

Privacy-Aware MMSE Estimation

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Abstract—We investigate the problem of the predictability of random variable Y under a privacy constraint dictated by random variable X , correlated with Y , where both predictability and privacy are assessed in terms of the minimum mean-squared error (MMSE). Given that X and Y are connected via a binary-input symmetric-output (BISO) channel, we derive the optimal random mapping $P_{Z|Y}$ such that the MMSE of Y given Z is minimized while the MMSE of X given Z is greater than $(1 - \varepsilon)\text{var}(X)$ for a given $\varepsilon \geq 0$. We also consider the case where (X, Y) are continuous and $P_{Z|Y}$ is restricted to be an additive-noise channel.

I. INTRODUCTION AND PRELIMINARIES

Given private information, represented by X , nature usually generates non-private observable information, say Y , via a fixed channel $P_{Y|X}$. Consider two communicating agents Alice and Bob, where Alice observes Y and wants to reveal it to Bob in order to receive a payoff. Alice, therefore, wishes to disclose Y to Bob as accurately as possible, but in such a way that X is kept almost private from him. For instance, Y may represent the information that a social network (Alice) obtains from its users and X may represent political preferences of the users. Alice wants to disclose Y as accurately as possible to an advertising company and, simultaneously, wishes to protect the privacy of its users. Given a fixed joint distribution P_{XY} , Alice, hence, needs to choose a random mapping $P_{Z|Y}$, the so-called *privacy filter*, to release a new random variable Z , called the *displayed data*, such that X and Z satisfy a privacy constraint and Z maximizes a utility function (corresponding to the predictability of Y).

This problem has been addressed from an information-theoretic viewpoint in [1]–[7] where both utility and privacy are measured in terms of information-theoretic quantities. In particular, in [4] *non-trivial perfect privacy* for discrete X and Y , where Z is required to be statistically independent of X and dependent on Y , is studied. It is shown that non-trivial perfect privacy is possible if and only if X is *weakly independent* of Y , that is, if the set of vectors $\{P_{X|Y}(\cdot) : y \in \mathcal{Y}\}$ is linearly dependent. An equivalent result is obtained by Calmon et al. [5] in terms of the singular values of the operator $f \mapsto \mathbb{E}[f(X)|Y]$.

Although, a connection between the information-theoretic privacy measure and a coding theorem is established in [3], the use of mutual information as a privacy measure is not satisfactorily motivated in an *operational* sense. To have an operational measure of privacy, in this paper we take an

estimation-theoretic approach and define both the privacy and utility functions in terms of the minimum mean-squared error (MMSE). For a given pair of random variables (U, V) , the MMSE of estimating U given V is

$$\text{mmse}(U|V) := \mathbb{E}[(U - \mathbb{E}[U|V])^2] = \mathbb{E}[\text{var}(U|V)],$$

where $\text{var}(\cdot)$ denotes the conditional variance. The privacy filter $P_{Z|Y}$ is said to satisfy the ε -strong estimation privacy condition for some $\varepsilon \geq 0$ if $\text{mmse}(f(X)|Y) \geq (1 - \varepsilon)\text{var}(f(X))$ for any Borel function¹ f of X and similarly, it is said to satisfy the ε -weak estimation privacy condition if $\text{mmse}(X|Y) \geq (1 - \varepsilon)\text{var}(X)$. The parameter ε determines the level of desired privacy; in particular, $\varepsilon = 0$ corresponds to perfect privacy. We propose to use the estimation noise to signal ratio (ENSR), defined by $\frac{\text{mmse}(Y|Z)}{\text{var}(Y)}$, as the loss function associated with Y and Z . The goal is to choose $P_{Z|Y}$ which satisfies the strong (resp., weak) estimation privacy condition and *minimizes* the ENSR (or equivalently maximizes $\frac{\text{var}(Y)}{\text{mmse}(Y|Z)}$ as the utility function), which ensures the best predictability of Y given a privacy-preserving Z . The function $\text{sENSR}_\varepsilon(X; Y)$ (resp., $\text{wENSR}_\varepsilon(X; Y)$) is introduced as this minimum to quantify the above goal.

