

1.

(a) Since  $A$  is the finite union  $A = \bigcup_{i=1}^n \{x_i\}$ , and since each  $\{x_i\}$  is closed,  $A$  is closed.

(b) Let  $x_i$  be a point  $A$ , and  $B = \mathcal{C}_A\{x_i\}$ . Then, by (a),  $B$  is closed in  $X$ , and so  $B \cap A = B$  is closed in  $A$ . Therefore each subset  $\{x_i\}$  is open in  $A$ , and so  $A$  has the discrete topology.

(c)

- For each  $i = 1, \dots, n$ ,  $U_i = U'_i \cap V_i$  is the intersection of two open sets, and hence open, while  $U_{n+1} = \bigcap_{i=1}^n W_i$  is the intersection of finitely many open sets and so also open.
- For each  $i = 1, \dots, n$ ,  $x_i \in U'_i$  and  $x_i \in V_i$ , so  $x_i \in U'_i \cap V_i$ . Similarly for  $i = n + 1$ ,  $x_{n+1} \in W_j$  for each  $j = 1, \dots, n$ , so  $x_{n+1} \in \bigcap_{j=1}^{n+1} W_j = U_{n+1}$ .
- If  $i, j \in \{1, \dots, n\}$  with  $i \neq j$  then

$$U_i \cap U_j = (U'_i \cap V_i) \cap (U'_j \cap V_j) = (U'_i \cap U'_j) \cap V_i \cap V_j = \emptyset \cap V_i \cap V_j = \emptyset,$$

since  $U'_i \cap U'_j = \emptyset$  if  $i \neq j$ .

On the other hand, if  $j = n + 1$  and  $i \in \{1, \dots, n\}$  then

$$U_i \cap U_{n+1} = (U'_i \cap V_i) \cap \left( \bigcap_{k=1}^n W_k \right) = U'_i \cap (V_i \cap W_i) \cap \left( \bigcap_{\substack{k \in \{1, \dots, n\} \\ k \neq i}} W_k \right) = \emptyset,$$

since  $V_i \cap W_i = \emptyset$ .

This establishes the properties we were claiming.

(d) The proof is by induction.

Base Case  $n = 2$  : This is the definition of a Hausdorff space. Given  $x_1, x_2 \in X$ ,  $x_1 \neq x_2$  we can find open sets  $U_1$  and  $U_2$  such that  $x_1 \in U_1$  and  $x_2 \in U_2$  and  $U_1 \cap U_2 = \emptyset$ .

Inductive Step : Given distinct  $x_1, \dots, x_n \in X$ , by induction we may assume we have open sets  $U'_1, \dots, U'_n$  such that  $x_i \in U'_i$  for each  $i$ , and  $U'_i \cap U'_j = \emptyset$  if  $i \neq j$ .

Given the point  $x_{n+1}$  (distinct from  $x_1, \dots, x_n$ ), since  $X$  is Hausdorff for each  $i = 1, \dots, n$  there are open sets separating  $x_{n+1}$  and each  $x_i$ . I.e., for each  $i$  there are open sets  $V_i$  and  $W_i$  with  $x_i \in V_i$ ,  $x_{n+1} \in W_i$ , and  $W_i \cap V_i = \emptyset$ .

Applying the construction of part (c) we obtain open sets  $U_1, \dots, U_{n+1}$  with  $x_i \in U_i$  for each  $i = 1, \dots, n + 1$ , and  $U_i \cap U_j = \emptyset$  if  $i \neq j$ , completing the inductive step.

2.

- (a) Suppose that  $(x_1, y_1)$  and  $(x_2, y_2)$  are two distinct points of  $X \times Y$ . Then either  $x_1 \neq x_2$ , or  $y_1 \neq y_2$ , or both. Suppose that  $x_1 \neq x_2$ . Then since  $X$  is Hausdorff there are open sets  $U_1, U_2 \subseteq X$  with  $x_1 \in U_1, x_2 \in U_2$  and  $U_1 \cap U_2 = \emptyset$ .

