

# Week #11 : Complex Eigenvalues, Applications of Systems

## Goals:

- Solutions for the Complex Eigenvalue Case
- Further Applications of Systems of DEs

# Complex Eigenvalue Case

First-order homogeneous systems have the standard form:

$$\boxed{\vec{x}' = A\vec{x}} \rightarrow \begin{array}{l} \text{eigenvalues} \rightarrow \\ \text{charact'c poly' } \end{array}$$

What happens when the coefficient matrix  $A$  has non-real eigenvalues?

(Note: for the remainder of the course, we will use the more traditional " $i$ " instead of  $\sqrt{-1}$ ; it will simplify some of the notation.)

**Proposition.** If the real matrix  $A$  has complex conjugate eigenvalues  $\alpha \pm \beta i$  with corresponding eigenvectors  $\vec{a} \pm \vec{b} i$ , then two linearly independent real vector solutions to  $\vec{x}' = A\vec{x}$  are

$\alpha = \text{real part}$   
 $\beta = \text{imaginary}$

$x_1 = e^{\alpha t} \underbrace{[\cos(\beta t)\vec{a} - \sin(\beta t)\vec{b}]}_{\text{new}}$       and  $e^{\alpha t} \underbrace{[\sin(\beta t)\vec{a} + \cos(\beta t)\vec{b}]}_{\text{new}}$

earlier:  $e^{\alpha t} \cos(\beta t)$        $e^{\alpha t} \sin(\beta t)$

**Problem.** Solve  $\vec{x}'(t) = A\vec{x}(t)$  where  $A := \begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix}$ . } assumption

Find eigenvalues of  $A$ : set  $\det(A - rI) = 0$   $\vec{x}(t) = e^{rt} \vec{v}$

$$\begin{vmatrix} -1-r & 2 \\ -1 & -3-r \end{vmatrix} = (-1-r)(-3-r) - (-1)(2)$$

$$= 3 + 4r + r^2 + 2$$

$$= \underbrace{r^2 + 4r + 5}_{\text{charac'ic poly'le}} = 0$$

quadratic formula

$$r = \frac{-4 \pm \sqrt{4^2 - 4(5)}}{2}$$

$$= -2 \pm \frac{1}{2} \sqrt{-4}$$

↑  
complex roots

$$= -2 \pm \sqrt{-1}$$

$$\boxed{r = -2 \pm \sqrt{-1}i}$$

$\alpha$                    $\beta$

Aside:

$e^{(-2+i)t}$  is a sol'n

but not all real sol'n

$$r = -2 \pm 1i \quad (\text{two eigenvalues})$$

find eigenvector for

$$r = \alpha + \beta i$$

$$\text{Solve } (A - rI)\vec{x} = \vec{0}$$

$$\begin{bmatrix} -1 - (-2 + i) & 2 \\ -1 & -3 - (-2 + i) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \vec{0}$$

$$\hookrightarrow \begin{bmatrix} 1 - i & 2 \\ -1 & -1 - i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow$$

not obvious, but I have  
that one row is redundant.

$$\vec{x}_1(t) = e^{\alpha t} \begin{bmatrix} \cos(\beta t)\vec{a} - \sin(\beta t)\vec{b} \\ \sin(\beta t)\vec{a} + \cos(\beta t)\vec{b} \end{bmatrix}$$

$$\vec{x}_2(t) = e^{\alpha t} \begin{bmatrix} \sin(\beta t)\vec{a} + \cos(\beta t)\vec{b} \\ \cos(\beta t)\vec{a} - \sin(\beta t)\vec{b} \end{bmatrix}$$

$$\vec{x}'(t) = \begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix} \vec{x}(t)$$

(vector for  $r = \alpha - \beta i$  will be  
the complex conjugate of this)

Treat 'i' as constant, except  $i^2 = -1$

$$\vec{x} = \begin{bmatrix} 1 \\ -1/2 + 1/2 i \end{bmatrix}$$

$$(1 - i)x_1 + 2x_2 = 0$$

$$\uparrow \\ \text{let } x_1 = 1$$

$$2x_2 = -1 + i$$

$$\underline{\underline{|x_2 = \frac{1}{2}(-1 + i)|}}$$

$$\vec{r}_2 = \begin{bmatrix} 1 \\ -\frac{1}{2} + \frac{1}{2}i \end{bmatrix} \times 2 = \begin{bmatrix} 2 \\ -1 + i \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ -1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} i$$

$$\text{for } r = -2 + i$$

$$\alpha = -2$$

$$\beta = +1$$

From matrix theory,

$$\vec{r}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} i \text{ is eigenv. for } r_2 = -2 - i$$

Use sol'n formula to build the general solution  
same form

$$\vec{x}(t) = c_1 e^{-2t} \left[ \cos(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \sin(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right] + c_2 e^{-2t} \left[ \sin(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} + \cos(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

$$\vec{x}_1(t) = e^{\alpha t} \left[ \cos(\beta t) \vec{a} - \sin(\beta t) \vec{b} \right]$$

$$\vec{x}_2(t) = e^{\alpha t} \left[ \sin(\beta t) \vec{a} + \cos(\beta t) \vec{b} \right]$$

$$\vec{x}'(t) = \begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix} \vec{x}(t)$$

$$\text{DE: } \underbrace{\vec{x}'(t)}_{\text{LHS}} = \underbrace{\begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix}}_{\text{RHS}} \vec{x}(t)$$

**Problem.** Verify your solution is correct.

$$x_1 = e^{-2t} \left[ \cos(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \sin(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

$$\text{LHS} = -2e^{-2t} \left[ \cos(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \sin(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right] + e^{-2t} \left[ -\sin(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \cos(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

$$= e^{-2t} \left[ \cos(t) \begin{bmatrix} -4+0 \\ 2-1 \end{bmatrix} + \sin(t) \begin{bmatrix} 0-2 \\ 2+1 \end{bmatrix} \right]$$

$$\begin{bmatrix} -4 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

LHS = RHS

$$\text{RHS} = \begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix} \left( e^{-2t} \right) \left[ \cos(t) \begin{bmatrix} 2 \\ -1 \end{bmatrix} - \sin(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

$$= \left( e^{-2t} \right) \left[ \cos(t) \begin{bmatrix} -4 \\ 1 \end{bmatrix} + \sin(t) \begin{bmatrix} -2 \\ 3 \end{bmatrix} \right]$$



$x_1$  is a solution.