To evaluate $\text{sENSR}_\varepsilon(X; Y)$, we first obtain an equivalent characterization of the ε -strong estimation privacy condition. We then show that $\text{sENSR}_\varepsilon(X; Y)$ and $\text{wENSR}_\varepsilon(X; Y)$ admit closed-form expressions when $P_{X|Y}$ is a BISO channel. Moreover, when X is discrete, we develop a bound characterizing the privacy-constrained error probability, $\Pr(\hat{Y}(Z) \neq Y)$, for all estimators $\hat{Y}(Z)$ given a privacy-preserving Z , thus generalizing the results of [9]. In particular, we show that the fundamental bound on privacy-constrained error probability decreases *linearly* as ε increases, analogously to [9, Corollaries 3,5]. We also study $\text{sENSR}_\varepsilon(X^n; Y^n)$ when n independent identically distributed (i.i.d.) copies (X^n, Y^n) of (X, Y) are available. We demonstrate that if the class of privacy filters is constrained to be memoryless, then $\text{sENSR}_\varepsilon(X^n; Y^n)$ remains the same for any n . This is reminiscent of the tensorization property for maximal correlation [10].

In addition, $\text{sENSR}_\varepsilon(X; Y)$ is considered for the case where (X, Y) has a joint probability density function by studying the problem where the displayed data Z is obtained

¹This is reminiscent of *semantic security* [8] in the cryptography community. An encryption mechanism is said to be semantically secure if the adversary's advantage for correctly guessing *any function* of the private data given an observation of the mechanism's output (i.e., the ciphertext) is required to be negligible.

by passing Y through an additive noise channel. In this case, we show that for a Gaussian noise process, jointly Gaussian (X_G, Y_G) is the worst case (i.e., has the largest ENSR). We also show that if only Y_G is Gaussian then the ENSR of (X, Y_G) is very close to the Gaussian ENSR if the maximal correlation between X and Y_G is close to the correlation coefficient between X and Y_G .

We omit the proof of most of the paper's results due to space limitation. The proofs are available in [11].

II. STRONG ESTIMATION PRIVACY GUARANTEE

Consider the scenario where Alice observes Y which is correlated with a private random variable X , drawn from a given joint distribution P_{XY} , and wishes to transmit the random variable Z to Bob to receive some utility from him. Her goal is to maximize the utility while making sure that Bob cannot efficiently estimate any non-trivial function of X given Z . To formalize this privacy guarantee, we give the following definition. In what follows random variables X , Y , and Z have alphabets \mathcal{X} , \mathcal{Y} , and \mathcal{Z} , respectively, which are either finite subsets of \mathbb{R} or they are all equal to \mathbb{R} .

Definition 1. Given a joint distribution P_{XY} and $\varepsilon \geq 0$, Z is said to satisfy ε -strong estimation privacy, denoted as $Z \in \Gamma_\varepsilon(P_{XY})$, if there exists a random mapping (channel) $P_{Z|Y}$ that induces a joint distribution $P_X \times P_{Z|X}$ on $\mathcal{X} \times \mathcal{Z}$, via the Markov condition $X \dashrightarrow Y \dashrightarrow Z$, satisfying

$$\text{mmse}(f(X)|Z) \geq (1 - \varepsilon)\text{var}(f(X)), \quad (1)$$

for any non-constant Borel functions f on \mathcal{X} . Similarly, Z is said to satisfy ε -weak estimation privacy, denoted as $Z \in \partial\Gamma_\varepsilon(P_{XY})$, if (1) is satisfied only for the identity function $f(x) = x$.

In the sequel, we drop in the notation the dependence of $\Gamma_\varepsilon(P_{XY})$ (resp., $\partial\Gamma_\varepsilon(P_{XY})$) on P_{XY} and simply write Γ_ε (resp., $\partial\Gamma_\varepsilon$).

Suppose the utility Alice receives from Bob is $\frac{\text{var}(Y)}{\text{mmse}(Y|Z)}$. The utility is maximized (and is equal to ∞) when $Z = Y$ with probability one and is minimized (and is equal to one) when Z is independent of Y . In order to quantify the tradeoff between privacy guarantee (introduced above) and the utility, we propose the following function, which we call the strong privacy-aware estimation noise to signal ratio (ENSR):

$$\text{sENSR}_\varepsilon(X; Y) := \inf_{Z \in \Gamma_\varepsilon} \frac{\text{mmse}(Y|Z)}{\text{var}(Y)}. \quad (2)$$

Similarly, we can use weak estimation privacy to define the weak privacy-aware ENSR as follows:

$$\text{wENSR}_\varepsilon(X; Y) := \inf_{Z \in \partial\Gamma_\varepsilon} \frac{\text{mmse}(Y|Z)}{\text{var}(Y)}. \quad (3)$$

Remark 1. Rényi [12] defined the *correlation ratio* of Y on Z , denoted by $\eta_Z(Y)$, as $\eta_Z^2(Y) := \frac{\text{var}(\mathbb{E}[Y|Z])}{\text{var}(Y)}$ which can be shown to be equal to $\sup_g \rho^2(Y; g(Z))$, where ρ is the standard correlation coefficient. It is clear from the law of total variance that $\frac{\text{mmse}(Y|Z)}{\text{var}(Y)} = 1 - \eta_Z^2(Y)$.