Then  $U_1 \times Y$  and  $U_2 \times Y$  are open sets of  $X \times Y$ ,  $(x_1, y_1) \in U_1 \times Y$ ,  $(x_2, y_2) \in U_2 \times Y$ , and

$$(U_1 \cap Y) \cap (U_2 \cap Y) = (U_1 \cap U_2) \times Y = \emptyset.$$

The remaining case is that  $x_1 = x_2$  but  $y_1 \neq y_2$ , in which case a similar argument, pulling back open sets from  $Y$ , works.

- (b) Since  $\Delta_X = \{(x, x) \mid x \in X\} \subseteq X \times X$ , and  $q_1(x_1, y_1, x_2, y_2) = (x_1, x_2)$ ,

$$q_1^{-1}(\Delta_X) = \{(x_1, y_2, x_2, y_2) \mid q(x_1, y_1, x_2, y_2) \in \Delta_X\} = \{(x, y_1, x, y_2) \mid x \in X, y_1, y_2 \in Y\}.$$

Similarly

$$q_2^{-1}(\Delta_Y) = \{(x_1, y, x_2, y) \mid x_1, x_2 \in X, y \in Y\}.$$

I.e.,  $q_1^{-1}(\Delta_X)$  is the subset of  $X \times Y \times X \times Y$  where the first and third coordinates are equal, and  $q_2^{-1}(\Delta_Y)$  is the subset where the second and fourth coordinates are equal. Therefore

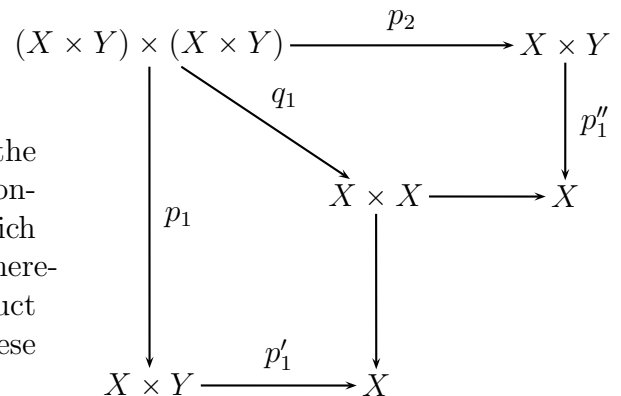
$$q_1^{-1}(\Delta_X) \cap q_2^{-1}(\Delta_Y) = \{(x, y, x, y) \mid x \in X, y \in Y\}$$

which is (under the identification  $(X \times Y) \times (X \times Y) = X \times Y \times X \times Y$ ) the diagonal  $\Delta_{X \times Y}$ .

- (c) We note that each of  $q_1$  and  $q_2$  are continuous maps.

For instance, the composition  $p'_1 \circ p_1$  is the map sending  $(x_1, y_1, x_2, y_2)$  to  $x_1$ , and is continuous, and the composition  $p''_1 \circ p_2$ , which sends  $(x_1, y_1, x_2, y_2)$  to  $x_2$  is continuous. Therefore (by the universal property of the product  $X \times X \dots$ ), the map  $q_1$  obtained from these maps is continuous.

Similarly  $q_2$  is continuous.



If  $X$  and  $Y$  are Hausdorff then  $\Delta_X$  and  $\Delta_Y$  are closed in  $X \times X$  and  $Y \times Y$  respectively. Since  $q_1$  and  $q_2$  are continuous,  $q_1^{-1}(\Delta_X)$  and  $q_2^{-1}(\Delta_Y)$  are then closed in  $(X \times Y) \times (X \times Y)$ .

Since, by (b),  $\Delta_{X \times Y} = q_1^{-1}(\Delta_X) \cap q_2^{-1}(\Delta_Y)$ ,  $\Delta_{X \times Y}$  is closed in the product, and therefore  $X \times Y$  is Hausdorff.

3.

- (a) In **H6 Q3** we have seen that for any point  $(0, y_1) \in X/R$  with  $y_1 \neq 0$ , and any  $\delta < |y_1|$ , that the set  $\{(0, y) \mid |y - y_1| < \delta\}$  is an open set in  $X/R$ . That is, away from  $(0, 0)$ , the topology of  $X/R$  “on the  $y$ -axis” is just like the topology of the  $y$ -axis in  $\mathbb{R}^2$ , and so the usual arguments work to establish the Hausdorff property.

