2008, page 379].

For the remainder of the proof we suppose that \( F \) is algebraically closed.

Let us next consider the negative degree case. Let \( \sigma \) be a global section of \( O_{\mathbb{P}(V)}(d) \) with \( \hat{\sigma} : \mathbb{P}(V) \to S^d(V) \) the induced map. Let \( \alpha \in S^d(V^*) \) so that \( \alpha \circ \hat{\sigma} \) is an \( F \)-valued regular function on \( \mathbb{P}(V) \), and so is constant by Proposition 4.5. We claim that this implies that \( \hat{\sigma} \) is constant. Suppose otherwise, and that \( \hat{\sigma}([v_1]) \neq \hat{\sigma}([v_2]) \) for distinct \([v_1],[v_2] \in \mathbb{P}(V)\). This implies that we can choose \( \sigma \in S^d(V^*) \) such that \( \alpha \circ \hat{\sigma}([v_1]) \neq \alpha \circ \hat{\sigma}([v_2]) \). To see this, suppose first that only one of \( \hat{\sigma}([v_1]) \) and \( \hat{\sigma}([v_2]) \) are nonzero, say \( \hat{\sigma}([v_1]) \). Then we need only choose \( \alpha \) so that \( \hat{\sigma}([v_1]) \neq 0 \). If both of \( \hat{\sigma}([v_1]) \) and \( \hat{\sigma}([v_2]) \) are nonzero, then they are either collinear (in which case our conclusion follows) or linearly independent (so one can certainly choose \( \alpha \) so that \( \alpha \circ \hat{\sigma}([v_1]) \neq \alpha \circ \hat{\sigma}([v_2]) \)). Thus we can indeed conclude that \( \hat{\sigma} \) is constant. Note that, for \([v] \in \mathbb{P}(V)\) we have \( \hat{\sigma}([v]) = a_v v^{\otimes d} \) for some \( a_v \in F \). That is to say, \( \hat{\sigma}([v]) \) is a point on the line \([v^{\otimes d}] \) for every \([v] \in \mathbb{P}(V)\). The only point in \( S^d(V) \) on every such line is zero, and so \( \hat{\sigma} \) is the zero function.

For \( d = 0 \) the result follows from Proposition 4.5.

Now consider \( d > 0 \) and let \( \sigma \) be a regular section of \( O_{\mathbb{P}(V)}(d) \) with \( \hat{\sigma} : V \to F \) the corresponding function. In order that this provide a well-defined section of \( O_{\mathbb{P}(V)}(d) \), we must have
\[
[\hat{\sigma}(\lambda v) \oplus (\lambda v)^{\otimes d}] = [\hat{\sigma}(v) \oplus v^{\otimes d}],
\]
which means that
\[
\hat{\sigma}(\lambda v) \oplus (\lambda v)^{\otimes d} = \alpha([\hat{\sigma}(v) \oplus v^{\otimes d}])
\]
for some \( \alpha \in F \). Since \( v \neq 0 \), \( v^{\otimes d} \neq 0 \) and so we must have \( \alpha = \lambda^d \), and so \( \hat{\sigma}(\lambda v) = \lambda^d \hat{\sigma}(v) \). The requirement that \( \hat{\sigma} \) be regular then ensures that \( \hat{\sigma} = f_A \) for \( A \in S^d(V^*) \), according to Proposition 4.2, since \( F \) is algebraically closed.