In the sequel, we obtain an equivalent characterization for the random mapping $P_{Z|X}$ which generates $Z \in \Gamma_\varepsilon$. To this goal, we need the following definition.

Definition 2 ([12]). Given random variables U and V taking values over arbitrary alphabets \mathcal{U} and \mathcal{V} , respectively, the maximal correlation $\rho_m(U; V)$ is defined as

$$\begin{aligned} \rho_m^2(U; V) &:= \sup_{f, g} \rho^2(f(U), g(V)) \\ &= \sup_{(f(U), g(V)) \in \mathcal{S}^0} \frac{\mathbb{E}^2[f(U)g(V)]}{\text{var}(f(U))\text{var}(g(V))}, \end{aligned}$$

where \mathcal{S}^0 is the collection of all pairs of real-valued measurable functions f and g of U and V , respectively, such that $\mathbb{E}[f(U)] = \mathbb{E}[g(V)] = 0$ and $0 < \text{var}(f(U)), \text{var}(g(V)) < \infty$.

Rényi [12] derived an equivalent characterization of maximal correlation as

$$\rho_m^2(U; V) = \sup_{f \in \mathcal{S}_U^0} \frac{\mathbb{E}[\mathbb{E}^2[f(U)|V]]}{\text{var}(f(U))}, \quad (4)$$

where \mathcal{S}_U^0 is the collection of real-valued measurable functions f of U such that $\mathbb{E}[f(U)] = 0$ and $0 < \text{var}(f(U)) < \infty$.

Theorem 1. For a given P_{XY} , $Z \in \Gamma_\varepsilon$ if and only if there exists $P_{Z|Y}$ which induces $P_{Z|X}$ via $X \dashrightarrow Y \dashrightarrow Z$ satisfying $\rho_m^2(X; Z) \leq \varepsilon$ for any $\varepsilon \geq 0$.

In light of Theorem 1 and Remark 1, we can alternatively write $\text{sENSR}_\varepsilon(X; Z)$ and $\text{wENSR}_\varepsilon(X; Z)$ as

$$\text{sENSR}_\varepsilon(X; Y) = 1 - \sup_{\substack{P_{Z|Y}: \rho_m^2(X; Z) \leq \varepsilon, \\ X \dashrightarrow Y \dashrightarrow Z}} \eta_Z^2(Y), \quad (5)$$

and

$$\text{wENSR}_\varepsilon(X; Y) = 1 - \sup_{\substack{P_{Z|Y}: \eta_Z^2(X) \leq \varepsilon, \\ X \dashrightarrow Y \dashrightarrow Z}} \eta_Z^2(Y), \quad (6)$$

for any $\varepsilon \geq 0$. We note that, using the Support Lemma [13], one can show that the set Γ_ε can be described by considering $Z \in \mathcal{Z}$ with $|\mathcal{Z}| \leq |\mathcal{Y}| + 1$ in case \mathcal{Y} is finite. We also note that since both maximal correlation and correlation ratio satisfy the data processing inequality [3], [9], i.e. $\rho_m^2(X; Z) \leq \eta_m^2(X; Y)$ and $\eta_Z^2(X) \leq \eta_Y^2(X)$ if $X \dashrightarrow Y \dashrightarrow Z$, we can restrict our attention to $0 \leq \varepsilon \leq \rho_m^2(X; Y)$ and $0 \leq \varepsilon \leq \eta_Y^2(X)$ in (5) and (6), respectively.