Given  $y_1, y_2$ , with  $y_1 \neq y_2$ , pick  $\delta$  to be strictly less than  $\min(|y_1|, |y_2|, \frac{|y_2 - y_1|}{2})$ . Then the sets

$$U_1 = \{(0, y) \mid |y - y_1| < \delta\} \quad \text{and} \quad U_2 = \{(0, y) \mid |y - y_2| < \delta\}$$

are both open in  $X/R$ , and satisfy  $y_1 \in U_1$ ,  $y_2 \in U_2$ , and  $U_1 \cap U_2 = \emptyset$ .

- (b) As in **H6 Q3**, for each  $\delta > 0$  let

$$V_\delta = \left\{ (0, y) \mid 0 < |y| < \delta \right\},$$

considered (via the quotient map) as a set in  $X/R$ . In the previous homework assignment we have seen that for any point  $(x_1, 0) \in X/R$ , and any  $\delta > 0$  that

$$\{(x, 0) \mid |x - x_1| < \delta\} \cup V_\delta$$

is an open set in  $X/R$ .

Given  $(x_1, 0), (0, y_2) \in X/R$ , with  $y_2 \neq 0$ , let  $\delta = \frac{|y_2|}{3}$ . Then both

$$U_1 = \{(x, 0) \mid |x - x_1| < \delta\} \cup V_\delta$$

and

$$U_2 = \{(0, y) \mid |y - y_2| < \delta\}$$

are open sets of  $X/R$ . By construction  $x_1 \in U_1$  and  $y_2 \in U_2$ . Finally  $U_1 \cap U_2 = \emptyset$ , since by choice of  $\delta$  we know that points of  $U_2$  are at least distance  $2\delta$  from  $(0, 0)$ , while points of  $U_1$  are within distance  $\delta$  of  $(0, 0)$ , and so the two sets cannot meet.

- (c) However, given  $(x_1, 0)$  and  $(x_2, 0)$ , if  $U_1$  and  $U_2$  are open sets of  $X/R$  containing  $(x_1, 0)$  and  $(x_2, 0)$  respectively, then by **H6 Q3(b)**, there is a  $\delta_1 > 0$  such that  $V_{\delta_1} \subseteq U_1$ , and a  $\delta_2 > 0$  such that  $V_{\delta_2} \subseteq U_2$ . Therefore  $U_1 \cap U_2$  contains at least  $V_\delta$ , where  $\delta = \min(\delta_1, \delta_2)$ . In particular it is impossible to separate  $(x_1, 0)$  and  $(x_2, 0)$  by open sets of  $X/R$ .

4.

(a) The map  $\pi$  sends  $x \in X$  to  $[x]$  (the equivalence class of  $x$ ) in  $X/R$ . Therefore

$$(\pi \times \pi)^{-1}(\Delta_{X/R}) = \left\{ (x_1, x_2) \in X \times X \mid [x_1] = [x_2] \right\} = \left\{ (x_1, x_2) \in X \times X \mid x_1 \sim_R x_2 \right\} = \Gamma_R.$$

(b) If  $X/R$  is Hausdorff, then  $\Delta_{X/R}$  is closed in  $(X/R) \times (X/R)$ , and therefore  $\Gamma_R = (\pi \times \pi)^{-1}(\Delta_{X/R})$  is closed in  $X \times X$ .

(c) Let us first suppose that there is a  $t \in \mathbb{R}_{>0}$  such that  $(x_2, y_2) = (tx_1, ty_1)$  then

$$\begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} = \begin{vmatrix} x_1 & y_1 \\ tx_1 & ty_1 \end{vmatrix} = 0$$

(for instance, since the rows are linearly dependent),  $x_1x_2 = t(x_1)^2 \geq 0$ , and  $y_1y_2 = t(y_1)^2 \geq 0$ .

Conversely, suppose that  $(x_1, y_1), (x_2, y_2) \in \mathbb{R}^2 \setminus \{(0, 0)\}$ , and that

$$\begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} = 0.$$

Since the determinant is zero, the rows are linearly dependent. Linear dependence for two vectors means that one is a scalar multiple of the other (including the possibility that the scalar is zero). But, since neither vector is zero, the scalar cannot be zero, and thus each is a non-zero scalar multiple of the other. In particular, there is a  $t \in \mathbb{R}^*$  so that  $(x_2, y_2) = t(x_1, y_1)$ .