Let us observe that the conclusions of the proposition do not necessarily hold when the field is not algebraically closed.
10.3 Example: We consider the simple example of line bundles over \( \mathbb{R}P^1 \). First let us show that there are nonzero regular sections of the tautological line bundle in this case. To define a section \( \sigma \) of \( O_{\mathbb{R}P^1}(-1) \), we prescribe \( \hat{\sigma}: \mathbb{R}P^1 \rightarrow \mathbb{R}^2 \), as in Definition 10.1(i). There are many possibilities here, and one way to prescribe a host of these is to take \( \hat{\sigma} \) to be of the form

\[
\hat{\sigma}([a_0 : a_1]) = \left( \frac{p(a_0, a_1)}{a_0^{2k} + a_1^{2k}}, \frac{ap(a_0, a_1)}{a_0^{2k} + a_1^{2k}} \right)
\]

for \( k \in \mathbb{Z}_{>0} \) and where \( p \) is a polynomial function of homogeneous degree \( 2k-1 \). In Figure 2 we show the images of \( \hat{\sigma} \) in a few cases, just for fun. Note that if \( \sigma \) is a section of \( O_{\mathbb{R}P^1}(-1) \), then \( \sigma^\otimes d \) is a section of \( O_{\mathbb{R}P^1}(-d) \). In this way, we immediately deduce that \( O_{\mathbb{R}P^1}(-d) \) has nonzero regular sections for every \( d \in \mathbb{Z}_{>0} \).

Of course, there are nonzero regular sections of \( O_{\mathbb{R}P^1}(0) \), as such sections are in correspondence with regular functions, cf. Example 4.3.

As for sections of \( O_{\mathbb{R}P^1}(d) \) for \( d > 0 \), it still follows from the proof of Proposition 10.2 that, if \( A \in S^d(V^*) \), we have a corresponding regular section of \( O_{\mathbb{R}P^1}(d) \). However, there are many other global regular sections since, given a given a regular function \( f \), there is the corresponding regular section \( fA \).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{image.png}
\caption{The image of \( \hat{\sigma} \) for \( k = 1 \) and \( p(a_0, a_1) = a_0 \) (top left), \( k = 2 \) and \( p(a_0, a_1) = a_0^2a_1 \) (top right), and \( k = 3 \) and \( p(a_0, a_1) = a_0^3a_1^2 \) (bottom)}
\end{figure}
10.4 Remark: Note that the preceding discussion regarding sections of line bundles reveals essential differences between the real and complex case that arise, at least in this algebraic setting, from the fact that $\mathbb{C}$ is algebraically closed, whereas $\mathbb{R}$ is not. These differences are also reflected in the geometric setting where, instead of regular sections, one wishes to consider holomorphic or real analytic sections. The restrictions for sections that we have seen in Proposition 10.2 in the algebraic case are also present in the holomorphic case [cf. Smith, Kahanpää, Kekäläinen, and Traves 2000, page 133]. On the flip side of this, we see that even in the algebraic case, there are many sections of vector bundles over real projective space. This is, moreover, consistent with the fact that, in the geometric setting, real analytic vector bundles admit many real analytic sections, cf. Cartan’s Theorem A in the real analytic case.

11. Coordinate representations

In this section, after working hard to this point to avoid the use of bases, we connect the developments above to the commonly seen transition function treatment of line bundles over projective space.

11.1. Coordinates for projective space. We fix a basis $(e_0, e_1, \ldots, e_n)$ for $V$, giving an isomorphism

$$(x_0, x_1, \ldots, x_n) \mapsto x_0 e_0 + x_1 e_1 + \cdots + x_n e_n$$

of $\mathbb{F}^{n+1}$ with $V$. We shall engage in a convenient abuse of notation and write

$$x = (x_0, x_1, \ldots, x_n),$$

i.e., confounding a vector with its components. The line

$$[x_0 e_0 + x_1 e_1 + \cdots + x_n e_n]$$

is represented by $[x_0 : x_1 : \cdots : x_n]$. Again, we shall often write

$$[x] = [x_0 : x_1 : \cdots : x_n],$$

confounding a line with its component representation. For $j \in \{0, 1, \ldots, n\}$ we denote

$$\mathcal{U}_j = \{[x_0 : x_1 : \cdots : x_n] \mid x_j \neq 0\}$$

and note that $\mathbb{P}(V) = \bigcup_{j=0}^n \mathcal{U}_j$. We let $O_j = \text{span}_F(e_j), j \in \{0, 1, \ldots, n\}$. As per Lemma 3.2, the map