III. CHARACTERIZATION OF $\text{sENSR}_\varepsilon(X; Y)$ AND $\text{wENSR}_\varepsilon(X; Y)$ FOR DISCRETE X AND Y

We first derive some properties of $\text{sENSR}_\varepsilon(X; Y)$ and $\text{wENSR}_\varepsilon(X; Y)$ when both X and Y are discrete. For a given P_{XY} and $0 \leq \varepsilon \leq \rho_m^2(X; Y)$, we have the following trivial bounds:

$$0 \leq \text{wENSR}_\varepsilon(X; Y) \leq \text{sENSR}_\varepsilon(X; Y) \leq 1 - \varepsilon, \quad (7)$$

where the last inequality can be proved by noticing that $\text{sENSR}_\varepsilon(X; Y) \leq \text{sENSR}_\varepsilon(Y; Y)$ and

$$\text{mmse}(Y|Z) = \text{var}(Y)(1 - \eta_Z^2(Y))$$

$$\geq \text{var}(Y)(1 - \rho_m^2(Y; Z)), \quad (8)$$

where (8) follows from the definition of maximal correlation. The lower bound $0 \leq \text{sENSR}_\varepsilon(X; Y)$ in (7) is achieved if and only if $\rho_m^2(X; Y) = \varepsilon$. On the other hand, when $\varepsilon = 0$, the upper bound $\text{sENSR}_0(X; Y) \leq 1$ is tight if and only if all $Z \in \Gamma_0$ are independent of Y . Hence, from [3, Lemma 6], $\text{sENSR}_0(X; Y) = 1$ if and only if X is not weakly independent of Y . In particular, if $|\mathcal{Y}| > |\mathcal{X}|$ then $\text{sENSR}_0(X; Y) < 1$, and if $|\mathcal{Y}| = 2$, then $\text{sENSR}_0(X; Y) = 1$.

The map $\varepsilon \mapsto \text{sENSR}_\varepsilon(X; Y)$ is clearly non-increasing. The following lemma states that this map is indeed convex and thus strictly decreasing. As another consequence of this convexity, we obtain an upper bound on $\text{sENSR}_\varepsilon(X; Y)$ which strictly strengthens (7).

Lemma 1. *For any joint distribution P_{XY} , the maps $\varepsilon \mapsto \text{sENSR}_\varepsilon(X; Y)$ and $\varepsilon \mapsto \text{wENSR}_\varepsilon(X; Y)$ are convex.*

In light of the convexity of $\varepsilon \mapsto \text{sENSR}_\varepsilon(X; Y)$, the following corollaries are immediate.

Corollary 1. *For a given P_{XY} , the maps $\varepsilon \mapsto \frac{1 - \text{sENSR}_\varepsilon(X; Y)}{\varepsilon}$ and $\varepsilon \mapsto \frac{1 - \text{wENSR}_\varepsilon(X; Y)}{\varepsilon}$ are non-increasing over $(0, 1)$.*

Corollary 2. *For a given P_{XY} and $0 \leq \varepsilon \leq \rho_m^2(X; Y)$,*

$$\text{sENSR}_\varepsilon(X; Y) \leq 1 - \frac{\varepsilon}{\rho_m^2(X; Y)}.$$

Remark 2. Note that simple calculations reveal that the upper bound in Corollary 2 is achieved by the erasure channel:

$$P_{Z|Y}(z|y) = \begin{cases} 1 - \tilde{\delta}, & \text{if } z = y \\ \tilde{\delta}, & \text{if } z = \text{e}, \end{cases}$$

for all $y \in \mathcal{Y}$ and the erasure probability $\tilde{\delta} = 1 - \frac{\varepsilon}{\rho_m^2(X; Y)}$ for $0 \leq \varepsilon \leq \rho_m^2(X; Y)$.

A. Binary Input Symmetric Output $P_{X|Y}$

We now turn our attention to the special case where the backward channel from Y to X , $P_{X|Y}$, belongs to a family of channels called binary input symmetric output (BISO) channels, see e.g., [14]. For $Y \sim \text{Bernoulli}(p)$, $P_{X|Y}$ is BISO if, for any $x \in \mathcal{X} = \{0, \pm 1, \pm 2, \dots, \pm k\}$, we have $P_{X|Y}(x|1) = P_{X|Y}(-x|0)$. As pointed out in [14], one can always assume that the output alphabet $\mathcal{X} = \{\pm 1, \pm 2, \dots, \pm k\}$ has even number of elements by splitting the symbol 0 into two symbols and assigning them equal probabilities. Binary symmetric channels and binary erasure channels are both BISO. In the following theorem, we show that $\text{wENSR}_\varepsilon(X; Y)$ can be calculated in closed-form when $P_{X|Y}$ is a BISO channel.