**Problem.** Solve  $\vec{x}'(t) = A\vec{x}(t)$  where

$$A := \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{bmatrix}$$

$$\vec{x}(t) = e^{rt} \vec{z}$$

$$r \vec{z} = A \vec{z}$$

Find eigenvalues

$$\det(A - rI) = 0$$

$$\begin{vmatrix} 1-r & 0 & 0 & | & 1-r & 0 \\ 2 & 1-r & -2 & | & 2 & -1-r \\ 3 & 2 & 1 & | & 3 & 2 \end{vmatrix} = (1-r)(1-r)(1-r) + 0 + 0 - [0 + (2)(-2)(1-r) + 0]$$

characteristic poly<sup>le</sup>

$$= (1 - 2r + r^2)(1-r) + 4(1-r)$$

$$= -r^3 + 2r^2 - r + r^2 - 2r + 1 + 4 - 4r$$

$$= -r^3 + 3r^2 - 7r + 5 = 0$$

Guess:  $r=1$ :  $-1 + 3 - 7 + 5 = 0$

so  $(r-1)$  is a factor

$$(r-1)(-r^2 + 2r - 5) = 0$$

$$(r-1)(r^2 - 2r + 5) = 0$$

quad  $\hookrightarrow$   $r = 1 \pm 2i$   
for roots complex pair

Let  $r_1 = 1$  (real distinct eigenvalue)

Find eigenvector

$$(A - rI)\vec{x} = \vec{0}$$

$$\begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & -2 \\ 3 & 2 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \vec{0}$$

(3)

$$3x_1 + 2x_2 = 0$$

$$x_1 = -\frac{2}{3}x_2$$

$$\boxed{x_1 = -2}$$

pick  $\boxed{x_2 = 3}$

$$(2) \quad 2x_1 - 2x_3 = 0$$

$$x_3 = x_1 = -2$$

so  $\vec{x}_1 = \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} \rightarrow$  one sol'n

$$x_1(t) = e^{1 \cdot t} \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix}$$

$$\begin{aligned} \vec{x}_1(t) &= e^{\alpha t} \begin{bmatrix} \cos(\beta t)\vec{a} - \sin(\beta t)\vec{b} \\ \sin(\beta t)\vec{a} + \cos(\beta t)\vec{b} \end{bmatrix} \\ \vec{x}_2(t) &= e^{\alpha t} \begin{bmatrix} \sin(\beta t)\vec{a} + \cos(\beta t)\vec{b} \\ \cos(\beta t)\vec{a} - \sin(\beta t)\vec{b} \end{bmatrix} \\ \vec{x}'(t) &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{bmatrix} \vec{x}(t) \end{aligned}$$



$$r_{2,3} = 1 \pm 2i$$

Find eigenvector for  $r_2 = 1 + 2i$

$$(A - rI) \vec{v} = \vec{0}$$

$$\begin{bmatrix} 1 - (1 + 2i) & 0 & 0 \\ 2 & 1 - (1 + 2i) & -2 \\ 3 & 2 & 1 - (1 + 2i) \end{bmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \vec{0}$$

$$\textcircled{1} \begin{bmatrix} -2i & 0 & 0 \\ 2 & -2i & -2 \\ 3 & 2 & -2i \end{bmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\textcircled{1} -2i v_1 = 0 \quad \boxed{v_1 = 0}$$

$$\textcircled{2} -2i v_2 - 2 v_3 = 0$$

$$\text{let } v_2 = 1$$

$$-2 v_3 = 2i$$

$$v_3 = -i$$

$$\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ -i \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{x}_1(t) = e^{\alpha t} \begin{bmatrix} \cos(\beta t) \vec{a} - \sin(\beta t) \vec{b} \end{bmatrix}$$

$$\vec{x}_2(t) = e^{\alpha t} \begin{bmatrix} \sin(\beta t) \vec{a} + \cos(\beta t) \vec{b} \end{bmatrix}$$

$$\vec{x}'(t) = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{bmatrix} \vec{x}(t)$$

$$\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}, \quad \lambda_2 = 1 + 2i$$

$\alpha$        $\beta$

$$\begin{aligned} \vec{x}_1(t) &= e^{\alpha t} \begin{bmatrix} \cos(\beta t) \vec{a} - \sin(\beta t) \vec{b} \\ \sin(\beta t) \vec{a} + \cos(\beta t) \vec{b} \end{bmatrix} \\ \vec{x}_2(t) &= e^{\alpha t} \begin{bmatrix} \cos(\beta t) \vec{a} - \sin(\beta t) \vec{b} \\ \sin(\beta t) \vec{a} + \cos(\beta t) \vec{b} \end{bmatrix} \\ \vec{x}'(t) &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{bmatrix} \vec{x}(t) \end{aligned}$$

$$\begin{aligned} \text{so } \vec{x}_2(t) &= e^t \left[ \cos(2t) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} - \sin(2t) \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} \right] \\ \text{and } \vec{x}_3 &= e^t \left[ \sin(2t) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \cos(2t) \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} \right] \end{aligned}$$

General sol'n = lin'ar comb'n of  $x_1$  (real  $r$ )  
 $x_2, x_3$  (complex  $r$  pair)

$$x(t) = c_1 e^t \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} + c_2 x_2(t) + c_3 x_3(t)$$

$$\begin{aligned}\vec{x}_1(t) &= e^{\alpha t} \left[ \cos(\beta t)\vec{a} - \sin(\beta t)\vec{b} \right] \\ \vec{x}_2(t) &= e^{\alpha t} \left[ \sin(\beta t)\vec{a} + \cos(\beta t)\vec{b} \right] \\ \vec{x}'(t) &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{bmatrix} \vec{x}(t)\end{aligned}$$

## Non-Homogeneous Systems

We now expand our solution approach to include non-homogeneous first-order systems:

$$\boxed{\vec{x}'(t) = A\vec{x}(t)} + \boxed{\vec{f}(t)}$$

→ homog's      ↙

To solve this non-homogeneous form, we will use the same method as we used for higher-order systems, called the method of undetermined coefficients.