$$\phi_j : \mathcal{U}_j \to \mathbb{F}^n$$

$$[x_0 : x_1 : \cdots : x_n] \mapsto (x_j^{-1} x_0, x_j^{-1} x_1, \ldots, x_j^{-1} x_{j-1}, x_j^{-1} x_{j+1}, \ldots, x_j^{-1} x_n)$$

is an affine isomorphism.
11.2. Coordinate representations for the negative degree line bundles. Let us consider the structure of our line bundles over \( \mathbb{P}(V) \). We first consider the negative degree line bundles \( \mathcal{O}_{\mathbb{P}(V)}(-d) \) for \( d \in \mathbb{Z}_{>0} \). In doing this, we recall from Proposition 6.1 that \( \mathcal{O}_{\mathbb{P}(V)}(-d) \) is a subset of the trivial bundle \( \mathbb{P}(V) \times S^d(V) \). We will thus use coordinates

\[
([x_0, x_1, \ldots, x_n], A),
\]

to denote a point in \(([x], A) \in \mathcal{O}_{\mathbb{P}(V)}(-d)\), with the understanding that (1) this is a basis representation and (2) the requirement to be in \( \mathcal{O}_{\mathbb{P}(V)}(-d) \) is that

\[
[A] = ([x_0, x_1, \ldots, x_n] \otimes d).
\]

The following lemma gives a local trivialisation of \( \mathcal{O}_{\mathbb{P}(V)}(-d) \) over the affine sets \( U_j, j \in \{0, 1, \ldots, n\} \).

11.1 Lemma: With all the above notation, for \( j \in \{0, 1, \ldots, n\} \) and \( d \in \mathbb{Z}_{>0} \), the map

\[
\tau_j^{(-d)} : \mathcal{O}_{\mathbb{P}(V)}(-d)|U_j \to U_j \times \mathbb{F}
\]

\[
([x_0, x_1 : \cdots : x_n], a(x_0, x_1, \ldots, x_n) \otimes d) \mapsto ([x_0 : x_1 : \cdots : x_n], ax_j^d)
\]

is an isomorphism of vector bundles.

Proof: Let us first show that \( \tau_j^{(-d)} \) is well-defined. Suppose that \([x] \in U_j \) is written as

\[
[x] = [x_0 : x_1 : \cdots : x_n] = [y_0, y_1 : \cdots : y_n]
\]

so that

\[
x_j^{-1}(x_0, x_1, \ldots, x_n) = y_j^{-1}(y_0, y_1, \ldots, y_n).
\]

If \( v = (x_0, x_1, \ldots, x_n) \) then we have

\[
v = x_jy_j^{-1}(x_0, x_1, \ldots, x_n)
\]

and so

\[
(x_0, x_1, \ldots, x_n) \otimes d = x_j^d y_j^{-d}(y_0, y_1, \ldots, y_n) \otimes d.
\]

From this we deduce that

\[
\tau_j^{(-d)} ([x_0 : x_1 : \cdots : x_n], a(x_0, x_1, \ldots, x_n) \otimes d) = ([x_0 : y_1 : \cdots : x_n], ax_j^d)
\]

\[
= ([x_jy_j^{-1}y_0 : (x_jy_j^{-1})y_1 : \cdots : (x_jy_j^{-1})y_n, ax_j^d(y_j^dy_j^{-d}))
\]

\[
= ([y_0 : y_1 : \cdots : y_n], ay_j^d(x_j^dy_j^{-d}))
\]

\[
= \tau_j^{(-d)} ([y_0 : y_1 : \cdots : y_n, ax_j^d(y_j^dy_j^{-d})],)
\]

and from this we see that \( \tau_j^{(-d)} \) is well-defined. Clearly \( \tau_j^{(-d)} \) is a vector bundle map. Moreover, since \( x_j \) is nonzero on \( U_j \), \( \tau_j^{(-d)} \) is surjective, and so an isomorphism.