Theorem 2. *Let $Y \sim \text{Bernoulli}(p)$ and $P_{X|Y}$ be a BISO channel. Then for $0 \leq \varepsilon \leq \rho_m^2(X; Y)$, we have*

$$\text{wENSR}_\varepsilon(X; Y) = 1 - \varepsilon \frac{\text{var}(X)}{4\text{var}(Y)\mathbb{E}^2[X|Y=1]},$$

and

$$1 - \varepsilon \frac{\text{var}(X)}{4\text{var}(Y)\mathbb{E}^2[X|Y=1]} \leq \text{sENSR}_\varepsilon(X; Y) \leq 1 - \frac{\varepsilon}{\rho_m^2(X; Y)}.$$

Similar to [9], we also consider the tradeoff between strong estimation privacy and the probability of correctly guessing Y . To quantify this, let $\hat{Y} : \mathcal{Z} \rightarrow \mathcal{Y}$ be the Bayes decoding map. The resulting (minimum) error probability is $\Pr(\hat{Y}(Z) \neq Y)$. Let

$$P_\varepsilon^e(X; Y) := \min_{Z \in \Gamma_\varepsilon} \Pr(\hat{Y}(Z) \neq Y). \quad (9)$$

Note that when Z is independent of Y , the optimal Bayes decoding map yields $\Pr(\hat{Y}(Z) \neq Y) = 1 - p$, if $p = P_Y(1) \geq \frac{1}{2}$. Using a similar argument as in [15, Appendix A], we establish the following connection between $P_\varepsilon^e(X; Y)$ and $\text{wENSR}_\varepsilon(X; Y)$.

Proposition 1. *Let $Y \sim \text{Bernoulli}(p)$ with $p \geq \frac{1}{2}$. Then we have*

$$\text{wENSR}_\varepsilon(X; Y) \leq \frac{P_\varepsilon^e(X; Y)}{\text{var}(Y)} \leq 2\text{wENSR}_\varepsilon(X; Y)$$

Calmon et al. [9] considered the same problem for $X = Y$, i.e., minimizing $\Pr(\hat{X}(Z) \neq X)$ over all $P_{Z|X}$ such that $\rho_m^2(X; Z) \leq \varepsilon$ and showed that the best privacy-constrained error probability is lower bounded by a straight line of ε with negative slope. Combining Theorem 2 and Proposition 1, we can lower bound $P_\varepsilon^e(X; Y)$ for all BISO $P_{X|Y}$ by a straight line in ε as follows:

$$P_\varepsilon^e(X; Y) \geq \text{var}(Y) - \varepsilon \frac{\text{var}(X)}{4\mathbb{E}^2[X|Y=1]},$$

which generalizes [9, Corollaries 3,5].

In the following, we consider two examples of BISO channels for which the bounds in Theorem 2 coincide. First consider $P_{X|Y}$ being a binary symmetric channel with crossover probability α , denoted as $\text{BSC}(\alpha)$.

Lemma 2. *For $Y \sim \text{Bernoulli}(p)$ and $P_{X|Y} = \text{BSC}(\alpha)$ for $\alpha \in [0, \frac{1}{2})$, we have for $0 \leq \varepsilon \leq \rho_m^2(X; Y)$,*

$$1 - \frac{\varepsilon \text{var}(X)}{4(1 - 2\alpha)^2 \text{var}(Y)} \leq \text{sENSR}_\varepsilon(X; Y) \leq 1 - \frac{\varepsilon}{\rho_m^2(X; Y)},$$

and

$$\text{var}(Y) - \frac{\varepsilon \text{var}(X)}{4(1 - 2\alpha)^2} \leq P_\varepsilon^e(X; Y) \leq 2 \left[\text{var}(Y) - \frac{\varepsilon \text{var}(X)}{4(1 - 2\alpha)^2} \right].$$

Moreover, if $p = 0.5$,

$$\text{sENSR}_\varepsilon(X; Y) = \text{wENSR}_\varepsilon(X; Y) = 1 - \frac{\varepsilon}{(1 - 2\alpha)^2},$$

and the optimal channel is $\text{BEC}(\tilde{\delta})$ (see Fig. 1) where

$$\tilde{\delta} = 1 - \frac{\varepsilon}{(1 - 2\alpha)^2}. \quad (10)$$

We next consider $P_{X|Y}$ being a binary erasure channel with erasure probability δ , denoted as $\text{BEC}(\delta)$.