**Problem.** What are the steps in this method?

- finding diff'l family of  $\vec{f}(t)$

↳ set of functions  $\{f_1, f_2, \dots, f_m\}$

↑ scalars

- build proposed solution

$$\vec{x}_{NH} = f_1(t) \vec{u}_1 + f_2(t) u_2 + f_3(t) u_3 + \dots + f_m(t) \vec{u}_m$$

↑      ↑      ↑      ↑      ↑  
are undetermined coeffs

**Problem.** Consider the DE system

$$\boxed{\vec{x}' = \underbrace{\begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix}}_A \vec{x}} + \begin{bmatrix} 10e^{2t} \\ 0 \end{bmatrix}$$

non-homog's  
↓  
corresp'd homog's DE.

The eigenvalues and corresponding eigenvectors for the matrix  $A$  in the system above are

$$\lambda_1 = 5, \vec{v}_1 = \begin{bmatrix} 7 \\ 1 \end{bmatrix} \qquad \lambda_2 = -1, \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Find the general solution to the *homogeneous* part of the system.

$$\vec{x}_c = c_1 e^{5t} \begin{bmatrix} 7 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\vec{x}' = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix} \vec{x} + \begin{bmatrix} 10e^{2t} \\ 0 \end{bmatrix}$$

Diff'l family  $\{e^{2t}\}$

Assume a form for the *particular* solution for the *non-homogeneous* form.

Assume  $\vec{x}_{part} = e^{2t} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$

SUB in  $\vec{x}_{part}$ , solve for  $u_1, u_2$

$$2e^{2t} \vec{u} = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix} e^{2t} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + e^{2t} \begin{bmatrix} 10 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2u_1 \\ 2u_2 \end{bmatrix} = \begin{bmatrix} 6u_1 & -7u_2 \\ u_1 & -2u_2 \end{bmatrix} + \begin{bmatrix} 10 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4u_1 + 7u_2 \\ -u_1 + 4u_2 \end{bmatrix} = \begin{bmatrix} 10 \\ 0 \end{bmatrix} \quad \textcircled{1} \quad \begin{bmatrix} -4 & 7 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 10 \\ 0 \end{bmatrix}$$

$-4 \times \textcircled{2}$

$$\begin{bmatrix} -1 & 4 \\ 0 & -9 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 10 \end{bmatrix}$$

$$-9u_2 = 10$$

$$\boxed{u_2 = \frac{-10}{9} \approx -1.11}$$

$$\vec{x}' = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix} \vec{x} + \begin{bmatrix} 10e^{2t} \\ 0 \end{bmatrix}$$

Find the constants/coefficients in the particular solution.

$$u_2 = \frac{-10}{9} \rightarrow \begin{bmatrix} -1 & 4 \\ 0 & -9 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 10 \end{bmatrix}$$

$$-u_1 + 4u_2 = 0$$

$$u_1 = 4u_2 = -\frac{40}{9}$$

so

$$\vec{x}_{\#} = e^{2t} \begin{bmatrix} -\frac{40}{9} \\ -\frac{10}{9} \end{bmatrix} = e^{2t} \cdot \frac{10}{9} \begin{bmatrix} -4 \\ -1 \end{bmatrix}$$

$$\vec{x}(t) = \begin{bmatrix} \vec{x}_c \\ \vec{x}_{\#} \end{bmatrix}$$

Write out the form for the general solution to

$$\vec{x}' = \underbrace{\begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix}}_A \vec{x} + \underbrace{\begin{bmatrix} 2 \\ -5t \end{bmatrix}}_{\text{diff'l family } \{t, 1\}}$$

in  $\vec{x} = \vec{x}_c + \vec{x}_{NH}$  form.

experiment w/  $\vec{f}(t)$ ,  
non-homog's part

$$\vec{x}(t) = \underbrace{c_1 e^{5t} \begin{bmatrix} 7 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\vec{x}_c} + t \vec{u}_1 + 1 \cdot \vec{u}_2$$

$\uparrow$                        $\uparrow$                        $\uparrow$   
 function / scalar    consts                     

$\underbrace{\hspace{15em}}_{\vec{x}_{NH}}$



Write out the form for the general solution to

$$\vec{x}' = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix} \vec{x} + \begin{bmatrix} \sin(t) \\ \sin(2t) \end{bmatrix}$$

diff'le family  
 $\{ \sin(t), \cos(t), \sin(2t), \cos(2t) \}$

in  $\vec{x} = \vec{x}_c + \vec{x}_{NH}$  form.

$$\vec{x}(t) = \underbrace{c_1 e^{5t} \begin{bmatrix} 7 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\vec{x}_c} + \underbrace{\sin(t) \vec{u}_1 + \cos(t) \vec{u}_2 + \sin(2t) \vec{u}_3 + \cos(2t) \vec{u}_4}_{\vec{x}_{NH}}$$

Write out the form for the general solution to

$$\vec{x}' = \begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ 10e^{-t} \end{bmatrix}$$

→ diff'l family  
 $\{e^{-t}\}$

in  $\vec{x} = \vec{x}_c + \vec{x}_{NH}$  form.

$$\vec{x} = \underbrace{c_1 e^{5t} \begin{bmatrix} 7 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\vec{x}_c} + e^{-t} \vec{u}_1$$

same!

Overlap b/w

$\vec{x}_c$  and  $\vec{x}_{NH}$  sol'ns.

⇒ requires special handling.

## Repeated Solutions in $\vec{x}_c$ and $\vec{x}_{NH}$

If a member of the differential family needed for  $\vec{x}_{NH}$ , say  $f(t)$ , is already present in  $\vec{x}_c$ , then you must include

$$\underline{t \cdot f(t)}$$

and all lower multiples of  $t$  in the assumed form for  $\vec{x}_{NH}$ .

