

1. We have  $\mathbf{F}(x, y) = (e^{x^2}, y \sin(\pi x), xy)$ , and  $\mathbf{G}(u, v, w) = (\cos(uv), w - u^2)$ .

(a) The point  $q$  is the point  $\mathbf{F}(1, 1) = (e, 0, 1)$  in  $\mathbb{R}^3$ .

(b) The composite function is  $(\mathbf{G} \circ \mathbf{F})(x, y) = (\cos(e^{x^2} y \sin(\pi x)), xy - e^{2x^2})$ . with derivative matrix

$$\mathbf{D}(\mathbf{G} \circ \mathbf{F}) = \begin{bmatrix} -\sin(e^{x^2} y \sin(\pi x)) y e^{x^2} (2x \sin(\pi x) + \pi \cos(\pi x)) & -\sin(e^{x^2} y \sin(\pi x)) e^{x^2} \sin(\pi x) \\ y - 4x e^{2x^2} & x \end{bmatrix}$$

At the point  $(1, 1)$  this has value  $\mathbf{D}(\mathbf{G} \circ \mathbf{F})(1, 1) = \begin{bmatrix} 0 & 0 \\ 1 - 4e^2 & 1 \end{bmatrix}$ .

(c) We have  $\mathbf{DF} = \begin{bmatrix} 2xe^{x^2} & 0 \\ \pi y \cos(\pi x) & \sin(\pi x) \\ y & x \end{bmatrix}$ , which at the point  $(1, 1)$  has value

$$\mathbf{DF}(1, 1) = \begin{bmatrix} 2e & 0 \\ -\pi & 0 \\ 1 & 1 \end{bmatrix}.$$

Similarly,  $\mathbf{DG} = \begin{bmatrix} -v \sin(uv) & -u \sin(uv) & 0 \\ -2u & 0 & 1 \end{bmatrix}$ , which at the point  $q$  is

$$\mathbf{DG}(q) = \begin{bmatrix} 0 & 0 & 0 \\ -2e & 0 & 1 \end{bmatrix}.$$

(d) Multiplying, we get

$$\mathbf{DG}(q)\mathbf{DF}(1, 1) = \begin{bmatrix} 0 & 0 & 0 \\ -2e & 0 & 1 \end{bmatrix} \begin{bmatrix} 2e & 0 \\ -\pi & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 1 - 4e^2 & 1 \end{bmatrix},$$

as the chain rule guarantees.

2. The way to deal with change of variables is to treat the process as a composition. We have a function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ , written in terms of  $(x, y, z)$  coordinates. We also have

a function  $\mathbf{G}$  which translates from  $(\rho, \alpha, \theta)$  coordinates to  $(x, y, z)$  coordinates. This function is given by

$$\mathbf{G}(\rho, \alpha, \theta) = (\rho \sin(\alpha) \cos(\theta), \rho \sin(\alpha) \sin(\theta), \rho \cos(\alpha)).$$

The function  $\mathbf{G}$  is a function from  $\mathbb{R}^3$  to  $\mathbb{R}^3$ , thinking of the first  $\mathbb{R}^3$  as  $(\rho, \alpha, \theta)$  coordinates, and the second  $\mathbb{R}^3$  as the  $(x, y, z)$  coordinates. When we want to understand  $f$  in terms of the  $(\rho, \alpha, \theta)$  coordinates, we're really talking about the composite function  $f \circ \mathbf{G}$ :

$$\begin{array}{c} \begin{array}{ccccc} & & f \circ \mathbf{G} & & \\ & \curvearrowright & & \curvearrowleft & \\ \mathbb{R}^3 & \xrightarrow{\mathbf{G}} & \mathbb{R}^3 & \xrightarrow{f} & \mathbb{R} \end{array} \\ \\ (2, \pi/4, \pi/3) \cdots \cdots \cdots \rightarrow q \cdots \cdots \cdots \rightarrow f(q) \end{array}$$

At the point  $q$  we're interested in, we know that  $\mathbf{D}f(q) = [ \sqrt{3} \quad \sqrt{12} \quad -1 ]$ .

(a) The derivative matrix for  $\mathbf{G}$  is

$$\mathbf{D}\mathbf{G} = \begin{bmatrix} \sin(\alpha) \cos(\theta) & \rho \cos(\alpha) \cos(\theta) & -\rho \sin(\alpha) \sin(\theta) \\ \sin(\alpha) \sin(\theta) & \rho \cos(\alpha) \sin(\theta) & \rho \sin(\alpha) \cos(\theta) \\ \cos(\alpha) & -\rho \sin(\alpha) & 0 \end{bmatrix},$$

which at the point  $(2, \pi/4, \pi/3)$  gives

$$\mathbf{D}\mathbf{G}(2, \pi/4, \pi/3) = \begin{bmatrix} \frac{1}{2\sqrt{2}} & \frac{1}{\sqrt{2}} & -\frac{\sqrt{3}}{\sqrt{2}} \\ \frac{\sqrt{3}}{2\sqrt{2}} & \frac{\sqrt{3}}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\sqrt{2} & 0 \end{bmatrix}.$$