Lemma 3. *For $Y \sim \text{Bernoulli}(p)$ and $P_{X|Y} = \text{BEC}(\delta)$ for $\delta \in [0, 1)$, we have for $0 \leq \varepsilon \leq \rho_m^2(X; Y)$,*

$$1 - \frac{\varepsilon \text{var}(X)}{4\text{var}(Y)(1 - \delta)^2} \leq \text{sENSR}_\varepsilon(X; Y) \leq 1 - \frac{\varepsilon}{1 - \delta},$$

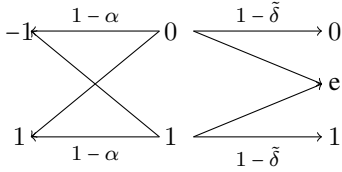


Fig. 1. Optimal privacy filter where $P_{Y|X} = \text{BSC}(\alpha)$ with $Y \sim \text{Bernoulli}(0.5)$ where δ is specified in (10).

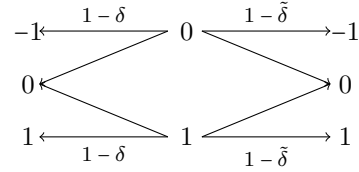


Fig. 2. Optimal privacy filter where $P_{X|Y} = \text{BEC}(\delta)$ with $Y \sim \text{Bernoulli}(0.5)$ where δ is specified in (11).

and

$$\text{var}(Y) - \frac{\varepsilon \text{var}(X)}{4(1-\delta)^2} \leq \mathbb{P}_\varepsilon^e(X; Y) \leq 2 \left[\text{var}(Y) - \frac{\varepsilon \text{var}(X)}{4(1-\delta)^2} \right].$$

Moreover, if $p = 0.5$,

$$\text{sENSR}_\varepsilon(X; Y) = 1 - \frac{\varepsilon}{1-\delta},$$

and the optimal channel is $\text{BEC}(\tilde{\delta})$ (see Fig. 2) where

$$\tilde{\delta} = 1 - \frac{\varepsilon}{1-\delta}. \quad (11)$$

We conclude this section by connecting the above results to initial efficiency². For BISO channels, we define the initial efficiency of $f_\varepsilon(X; Y) := \text{var}(Y) - \text{var}(Y) \text{wENSR}_\varepsilon(X; Y)$ with respect to ε as the derivative $f'_0(X; Y)$ of $\varepsilon \mapsto f_\varepsilon(X; Y)$ at $\varepsilon = 0$. In fact, $f'_0(X; Y)$ quantifies the decrease of $\text{mmse}(Y|Z)$ when ε slightly increases from 0. Then since for any BISO $P_{X|Y}$, $f_0(X; Y) = 0$, using Corollary 1 and the convexity of $\varepsilon \mapsto \text{wENSR}_\varepsilon(X; Y)$, we can write

$$\begin{aligned} f'_0(X; Y) &= \lim_{\varepsilon \downarrow 0} \frac{f_\varepsilon(X; Y)}{\varepsilon} = \sup_{\varepsilon > 0} \frac{f_\varepsilon(X; Y)}{\varepsilon} \\ &= \text{var}(X) \max_{\substack{P_{Z|Y}: \\ X \rightarrow Y \rightarrow Z}} \frac{\text{var}(Y) - \text{mmse}(Y|Z)}{\text{var}(X) - \text{mmse}(X|Z)} \end{aligned}$$

We can, therefore, conclude from Theorem 2 that for a given pair of random variables (X, Y) with BISO $P_{X|Y}$, we have

$$\max_{\substack{P_{Z|Y}: \\ X \rightarrow Y \rightarrow Z}} \frac{\text{var}(Y) - \text{mmse}(Y|Z)}{\text{var}(X) - \text{mmse}(X|Z)} = \frac{1}{4\mathbb{E}^2[X|Y=1]}.$$

B. $\text{sENSR}_\varepsilon(X; Y)$ and $\text{wENSR}_\varepsilon(X; Y)$ with n i.i.d. observations

Let (X^n, Y^n) be n i.i.d. copies of (X, Y) with a given distribution P_{XY} . Similar to (2) and (3), we can define

$$\text{sENSR}_\varepsilon(X^n; Y^n) := 1 - \frac{1}{n} \sup_{Z \in \Gamma_\varepsilon^{\otimes n}} \sum_{i=1}^n \eta_{Z^n}^2(Y_i),$$

and

$$\text{wENSR}_\varepsilon(X^n; Y^n) := 1 - \frac{1}{n} \sup_{Z \in \partial \Gamma_\varepsilon^{\otimes n}} \sum_{i=1}^n \eta_{Z^n}^2(Y_i),$$

²Initial efficiency was previously defined for the common randomness problem in [16], for secret key generation in [17], for incremental growth rate in a stock market [18], and for information extraction under privacy constraint in [3].

where $\Gamma_\varepsilon^{\otimes n} := \{P_{Z^n|Y^n} : \rho_m^2(X^n; Z^n) \leq \varepsilon\}$, and $\partial \Gamma_\varepsilon^{\otimes n} := \{P_{Z^n|Y^n} : \sum_{i=1}^n \eta_{Z^n}^2(X_i) \leq n\varepsilon\}$.