↳ new for systems

**Problem.** Write the form of the general solution to

$$\vec{x}' = \underbrace{\begin{bmatrix} 6 & -7 \\ 1 & -2 \end{bmatrix}}_A \vec{x} + \begin{bmatrix} 0 \\ 10e^{-t} \end{bmatrix}$$

non-homog's  
diff'l family

in  $\vec{x} = \vec{x}_c + \vec{x}_{NH}$  form. Recall: for this  $A$  matrix,

$$\lambda_1 = 5, \vec{v}_1 = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -1, \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \xrightarrow{\vec{x}_{NH}}$$

$$\vec{x} = \underbrace{c_1 e^{5t} \begin{bmatrix} 7 \\ 1 \end{bmatrix} + c_2 e^{-1t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\vec{x}_c} + \underbrace{t e^{-t} \vec{u}_1 + e^{-t} \vec{u}_2}_{\vec{x}_{NH}}$$

new func b/c of overlap w/ $\vec{x}_c$

↑  
vec const's

Find  $\vec{u}_1, \vec{u}_2$  by subbing in  $\vec{x}_{NH}$  into DE

**Problem.** Write out the form for the general solution to

$$\vec{x}' = \underbrace{\begin{bmatrix} 0 & 1 \\ -4 & 0 \end{bmatrix}}_A \vec{x} + \overset{F_{ext}}{\begin{bmatrix} \sin(bt) \\ 0 \end{bmatrix}} \quad \begin{array}{l} \text{diff'l family} \\ \{ \sin(bt), \cos(bt) \} \end{array}$$

in  $\vec{x} = \vec{x}_c + \vec{x}_{NH}$  form.

You are given that the eigenvalues of  $A$  are  $\lambda_{1,2} = 0 \pm 2i$  and

$$\vec{v}_{1,2} = \begin{bmatrix} 0 \\ 2 \end{bmatrix} \pm \begin{bmatrix} 1 \\ 0 \end{bmatrix} i \text{ so } \quad \text{eigen vectors}$$

$$\vec{x}_c = c_1 e^{0t} \left( \begin{bmatrix} 0 \\ 2 \end{bmatrix} \cos(2t) - \begin{bmatrix} 1 \\ 0 \end{bmatrix} \sin(2t) \right) + c_2 e^{0t} \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cos(2t) + \begin{bmatrix} 0 \\ 2 \end{bmatrix} \sin(2t) \right)$$

pure oscillation w/ const amplitude

$$\vec{x}_{NH} = \sin(bt) \vec{u}_1 + \cos(bt) \vec{u}_2 \quad \text{if } b \neq 2$$

if  $b=2$ ,  $\sin(2t)/\cos(2t)$  in  $\vec{x}_c \Rightarrow$   
 have to boost by 't':  $\vec{x}_{NH} = t \cdot \sin(2t) \vec{u}_1 + t \cos(2t) \vec{u}_2 + \sin(2t) \vec{u}_3 + \cos(2t) \vec{u}_4$   
 = amplitudes grow linearly

Explain the conditions for resonance and beats in a first-order DE system.

non-homog's part has

→  $\sin / \cos$  w/ exactly the same

Freq as  $\vec{x}_c$  → resonance

$$\begin{matrix} t \sin / t \cos \\ \uparrow \quad \uparrow \\ \vec{x}_{NH} \end{matrix}$$

→  $\sin / \cos$  w/ close to same freq  
as in  $\vec{x}_c$

↳ beats / large  
amplitude response

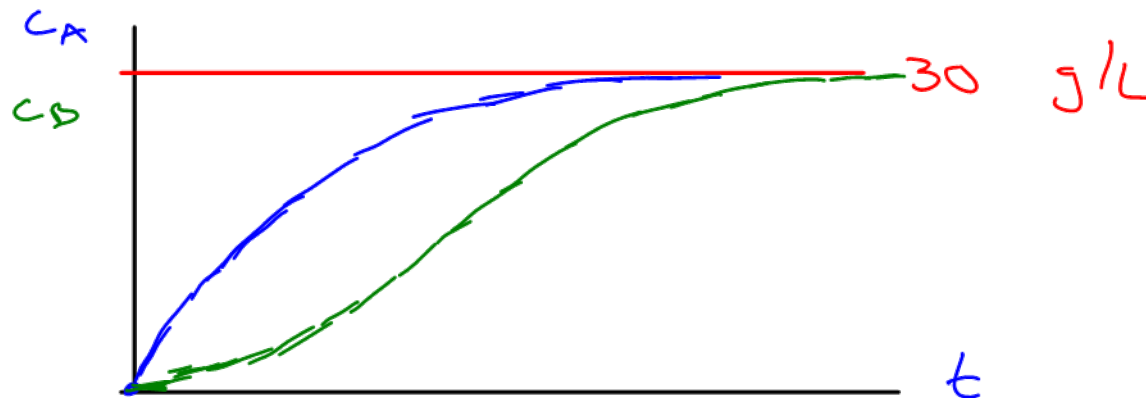
## Modelling Systems - Interconnected Tanks

Consider the tanks shown below, which show water flowing between the tanks, and the concentration of a salt solution coming in. Within each tank, the water/salt solution is kept well mixed.

water  
salt →  
dissolved

volumes of  
water are  
constant.

**Problem.** If both tanks start with no salt, sketch what you expect will happen to the concentration within each tank over time.



