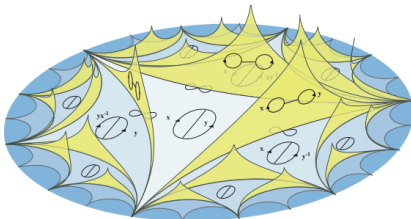


A Nielsen-Thurston inspired story of iterating free group automorphisms and efficiently deforming graphs

Catherine PFAFF
(with Y. Algom-Kfir, I. Kapovich, L. Mosher)

University of California, Santa Barbara

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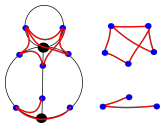
Is A Tale With Two Surprisingly Interconnected Themes

What happens when
you iterate a
free group automorphism?

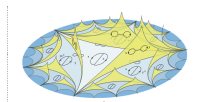


What happens when
you efficiently deform
a metric graph?

- Outer automorphism invariants



- Geodesics in Culler-Vogtmann Outer Space



The Backstory (will return to)

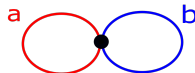
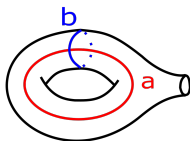
$$GL_2(\mathbb{Z}) \cong \text{MCG}(\text{torus}) \cong \text{Out}(F_2)$$

2x2 integer matrices
of determinant ± 1

$\text{Homeo}(\text{torus}) / \text{Homotopy}$

$\text{Aut}(F_2) / \text{Inn}(F_2)$

$$\begin{bmatrix} a & b \\ b & a \end{bmatrix}$$



The Free Group F_r

$F_r = \langle x_1, \dots, x_r \rangle$ **rank- r free group**

Example: $F_3 = \langle x_1, x_2, x_3 \rangle$

Some elements:

$$x_2 x_1 x_3^{-1} \quad \text{or} \quad x_3 x_1^{-1} x_2^{-1} x_3^{-1} x_1 \quad \text{or} \quad x_3^{-1} x_2 x_1$$

Multiplication:

$$x_1 x_3^{-1} * x_3 x_2 x_1 x_3^{-1} = x_1 \cancel{x_3^{-1}} \cancel{x_3} x_2 x_1 x_3^{-1} = x_1 x_2 x_1 x_3^{-1}$$

Outer Automorphism Group of the Free Group $Out(F_r)$

$F_r = \langle x_1, \dots, x_r \rangle$ rank- r free group

Definition

$$Out(F_r) = \frac{Aut(F_r)}{Inn(F_r) = \{\varphi_a \mid \varphi_a(b) = aba^{-1} \ \forall \ a, b \in F_r\}}$$

To define $\Phi \in Aut(F_r)$, just need to describe images of generators:

$$\Phi = \begin{cases} x_1 \mapsto x_1 x_3^{-1} \\ x_2 \mapsto x_3 \\ x_3 \mapsto x_2 \end{cases}$$

Nielsen proved they're compositions of these “replacement” functions, e.g.

• $x_2 \rightsquigarrow x_2 x_3^{-1}$ (& $x_2^{-1} \rightsquigarrow x_3 x_2^{-1}$).

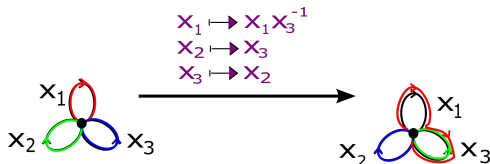
$$\varphi(x_2 x_1) = x_2 x_3^{-1} x_1 \quad \& \quad \varphi(x_3 x_1^{-1} x_2^{-1} x_3^{-1} x_2) = x_3 x_1^{-1} x_3 x_2^{-1} x_3^{-1} x_2 x_3^{-1}$$

Outer Automorphism Group of the Free Group $Out(F_r)$

To utilize work of Nielsen, Skora, Stallings, Whitehead, and Bestvina-Feighn-Handel we view

$$\Phi = \begin{cases} x_1 \mapsto x_1 x_3^{-1} \\ x_2 \mapsto x_3 \\ x_3 \mapsto x_2 \end{cases}$$

as a homotopy equivalence of graphs:



The Backstory

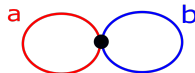
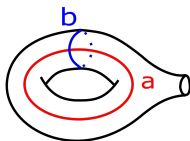
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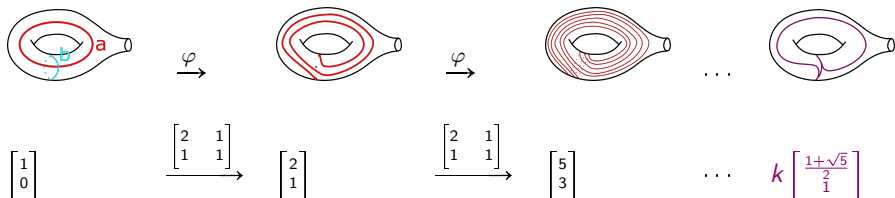
$\text{Aut}(F_2) / \text{Inn}(F_2)$

$$\begin{bmatrix} a & b \\ b & a \end{bmatrix}$$



Nielsen-Thurston studied asymptotic dynamical invariants

For φ a generic surface homeo, repeated application of φ to any curve limits on the same object...