Now suppose that \([x] \in U_j \cap U_k \) and that \(([x], A) \in \mathcal{O}_{\mathbb{P}(V)}(-d)\). The following lemma relates the representations of \(([x], A) \) in the two local trivialisations.
11.2 Lemma: With all the above notation, if
\[ \tau_j^{(d)}([x], A) = ([x_0 : x_1 : \cdots : x_n], a_j), \quad \tau_k^{(d)}([x], A) = ([x_0 : x_1 : \cdots : x_n], a_k), \]
then \( a_k = (\frac{x_k}{x_j})^d a_j \).

Proof: Note that
\[ (\tau_j^{(-d)})^{-1}([x_0 : x_1 : \cdots : x_n], a) = ([x_0 : x_1 : \cdots : x_n], ax_j^{-d}(x_0, x_1, \ldots, x_n)^\otimes d) \]
and so
\[ \tau_k^{(-d)} \circ (\tau_j^{(-d)})^{-1}([x_0 : x_1 : \cdots : x_n], a) = \tau_k^{(-d)}([x_0 : x_1 : \cdots : x_n], ax_j^{-d}(x_0, x_1, \ldots, x_n)^\otimes d) \]
\[ = ([x_0 : x_1 : \cdots : x_n], ax_k^d x_j^{-d}). \]
We then compute
\[ ([x_0 : x_1 : \cdots : x_n], a_k) = \tau_k^{(-d)}([x], A) = \tau_k^{(-d)} \circ (\tau_j^{(-d)})^{-1} \circ (\tau_j^{(-d)}([x], A) \]
\[ = \tau_k^{(-d)} \circ (\tau_j^{(-d)})^{-1}([x_0 : x_1 : \cdots : x_n], a_j) \]
\[ = ([x_0 : x_1 : \cdots : x_n], ax_k^d x_j^{-d}), \]
giving the desired conclusion.

Since the function
\[ [x_0 : x_1 : \cdots : x_n] \mapsto \left( \frac{x_k}{x_j} \right)^d \]
is a regular function on \( U_j \cap U_k \), we are finally justified in calling \( O_{\mathbb{P}(V)}(-d) \) a vector bundle over \( \mathbb{P}(V) \) since we have found local trivialisations which satisfy an appropriate overlap condition within our algebraic setting.

11.3. Coordinate representations for the positive degree line bundles. Next we turn to the positive degree line bundles. Here we have to consider sections of the bundle
\[ \mathbb{P}(F \oplus S^d(V)) \setminus \mathbb{P}(F \oplus 0), \]
so we establish some notation for this. We use the basis
\[ 1 \oplus 0, 0 \oplus e_1, \ldots, 0 \oplus e_n \]
for \( F \oplus V \) and denote a point
\[ F \oplus V \ni (\xi, x) = \xi(1 \oplus 0) + x_0(0 \oplus e_0) + x_1(0 \oplus e_1) + \cdots + x_n(0 \oplus e_n) \]
by \( (\xi, (x_0, x_1, \ldots, x_n)) \in F \oplus F^n \). The line \([\xi, x]\) is then denoted by \([\xi : [x_0 : x_1 : \cdots : x_n]] \]. We shall also need notation for lines in \( S^d(V) \) and \( F \oplus S^d(V) \). For \( x \in V \setminus \{0\} \) we use the notation
\[ [x_0 : x_1 : \cdots : x_n]^{\otimes d}, \quad [\xi : [x_0 : x_1 : \cdots : x_n]]^{\otimes d} \]
to denote the lines \([x^{\otimes d}] \) and \([\xi \oplus x^{\otimes d}] \), respectively.

We are now able to give the following local trivialisations for the positive degree line bundles.
11.3 Lemma: With all the above notation, for \( j \in \{0, 1, \ldots, n\} \) and \( d \in \mathbb{Z}_{>0} \), the map
\[
\tau_j^{(d)} : \mathcal{O}_{\mathbb{P}(\mathbb{V})}(d)|_{U_j} \to U_j \times \mathcal{F}
\]
\[
([x_0 : x_1 : \cdots : x_n], [\xi : [x_0 : x_1 : \cdots : x_n]^\otimes d]) \mapsto ([x_0 : x_1 : \cdots : x_n], \xi x_j^{-d})
\]

is an isomorphism of vector bundles.