**Problem.** Create a system of differential equations that dictate how the two tank concentrations will evolve over time.

$$c = \frac{S}{V}$$

Study first  $S_A =$  mass of salt in tank A (g)

$$\left(\frac{\text{g}}{\text{min}}\right) \frac{dS_A}{dt} = \left(\text{rate of salt in}\right) - \left(\text{rate salt going out}\right)$$



$$= \left(5 \frac{\text{L}}{\text{min}}\right) \left(30 \frac{\text{g}}{\text{L}}\right) - \left(5 \frac{\text{L}}{\text{min}}\right) \left(\frac{S_A}{V_A} \frac{\text{g}}{\text{L}}\right)$$

$$\frac{dS_A}{dt} = 150 \frac{\text{g}}{\text{min}} - 5 \frac{S_A}{V_A} \frac{\text{g}}{\text{min}}$$

To convert to

$$C_A = \frac{S_A}{V_A}$$

const  $\rightarrow V_A \frac{d}{dt}$

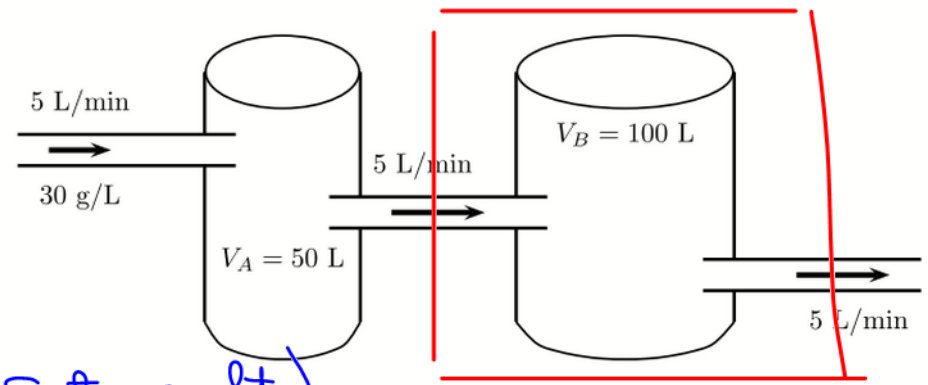
$$\frac{dC_A}{dt} = \frac{1}{V_A} \left( 150 - 5 \frac{S_A}{V_A} C_A \right)$$

← hang's

non-hang's

$$\frac{dC_A}{dt} = \frac{1}{V_A} \frac{dS_A}{dt}$$





$$\frac{dc_B}{dt} = \frac{1}{V_B} \left( \begin{array}{l} \text{rate salt} \\ \text{in } \text{g/min} \end{array} - \begin{array}{l} \text{rate salt} \\ \text{out } \text{g/min} \end{array} \right)$$

$$\frac{dc_B}{dt} = \frac{1}{V_B} \left( 5 \frac{\text{L}}{\text{min}} \cdot c_A \frac{\text{g}}{\text{L}} - 5 \frac{\text{L}}{\text{min}} c_B \right) \frac{\text{g}}{\text{L}}$$

$$\frac{dc_B}{dt} = \frac{1}{V_B} (5c_A - 5c_B)$$

matrix form

$$\underbrace{\frac{d}{dt} \begin{bmatrix} c_A \\ c_B \end{bmatrix}}_{\vec{x}'(t)} = \begin{matrix} A \\ \begin{bmatrix} -5/V_A & 0 \\ 5/V_B & -5/V_B \end{bmatrix} \end{matrix} \underbrace{\begin{bmatrix} c_A \\ c_B \end{bmatrix}}_{\vec{x}} + \begin{matrix} \vec{f}(t) \\ \begin{bmatrix} 150/V_A \\ 0 \end{bmatrix} \end{matrix}$$



**Problem.** Predict the exact salt concentrations over time by solving the system of linear differential equations

$$\frac{d}{dt} \underbrace{\begin{bmatrix} c_A \\ c_B \end{bmatrix}}_{\vec{x}(t)} = \underbrace{\begin{bmatrix} -\frac{1}{10} & 0 \\ \frac{1}{20} & -\frac{1}{20} \end{bmatrix}}_A \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

Goal:  $c_A = \dots$   
 $c_B = \dots$

find  $\vec{x}_c$

A has eigenvalues  $r_1 = -\frac{1}{10}$ ,  $r_2 = -\frac{1}{20}$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\vec{x}_c = c_1 e^{-t/10} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{-t/20} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$x_{N\#} = 10 \vec{u}$  sub into DE  
 $\vec{u}$  const

$$\frac{d}{dt} \begin{pmatrix} c_A \\ c_B \end{pmatrix} = \begin{bmatrix} -\frac{1}{10} & 0 \\ \frac{1}{20} & -\frac{1}{20} \end{bmatrix} \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$0 = -\frac{1}{10} c_A + 3 \rightarrow \boxed{c_A = 30}$$

$$0 = \frac{1}{20} c_A - \frac{1}{20} c_B \rightarrow \boxed{c_B = c_A = 30}$$

diff'l family  
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$$\vec{x}_{N\#} = \begin{bmatrix} 30 \\ 30 \end{bmatrix} \text{ g/L}$$

$$\begin{bmatrix} c_A \\ c_B \end{bmatrix} = c_1 e^{-t/10} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{-t/20} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix} \rightarrow \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

$\rightarrow 0$  as  $t \rightarrow \infty$

$$c_A(0) = 0$$

Solve for  $c_1, c_2$

$$c_B(0) = 0$$

$$\begin{bmatrix} c_A \\ c_B \end{bmatrix} = c_1 e^{-t/\tau_{10}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{-t/\tau_{20}} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