As shown in [5], $\text{sENSR}_0(X; Y) < 1$ if and only if the smallest singular value, σ_{\min} , of the operator $f(X) \mapsto \mathbb{E}[f(X)|Y]$ is zero. It is also shown in [5, Proposition 1] that the smallest singular value of the operator $f(X^n) \mapsto \mathbb{E}[f(X^n)|Y^n]$ for i.i.d. (X^n, Y^n) , is σ_{\min}^n and it hence follows that unless $\sigma_{\min} = 1$, $\lim_{n \rightarrow \infty} \text{sENSR}_0(X^n; Y^n) < 1$ for any distribution P_{XY} and hence non-trivial perfect privacy is possible. The following result implies that the optimal privacy filter $P_{Z^n|Y^n}$ which achieves non-trivial perfect privacy cannot be a memoryless channel.

Proposition 2. *Let (X^n, Y^n) be an i.i.d. copies of (X, Y) with distribution P_{XY} . If the family of feasible random mapping in the optimizations (5) and (6) is constrained to be of the form $P_{Z^n|Y^n}(z^n|y^n) = \prod_{i=1}^n P_i(z_i|y_i)$, then*

$$\begin{aligned} \text{sENSR}_\varepsilon(X^n; Y^n) &= \text{sENSR}_\varepsilon(X; Y), \\ \text{wENSR}_\varepsilon(X^n; Y^n) &= \text{wENSR}_\varepsilon(X; Y). \end{aligned}$$

IV. CONTINUOUS (X, Y) , ADDITIVE GAUSSIAN NOISE AS PRIVACY FILTER

In this section, we assume that X and Y are both absolutely continuous random variables and the channel $P_{Z|Y}$ is modelled by a scaled additive stable³ noise variable N_f which is independent of (X, Y) and has density f with zero mean and unit variance, i.e.,

$$Z_\gamma = Y + \gamma N_f,$$

for some $\gamma \geq 0$. We then define

$$\text{sENSR}_\varepsilon^f(X; Y) := 1 - \sup_{\gamma \in \mathcal{C}_\varepsilon(P_{XY})} \eta_{Z_\gamma}^2(Y),$$

and

$$\text{wENSR}_\varepsilon^f(X; Y) := 1 - \sup_{\gamma \in \partial \mathcal{C}_\varepsilon(P_{XY})} \eta_{Z_\gamma}^2(Y),$$

where $\mathcal{C}_\varepsilon(P_{XY}) := \{\gamma \geq 0 : \rho_m^2(X; Z_\gamma) \leq \varepsilon\}$ and $\partial \mathcal{C}_\varepsilon(P_{XY}) := \{\gamma \geq 0 : \eta_{Z_\gamma}^2(X) \leq \varepsilon\}$. If the noise process is Gaussian $N(0, 1)$, we denote N_f , $\text{sENSR}_\varepsilon^f(X; Y)$, and $\text{wENSR}_\varepsilon^f(X; Y)$ by N_G , $\text{sENSR}_\varepsilon(X; Y)$, and $\text{wENSR}_\varepsilon(X; Y)$, respectively.

³A random variable X with distribution P is called stable if for X_1, X_2 i.i.d. according to P , for any constants a, b , the random variable $aX_1 + bX_2$ has the same distribution as $cX + d$ for some constants c and d [19, Chapter 1].

The bounds for $w\text{ENSR}_\varepsilon(X; Y)$ obtained in (7) clearly hold: $0 \leq w\text{ENSR}_\varepsilon^f(X; Y) \leq s\text{ENSR}_\varepsilon^f(X; Y) \leq 1 - \varepsilon$, and in particular, $s\text{ENSR}_0^f(X; Y) \leq 1$. In the following, we show that this last inequality is in fact an equality.