If we now assume the other two conditions  $x_1x_2 = t(x_1)^2 \geq 0$ , and  $y_1y_2 = t(y_1)^2 \geq 0$ , then adding them gives  $t(x_1^2 + y_1^2) \geq 0$ . Since  $(x_1, y_1) \neq (0, 0)$ ,  $x_1^2 + y_1^2 > 0$ , and so we can divide and conclude that  $t \geq 0$ . Thus, there is  $t \in \mathbb{R}_{>0}$  so that  $(x_2, y_2) = t(x_1, y_1)$ .

This shows the equivalence of the given algebraic conditions and  $R$ -equivalence in this case.

(d) The subset of  $X \times X$  (where  $X = \mathbb{R}^2 \setminus \{(0, 0)\}$ ) described by the conditions in (c) is a closed subset. Each of the maps

$$f: \begin{array}{ccc} X \times X & \longrightarrow & \mathbb{R} \\ (x_1, y_1, x_2, y_2) & \longmapsto & \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \end{array}$$

$$g: \begin{array}{ccc} X \times X & \longrightarrow & \mathbb{R} \\ (x_1, y_1, x_2, y_2) & \longmapsto & x_1x_2 \end{array}$$

$$h: \begin{array}{ccc} X \times X & \longrightarrow & \mathbb{R} \\ (x_1, y_1, x_2, y_2) & \longmapsto & y_1y_2 \end{array}$$

is continuous. (For instance, each of the coordinate projection maps are continuous, and then one can use the result of **H4 Q1(g)**, applied to  $X \times X$ .)

Thus each of the sets  $f^{-1}(\{0\})$ ,  $g^{-1}([0, \infty))$ , and  $h^{-1}([0, \infty))$  are closed subsets of  $X \times X$ , since  $\{0\}$  and  $[0, \infty)$  are closed subsets of  $\mathbb{R}$ . The subsets  $f^{-1}(\{0\})$ ,  $g^{-1}([0, \infty))$ , and  $h^{-1}([0, \infty))$  are the solutions to the individual conditions in (c). By (c) the intersection of these conditions is  $\Gamma_{\mathbb{R}}$ . Therefore  $\Gamma_{\mathbb{R}}$  is a closed subset of  $X \times X$ .

(e) The other piece of  $\Gamma_{\mathbb{R}}$  is the subset

$$\left\{ (x_1, y, x_2, y) \mid x_1, x_2, y \in \mathbb{R}, y \neq 0 \right\}.$$

Letting  $q_2: \mathbb{R}^4 \rightarrow \mathbb{R}^2$  be the map  $q_2(x_1, y_1, x_2, y_2) = (y_1, y_2)$  as in **Q2**, the subset above is  $q_2^{-1}(\Delta_{\mathbb{R}}) \cap \{(x_1, y_1, x_2, y_2) \mid y_1, y_2 > 0\}$ . That is, the subset above is the intersection of a closed set and an open set.

(f) In this case the subset  $\Gamma_R$  is not closed. Let  $x_1, x_2 \in \mathbb{R}$  be any two numbers with  $x_1 \neq x_2$ . Then for all  $n \geq 1$ ,  $n \in \mathbb{N}$ , the point  $(x_1, \frac{1}{n}, x_2, \frac{1}{n})$  is in the set in (e) above, and so in  $\Gamma_R$ . The limit of this sequence of points (as  $n \rightarrow \infty$ ) is  $(x_1, 0, x_2, 0)$ . This is not in the piece from (e) (since the  $y$ -coordinates are zero), and is not in the other piece of  $\Gamma_R$  since  $x_1 \neq x_2$ . Thus, when  $x_1 \neq x_2$ ,  $(x_1, 0, x_2, 0)$  is a point in  $\overline{\Gamma}_R$  which is not in  $\Gamma_R$ . Thus  $\Gamma_R$  is not closed in  $X \times X$ .