sub in  $c_A=0$   
 $c_B=0$   
 $t=0$

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

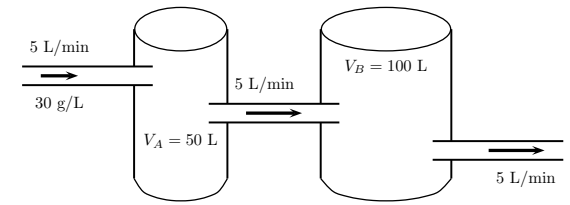
$$0 = c_1 + 30$$

$$\boxed{c_1 = -30}$$

$$0 = -c_1 + c_2 + 30$$

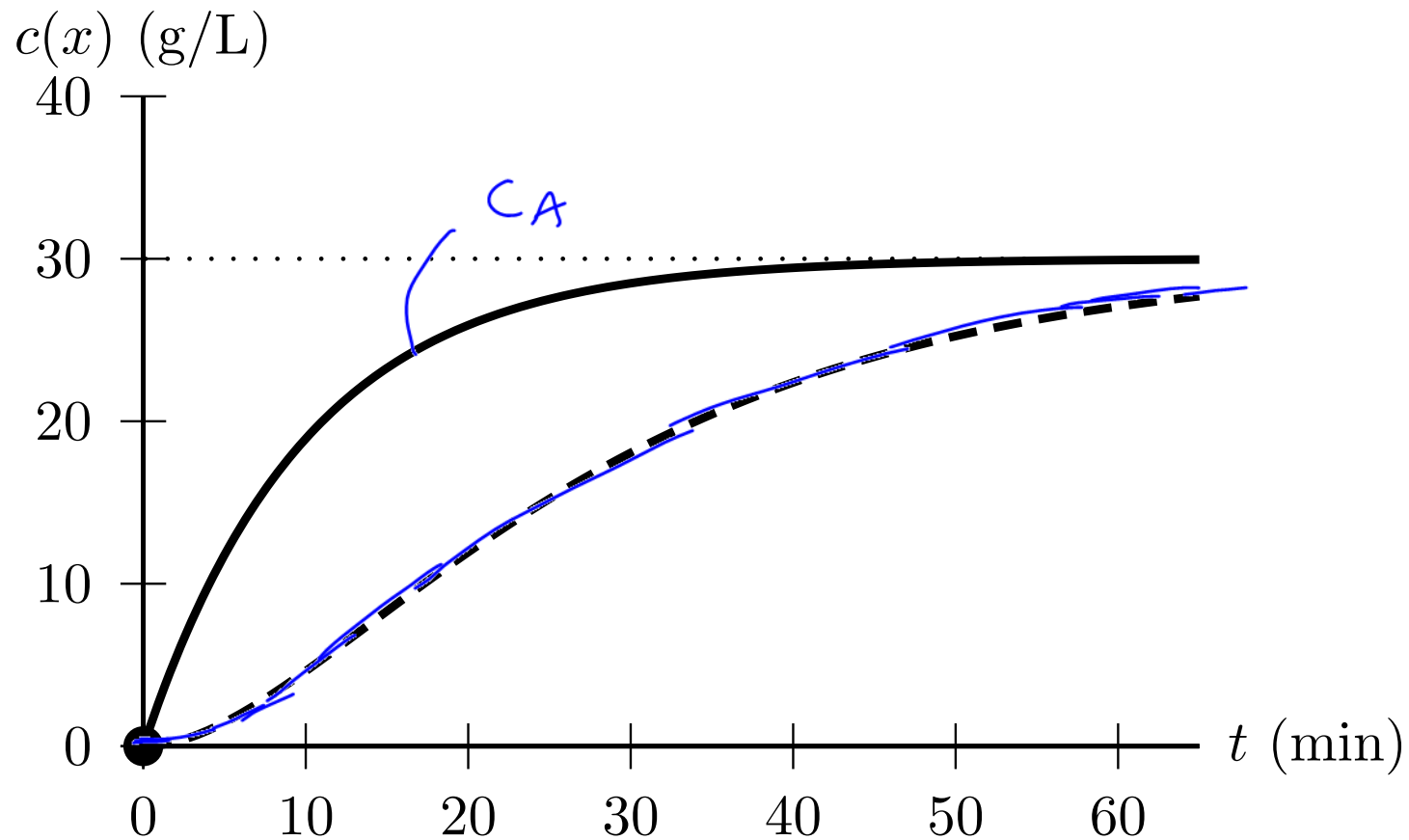
$$\boxed{c_2 = -30 + c_1 = -60}$$

$$\begin{bmatrix} c_A \\ c_B \end{bmatrix} = -30 e^{-t/\tau_{10}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} - 60 e^{-t/\tau_{20}} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