Proof: Suppose that
\[
[x_0 : x_1 : \cdots : x_n] = [y_0 : y_1 : \cdots : y_n]
\]
and
\[
[\xi : [x_0 : x_1 : \cdots : x_n]^\otimes d] = [\eta : [y_0 : y_1 : \cdots : y_n]^\otimes d],
\]
which implies that
\[
x_j^{-1}(x_0, x_1, \ldots, x_n) = y_j^{-1}(y_0, y_1, \ldots, y_n)
\]
and so \( \xi x_j^{-d} = \eta y_j^{-d} \). From this we conclude that \( \tau_j^{(d)} \) is well-defined. To verify that \( \tau_j^{(d)} \) is linear, we recall from Lemma 3.2 that, with the origin \([0 : [x_0 : x_1 : \cdots : x_n]^\otimes d]\), the operations of vector addition and scalar multiplication in \( \mathcal{O}_{\mathbb{P}(\mathbb{V})}(d)|_{[x]} \) are given by
\[
[\xi : [x_0 : x_1 : \cdots : x_n]^\otimes d] + [\eta : [x_0 : x_1 : \cdots : x_n]^\otimes d] = [\xi + \eta : [x_0 : x_1 : \cdots : x_n]^\otimes d],
\]
\[
\alpha [\xi : [x_0 : x_1 : \cdots : x_n]^\otimes d] = [\alpha \xi : [x_0 : x_1 : \cdots : x_n]^\otimes d].
\]
From this, the linearity of \( \tau_j^{(d)} \) follows easily. It is also clear that \( \tau_j^{(d)} \) is an isomorphism since \( x_j \) is nonzero on \( U_j \).

Finally, we can give the transition functions for the line bundles in this case. That is, we let \([x] \in U_j \cap U_k\) and consider the representation of \(([x], [a \oplus x^\otimes d])\) in both trivialisations.

11.4 Lemma: With all of the above notation, if
\[
\tau_j^{(d)}([x], [a \oplus x^\otimes d]) = ([x_0 : x_1 : \cdots : x_n], a_j),
\]
\[
\tau_k^{(d)}([x], [a \oplus x^\otimes d]) = ([x_0 : x_1 : \cdots : x_n], a_k),
\]
then \( a_k = (\frac{x_j}{x_k})^da_j \).

Proof: We have
\[
(\tau_j^{(d)})^{-1}([x_0 : x_1 : \cdots : x_n], a) = ([x_0 : x_1 : \cdots : x_n], ax_j^d : [x_0 : x_1 : \cdots : x_n]^\otimes d])
\]
which gives
\[
\tau_k^{(d)} \circ (\tau_j^{(d)})^{-1}([x_0 : x_1 : \cdots : x_n], a) = \tau_k^{(d)}([x_0 : x_1 : \cdots : x_n], ax_j^d : [x_0 : x_1 : \cdots : x_n]^\otimes d])
\]
\[
= ([x_0 : x_1 : \cdots : x_n], ax_j^d x_k^{-d}).
\]
Thus we compute
\[
([x_0 : x_1 : \cdots : x_n], a_k) = \tau_k^{(d)}([x], [a \oplus x^\otimes d])
\]
\[
= \tau_k^{(d)} \circ (\tau_j^{(d)})^{-1} \circ \tau_j^{(d)}([x], [a \oplus x^\otimes d])
\]
\[
= \tau_k^{(d)} \circ (\tau_j^{(d)})^{-1}([x_0 : x_1 : \cdots : x_n], a_j)
\]
\[
= ([x_0 : x_1 : \cdots : x_n], a_j x_j^d x_k^{-d}),
\]
as desired. 

\[\blacksquare\]
References