Proposition 3. *For a given absolutely continuous (X, Y) , the map $\varepsilon \mapsto s\text{ENSR}_\varepsilon^f(X; Y)$ is non-negative, strictly decreasing and satisfies*

$$s\text{ENSR}_0^f(X; Y) = 1.$$

Example 1. Let (X_G, Y_G) be jointly Gaussian with correlation coefficient ρ and let $N_f = N_G$. Without loss of generality, we can assume that $\mathbb{E}[X_G] = \mathbb{E}[Y_G] = 0$. It is known [12] that $\rho_m^2(X_G; Z_\gamma) = \rho^2(X_G; Z_\gamma)$ and hence

$$\rho_m^2(X_G; Z_\gamma) = \rho^2 \frac{\text{var}(Y_G)}{\text{var}(Y_G) + \gamma^2},$$

which implies that $\gamma \mapsto \rho_m^2(X_G; Z_\gamma)$ is strictly decreasing and hence $\rho_m^2(X_G; Z_\gamma) = \varepsilon$ for $0 \leq \varepsilon \leq \rho_m^2(X_G; Y_G) = \rho^2$ has a unique solution

$$\gamma_\varepsilon^2 := \text{var}(Y_G) \left(\frac{\rho^2}{\varepsilon} - 1 \right)$$

and $Z_\gamma \in \Gamma_\varepsilon$ for any $\gamma \geq \gamma_\varepsilon$. On the other hand, $\text{mmse}(Y_G|Z_\gamma) = \text{var}(Y_G) \frac{\gamma^2}{\text{var}(Y_G) + \gamma^2}$ which shows that the map $\gamma \mapsto \text{mmse}(Y_G|Z_\gamma)$ is strictly increasing and hence

$$s\text{ENSR}_\varepsilon(X_G; Y_G) = \frac{\text{mmse}(Y_G|Z_{\gamma_\varepsilon})}{\text{var}(Y_G)} = 1 - \frac{\varepsilon}{\rho^2}. \quad (12)$$

It is easy to check that that $\eta_{Z_\varepsilon}^2(X_G) = \rho_m^2(X_G; Z_\varepsilon) = \varepsilon$. This then implies that for the jointly Gaussian (X_G, Y_G) , $\mathcal{C}_\varepsilon(P_{X_G Y_G}) = \partial \mathcal{C}_\varepsilon(P_{X_G Y_G})$. Hence, for $0 \leq \varepsilon \leq \rho^2$,

$$s\text{ENSR}_\varepsilon(X_G; Y_G) = w\text{ENSR}_\varepsilon(X_G; Y_G) = 1 - \frac{\varepsilon}{\rho^2}. \quad (13)$$

This example suggests that the bound in Corollary 2 still holds for absolutely continuous (X, Y) in this model. We prove this observation in the following lemma with the assumption that $N = N_G$.

Lemma 4. *For a given absolutely continuous (X, Y) , we have for $0 \leq \varepsilon \leq \rho_m^2(X; Y)$*

$$w\text{ENSR}_\varepsilon(X; Y) \leq s\text{ENSR}_\varepsilon(X; Y) \leq 1 - \frac{\varepsilon}{\rho_m^2(X; Y)}.$$

Combined with (13), this lemma also shows that among all (X, Y) with identical maximal correlation, the jointly Gaussian (X_G, Y_G) yields the largest $s\text{ENSR}_\varepsilon(X; Y)$ when the noise process is Gaussian. This observation is similar to [20, Theorem 12] which states that for Gaussian noise, the Gaussian input is the worst with no privacy constraint imposed; i.e., $\text{mmse}(Y|Y + N_G) \leq \text{mmse}(Y_G|Y_G + N_G)$ where Y_G is Gaussian having the same variance as Y .

We finally obtain a lower bound on $s\text{ENSR}_\varepsilon(X; Y)$ when only Y is Gaussian.

Lemma 5. *Let X be jointly distributed with Gaussian Y_G .*

Then,

$$1 - \frac{\varepsilon}{\rho^2(X; Y_G)} \leq s\text{ENSR}_\varepsilon(X; Y_G) \leq 1 - \frac{\varepsilon}{\rho_m^2(X; Y_G)},$$

This lemma, together with Example 1, implies that

$$s\text{ENSR}_\varepsilon(X_G, Y_G) - s\text{ENSR}_\varepsilon(X; Y_G) \leq \varepsilon \left[\frac{1}{\rho^2(X; Y_G)} - \frac{1}{\rho_m^2(X; Y_G)} \right]$$

for Gaussian X_G which satisfies $\rho_m^2(X_G; Y_G) = \rho_m^2(X; Y_G)$. This demonstrates that if the difference $\rho_m^2(X; Y_G) - \rho^2(X; Y_G)$ is small, then $s\text{ENSR}_\varepsilon(X; Y_G)$ is very close to $s\text{ENSR}_\varepsilon(X_G; Y_G)$.

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