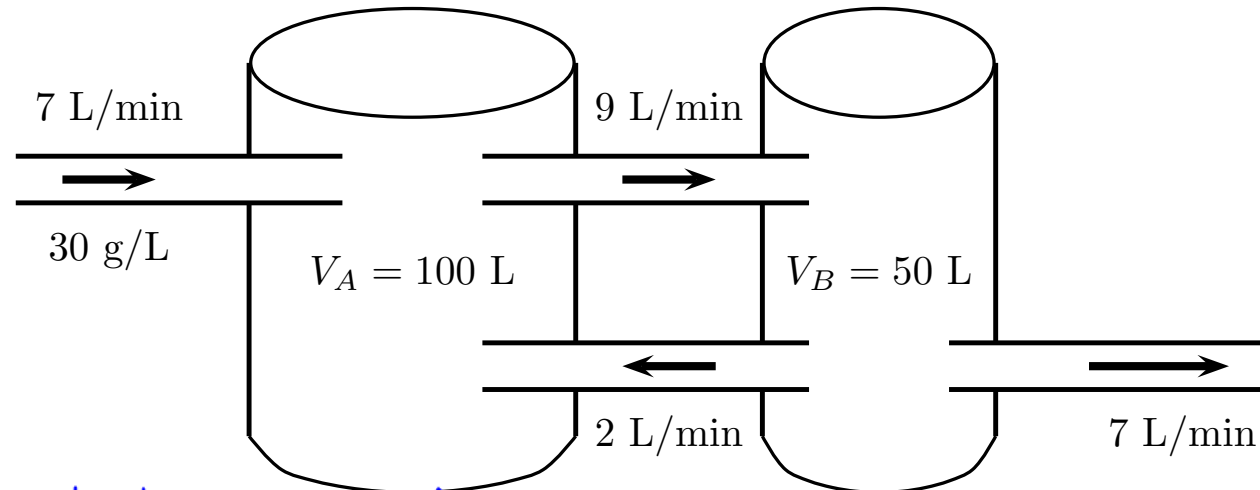


$$c_A = -30e^{-t/10} + 30;$$

$$c_B = 30e^{-t/10} - 60e^{-t/20} + 30$$



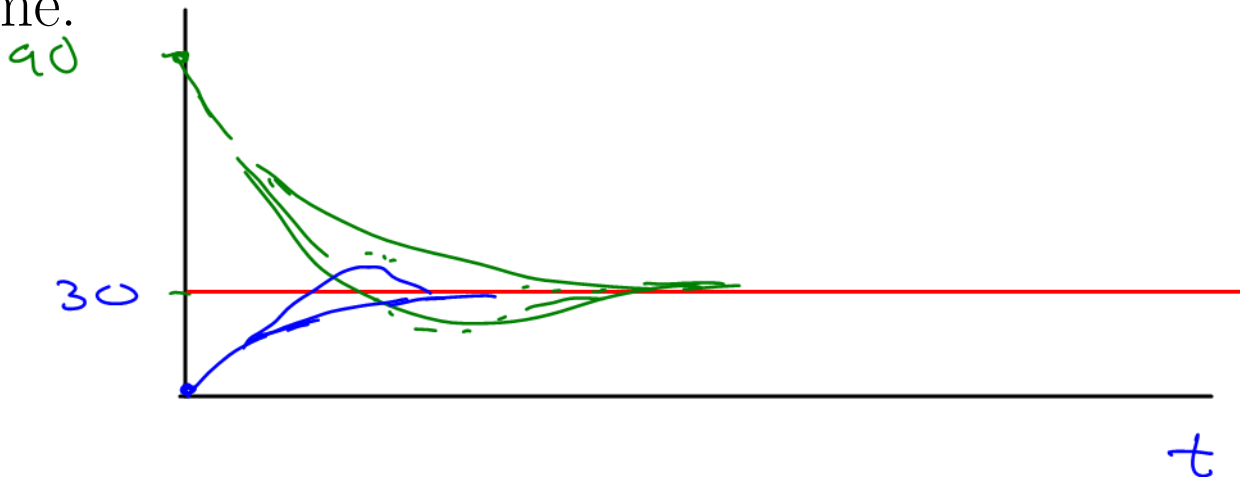
Consider the more complicated tank arrangement shown below.



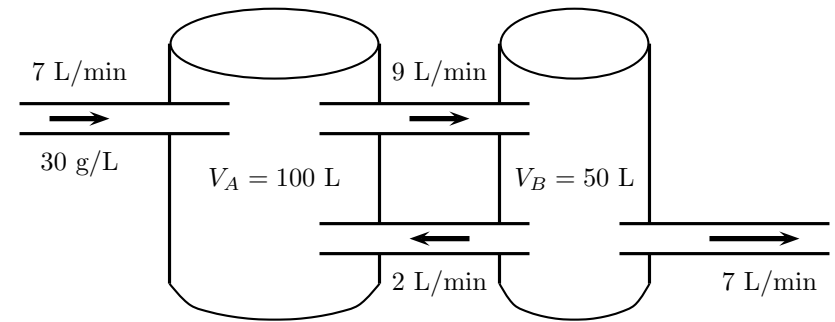
*starts w/ no salt*

*starts very concentrated*

**Problem.** Given that the initial concentrations are  $c_A(0) = 0$  g/L and  $c_B(0) = 90$  g/L, *← initial conditions* sketch what you would predict for the concentration in each tank over time.



**Problem.** Construct the differential equation for the salt concentration in each tank, and write it in matrix form.



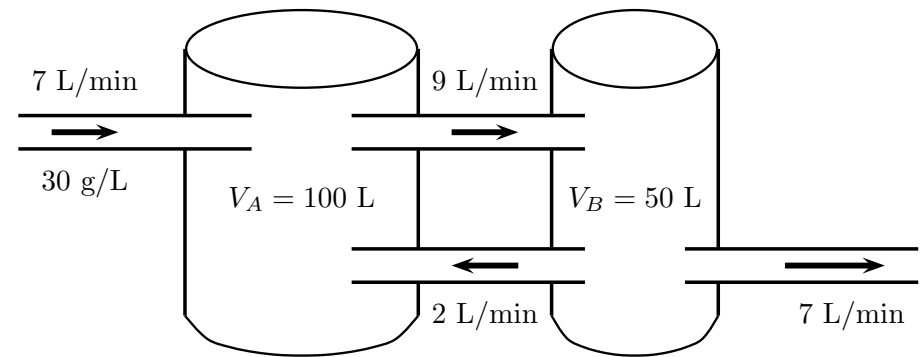
$$\frac{dc_A}{dt} = \frac{1}{V_A} \left( \begin{array}{l} \text{salt rate} \\ \text{in} \\ \text{g/min} \end{array} - \begin{array}{l} \text{salt rate} \\ \text{out} \\ \text{g/min} \end{array} \right)$$

$$\frac{dc_A}{dt} = \frac{1}{V_A 100} \left( \begin{array}{l} [7 \times 30 + 2 \cdot c_B] - (9 \cdot c_A) \\ \text{L/min} \times \text{g/L} \quad \text{L/min} \quad \text{g/L} \quad \text{L/min} \quad \text{g/L} \end{array} \right)$$

$$c_A' = -0.09 c_A + 0.02 c_B + 2.1$$

$$\frac{dc_B}{dt} = \frac{1}{V_B 50} \left( 9 \cdot c_A - (2+7) c_B \right)$$

$$c_B' = 0.18 c_A - 0.18 c_B$$



$$c_A' = -0.09 c_A + 0.02 c_B + 2.1$$

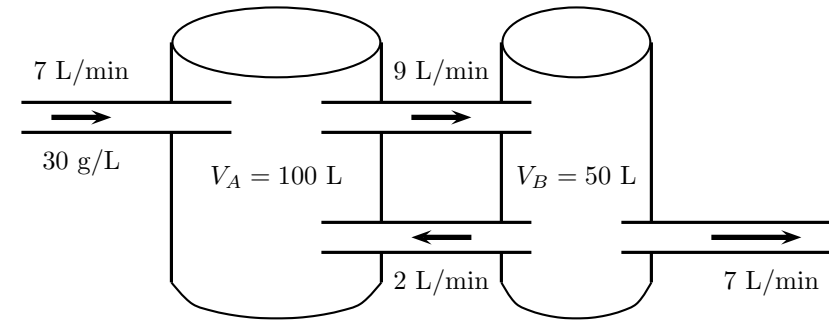
$$c_B' = 0.18 c_A - 0.18 c_B$$

$$\frac{d}{dt} \begin{bmatrix} c_A \\ c_B \end{bmatrix} = \begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix} \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 2.1 \\ 0 \end{bmatrix}$$