By the chain rule,  $\mathbf{D}(f \circ \mathbf{G})(2, \pi/4, \pi/3) = \mathbf{D}f(q) \mathbf{D}\mathbf{G}(2, \pi/3, \pi/4)$ , or

$$\begin{aligned} \mathbf{D}(\mathbf{G} \circ f)(2, \pi/4, \pi/3) &= \begin{bmatrix} \sqrt{3} & \sqrt{12} & -1 \end{bmatrix} \begin{bmatrix} \frac{1}{2\sqrt{2}} & \frac{1}{\sqrt{2}} & -\frac{\sqrt{3}}{\sqrt{2}} \\ \frac{\sqrt{3}}{2\sqrt{2}} & \frac{\sqrt{3}}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\sqrt{2} & 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{\sqrt{6}}{4} + \sqrt{2}, & \frac{\sqrt{6}}{2} + 4\sqrt{2}, & -\frac{3}{\sqrt{2}} + \sqrt{6} \end{bmatrix} \end{aligned}$$

from which we can read off that (in this bad notation):

$$\begin{aligned}\frac{\partial f}{\partial \rho}(q) &= \frac{\sqrt{6}}{4} + \sqrt{2}, \\ \frac{\partial f}{\partial \alpha}(q) &= \frac{\sqrt{6}}{2} + 4\sqrt{2}, \text{ and} \\ \frac{\partial f}{\partial \theta}(q) &= -\frac{3}{\sqrt{2}} + \sqrt{6}.\end{aligned}$$

- (b) We want to move from  $(2, \pi/3, \pi/4)$  in direction  $\vec{v} = (v_\rho, v_\alpha, v_\theta)$  so that the instantaneous rate of change of  $f$  is zero. We also want  $v_\rho$  to be zero.

This means (using the expression for the derivative in the direction  $\vec{v}$ ) that we want

$$\left(\frac{\sqrt{6}}{4} + \sqrt{2}\right) 0 + \left(\frac{\sqrt{6}}{2} + 4\sqrt{2}\right) v_\alpha + \left(-\frac{3}{\sqrt{2}} + \sqrt{6}\right) v_\theta = 0.$$

The end result (after multiplying by  $\sqrt{6}$  to make the equation slightly cleaner) is that we want to take  $(0, v_\alpha, v_\theta)$  to be any multiple of the vector

$$(0, 3\sqrt{3} - 6, 3 + 8\sqrt{3}).$$

(The numbers in this question weren't intended to be so awkward – I made a mistake in setting up the problem.)

3.

- (a)  $u_t = b e^{ax+bt}$  and  $u_{xx} = a^2 e^{ax+bt}$ , so it's certainly true that  $u_t = (b/a^2) u_{xx}$ .

(b)

$$\begin{aligned}u_t &= -\frac{1}{2}t^{-3/2}e^{-x^2/t} + x^2t^{-5/2}e^{-x^2/t}, \text{ and} \\ u_x &= -2xt^{-3/2}e^{-x^2/t}, \text{ giving} \\ u_{xx} &= -2t^{-3/2}e^{-x^2/t} + 4x^2t^{-5/2}e^{-x^2/t}\end{aligned}$$

and it's again clear that  $u_t = \frac{1}{4}u_{xx}$ .

- (c) If  $f$  is a  $C^2$  function, then  $f_{xy} = f_{yx}$ . If  $f_x = e^x + xy$  then this gives  $f_{xy} = \frac{d}{dy}f_x = x$ . On the other hand, if  $f_y = e^x + xy$ , then  $f_{yx} = \frac{d}{dx}f_y = e^x + y$ . Since these aren't equal, there is no  $C^2$  function with those  $x$  and  $y$  derivatives.

4. The equation  $x^2 + y^2 = 1$  in  $\mathbb{R}^3$  describes a cylinder of radius 1, with central axis the  $z$ -axis. Slicing with the plane  $x + z = 1$  gives an ellipse contained in that plane.

In order to find a parameterization, we could first just parameterize the  $x$  and  $y$  values in the usual way:

$$\begin{aligned}x(t) &= \cos(t) \\y(t) &= \sin(t)\end{aligned}$$

and then work out what the  $z$  coordinate should be. From the equation  $x + z = 1$ , or  $z = 1 - x$  we see that

$$z(t) = 1 - \cos(t)$$

gives us a parameterization. (For, say  $t \in [0, 2\pi]$ ).

5.

- (a) Since  $1/(x^2 + y^2)$  can be written solely in terms of  $\sqrt{x^2 + y^2}$ , the graph is rotationally symmetric. Restricting to the slice  $y = 0$ , we see that this is the graph of  $z = 1/x^2$ , rotated around the  $z$  axis.



- (b) The parameterized curve satisfies  $(x(t))^2 + (y(t))^2 = e^{2t}(\cos^2(t) + \sin^2(t)) = e^{2t}$ , so  $1/((x(t))^2 + (y(t))^2) = e^{-2t} = z(t)$ , showing that the curve lies on the graph.
- (c) Viewed from above the curve is a spiral with an exponentially increasing radius. From part (b) it lies on the graph. A piece of the curve is sketched on the graph above. (Note: some license was taken with this sketch. The radius increases so quickly that it's difficult to get an accurate sketch showing the features of the curve. In the picture above I increased the rate at which the curve rotates around the origin to be able to show how the curve spirals around on a reasonable piece of the graph.)