Some important “conjugacy class” invariants:

$GL(2, \mathbb{Z})$

- Eigenvector
- Dominant eigenval

$MCG(\Sigma_{1,1})$

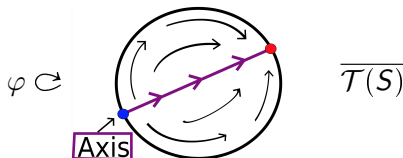
- Lamination
- Indices / IWG
- Stretch factor

$Out(F_2)$

- Lamination
- Axis bundle
- Indices / IWG
- Stretch factor

$\mathcal{T}(S)$: Deformation space of hyp. metrics on a surface S

- Amazingly, the space of metrics is itself a metric space &...
- [Royden] For closed surface S : $Isom(\mathcal{T}(S)) \cong MCG(S)$
- [Thurston] $\mathcal{T}(S)$ is compactified by projective measured laminations on S & $\overline{\mathcal{T}(S)}$ is a ball
- Bers, Marden, Masur, Strebel, Thurston, & others connected mapping class group invariants with geodesics in $\mathcal{T}(S)$

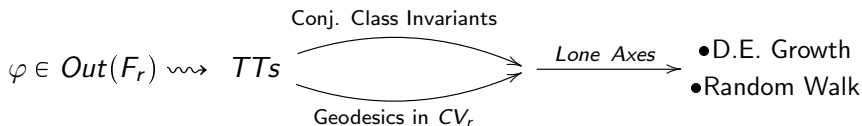


The $Out(F_r)$ Tale: Interconnected Goals & Strategy

Interconnected Goals:

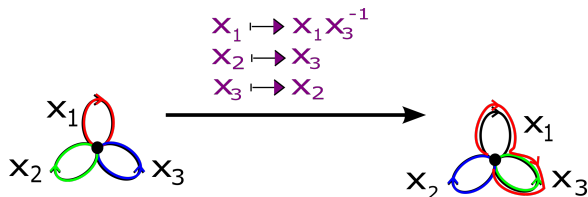
- 1 Understanding $Out(F_r)$ conjugacy class invariants
- 2 Understanding Geodesics in Outer Space CV_r

Strategy/Outline:



Train Track Representatives (Bestvina-Handel)

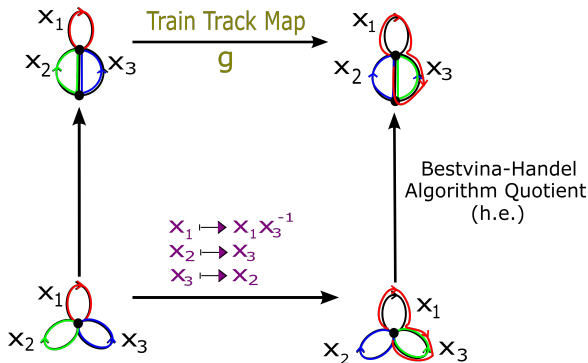
Recall: $\varphi \in \text{Out}(F_r)$ always have topological representatives:



- But iteration may lead to cancellation on edge interiors

Train Track Representatives (Bestvina-Handel)

Nice $\varphi \in \text{Out}(F_r)$ have **train track representatives** $g: \Gamma \xrightarrow{\text{h.e.}} \Gamma$



No cancellation on edge interiors even after iteration!

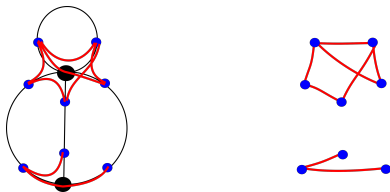
$Out(F_r)$ Conjugacy Class Invariants: $\mathcal{IW}(\varphi)$, $\lambda(\varphi)$

Idea in analogy with Nielsen-Thurston setting:

- Iterate loops (*in graph*) \rightsquigarrow Lamination leaves

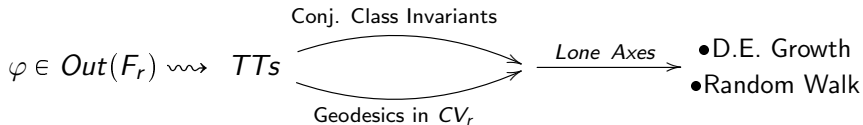
$a \xrightarrow{\varphi} \text{abbab} \xrightarrow{\varphi} \text{abbabbababbabbababbababbabbababbababbab}$