**Problem.** Predict the exact salt concentrations over time by solving the system of linear differential equations

$$\frac{d}{dt} \begin{bmatrix} c_A \\ c_B \end{bmatrix} = \underbrace{\begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix}}_A \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 2.1 \\ 0 \end{bmatrix}$$



↑ non-homog's

$\vec{x}_c$ : eigenvalues

$$\lambda_1 = -0.06$$

$$\lambda_2 = -0.21$$

eigenvectors

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

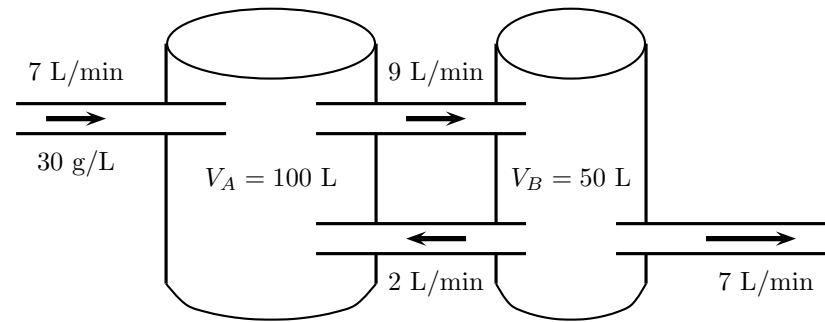
$$\vec{v}_2 = \begin{bmatrix} 1 \\ -6 \end{bmatrix}$$

$$\vec{x}_c = c_1 e^{-0.06t} \begin{bmatrix} 2 \\ 3 \end{bmatrix} + c_2 e^{-0.21t} \begin{bmatrix} 1 \\ -6 \end{bmatrix}$$

$\rightarrow 0$

$\rightarrow 0$

as  $t \rightarrow \infty$



Assume  $\vec{x}_{NH} = 1 \cdot \vec{u}$

Sub into DE

$$\frac{d}{dt} \begin{bmatrix} c_A \\ c_B \end{bmatrix} = \begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix} \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 2.1 \\ 0 \end{bmatrix}$$

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$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} \frac{d}{dt} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} 2.1 \\ 0 \end{bmatrix}$$

$$2x \begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} -2.1 \\ 0 \end{bmatrix}$$

$$-0.14 u_2 = -4.2$$

$$\vec{x}_{NH} = \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

$$\dots \begin{bmatrix} u_2 = 30 \\ u_1 = 30 \end{bmatrix} \text{ g/L}$$

---


$$c(t) = c_1 e^{-0.02t} \begin{bmatrix} 2 \\ 3 \end{bmatrix} + c_2 e^{-0.21t} \begin{bmatrix} 1 \\ -6 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

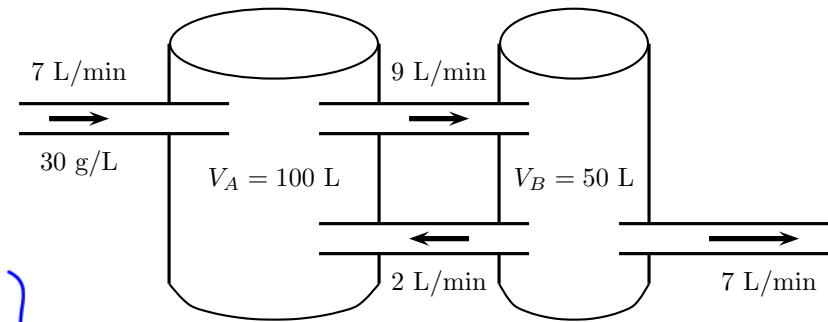
Match  $c_1, c_2$  to  $c_A(0) = 0$   
 $c_B(0) = 90$   
 $t=0$  in sol'n

$$\begin{bmatrix} 0 \\ 90 \end{bmatrix} = c_1 e^0 \begin{bmatrix} 2 \\ 3 \end{bmatrix} + c_2 e^0 \begin{bmatrix} 1 \\ -6 \end{bmatrix} + \begin{bmatrix} 30 \\ 30 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix} c_1 + \begin{bmatrix} 1 \\ -6 \end{bmatrix} c_2 = \begin{bmatrix} -30 \\ 60 \end{bmatrix}$$

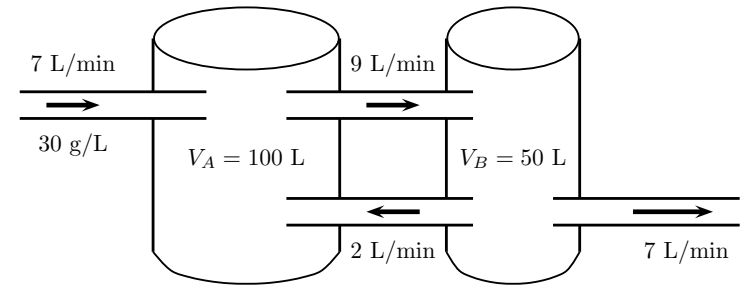
$$\begin{bmatrix} 2 & 1 \\ 3 & -6 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -30 \\ 60 \end{bmatrix} \quad \dots \quad c_1 = -8$$

$$c_2 = -14$$



$$\frac{d}{dt} \begin{bmatrix} c_A \\ c_B \end{bmatrix} = \begin{bmatrix} -0.09 & 0.02 \\ 0.18 & -0.18 \end{bmatrix} \begin{bmatrix} c_A \\ c_B \end{bmatrix} + \begin{bmatrix} 2.1 \\ 0 \end{bmatrix}$$

# Solution



*eigenvalues*

$$c_A = -8(2)e^{-0.06t} - 14(1)e^{-0.21t} + 30$$

$$c_B = -8(3)e^{-0.06t} - 14(-6)e^{-0.21t} + 30$$