- $\mathcal{IW}(\varphi)$: Record at vertices how lamination leaves enter & leave



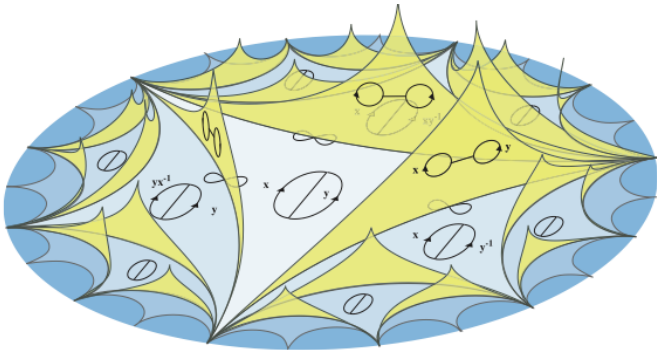
- $\lambda(\varphi)$: Record how lamination leaves stretched by φ (equivalently how curves asymptotically stretched)

Strategy/Outline:



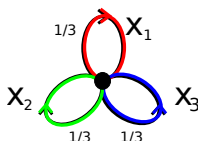
$Out(F_r)$ & the Deformation Space of Metric Graphs

$Out(F_r)$ is the isometry group for a deformation space of metric graphs,
Culler-Vogtmann Outer Space CV_r



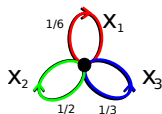
Outer Space CV_r

Points in CV_r are *marked, metric, graphs*:

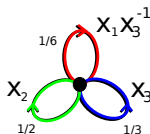


Most basic point:

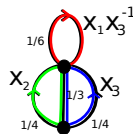
Can additionally:



Change lengths
on edges



Apply
automorphism



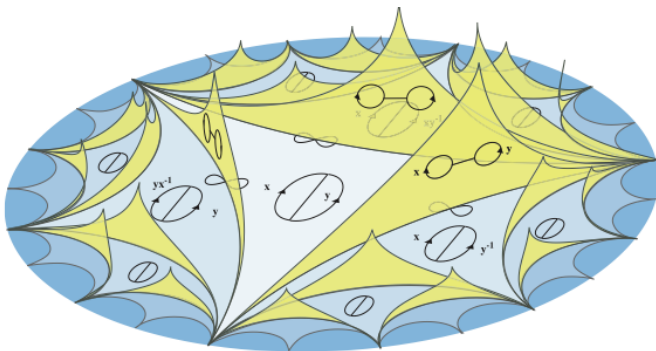
“Blow up”
vertex

Outer Space in Rank 2 (CV_2)

The graphs Γ with $\pi_1(\Gamma) = F_2$:

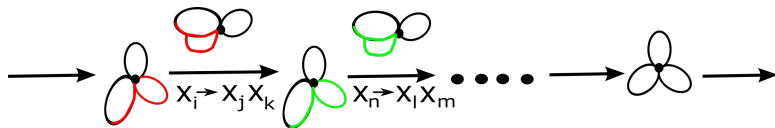


CV_2 :



TT Maps $g \rightsquigarrow$ Geodesics in CV_r

- Stallings decomposes g as a sequence of “folds”
- Skora made process continuous \rightsquigarrow geodesic in CV_r

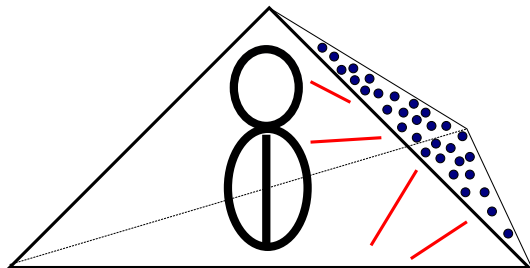


Complicated Geodesics Exist: Dense Geodesics

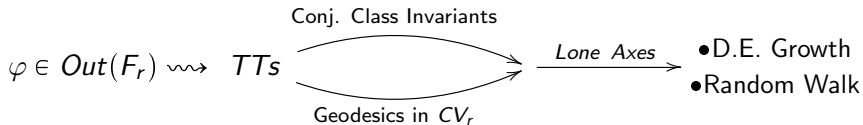
Theorem (Main Theorem I; Algom-Kfir, Pfaff)

For each $r \geq 2$,

\exists a geodesic fold ray in CV_r w/ dense image under
 $CV_r \xrightarrow{\text{quotient}} CV_r/Out(F_r).$



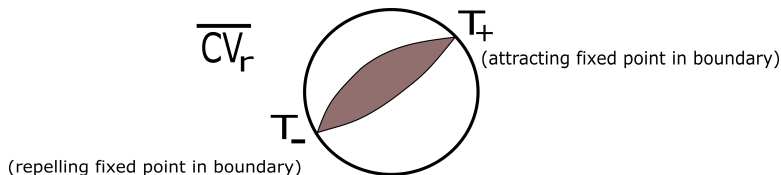
Strategy/Outline:



Surprising Connection: Lone Axes in Outer Space

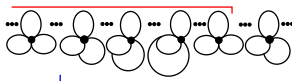
Definition (Axis bundle \mathcal{A}_φ for nice $\varphi \in \text{Out}(F_r)$ (Handel, Mosher))

$$\mathcal{A}_\varphi = \overline{\{\text{Fold line geodesics for tt reps of } \varphi^k \text{ with } k > 0\}} \subset \text{CV}_r$$



Theorem (Main Theorem II; Mosher, Pfaff)

(Algorithmically checkable) $\mathcal{IW}(\varphi)$ condition for when \mathcal{A}_φ a “lone axis”

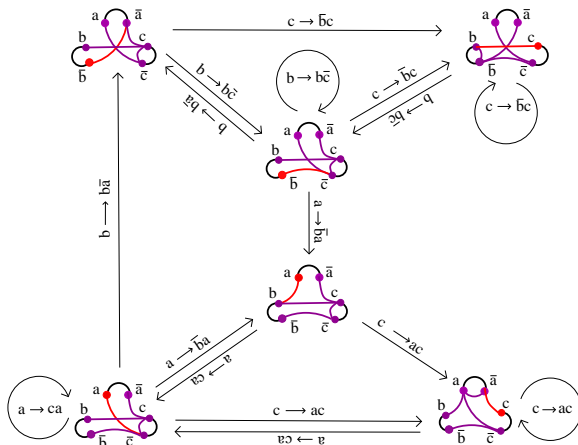


- Exist (Pfaff), many (Kapovich-Pfaff), different kinds (Coulbois-Lustig)

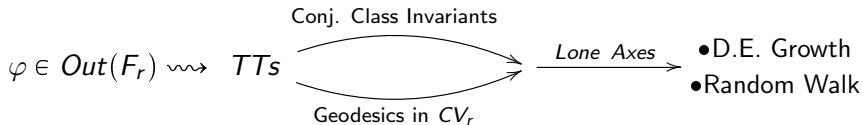
Lone Axes are Beautiful

When additionally $\mathcal{IW}(\varphi)$ connected:

“Lone Axes” give infinite paths in the tt automata of my thesis



Strategy/Outline:



Double Exponential Growth

- [Margulis, '69, '70] In hyp. manifold # of closed curves of bdd lngth grows exponentially w. the lngth bound.
- [Eskin, Mirzakhani, '11] In $\mathcal{T}(S)/MCG(S)$, # of closed curves of bdd lngth grows exponentially w. the lngth bound.
- $\mathfrak{N}_r(R) := \#\{[\varphi] \mid \varphi \text{ f.i., } \log(\lambda(\varphi)) < R\}$

Theorem (Main Theorem IV; I. Kapovich, Pfaff)

For $r \geq 3$, \exists constants $a > 1, b > 1, c > 1, M$ s.t. $\forall R > M$:

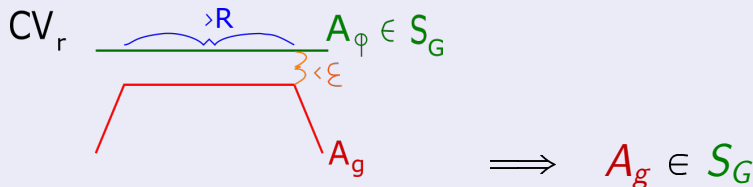
$$c^{e^R} \leq \mathfrak{N}_r(R) \leq a^{b^R}$$

- Corollary: # of closed curves grows double exponentially!!!

Test for generic behavior (Stable Strata)

Theorem (Main Theorem III; Algom-Kfir, I. Kapovich, Pfaff)

- Stratify geodesics by $\mathcal{IW}(\varphi)$
- \exists lone axis “stable strata” S_G :



- The lies make this interesting!

Unhatched Egg: Random Walks

If you would like this slide, please contact Catherine Pfaff directly.

Extended Program: Dynamical properties of space of geodesics

- Dense geodesic ray, stable strata, and growth rate work all give hints of dynamical properties of spc of geodesics in CV_r
- What kind of dynamical theory can be built on spc of geodesics in CV_r & what does this tell us about $Out(F_r)$?

Broader Program: Deformation Spaces

- How much of Nielsen-Thurston story holds for the space of convex projective structures on a surface?
(Work w. Cooper on associating foliations to hyp metrics is bridge)
- Billera, Holmes, & Vogtmann define & study geometry of spc of phylogenetic trees.
Can constructing other deformation spaces help to understand other biological or technological settings?

Thank you!