## MATH 110 Tutorial 7

A basis is a linearly independent spanning set. This means: If  $\beta_1, \ldots, \beta_n$  is a basis for  $\mathbb{R}^n$ then the vectors  $\beta_1, \ldots, \beta_n$  are linearly independent, and every  $x \in \mathbb{R}^n$  can be written as  $x = c_1\beta_1 + \ldots + c_n\beta_n$  for some real scalars  $c_1, \ldots, c_n$ .

Let  $T : \mathbb{R}^m \to \mathbb{R}^n$  be a linear transformation represented by the matrix A. A basis for the image of T (or A) is the set of pivot columns of A. **Note:** It does *NOT* work to take the pivot columns from  $\operatorname{rref}(A)$ .

Let  $T : \mathbb{R}^m \to \mathbb{R}^n$  be a linear transformation represented by the matrix A. A basis for the kernel of T (or A) is obtained by solving the system Ax = 0 in terms of the free variables.

A subspace V of  $\mathbb{R}^n$  is a subset which:

- 1. Contains the zero vector:  $\vec{0} \in V$ ,
- 2. is closed under scalar multiplication: For  $c \in \mathbb{R}$  and  $\vec{v} \in V$ , we have  $c\vec{v} \in V$ ,
- 3. is closed under vector addition: For  $\vec{v_1}, \vec{v_2} \in V$ , we have  $\vec{v_1} + \vec{v_2} \in V$ .

## Practice Problems.

1. Find a basis for the kernel and image of the following matrices.

(a) 
$$\begin{bmatrix} 1 & 1 & 4 \\ 2 & 2 & 1 \\ 3 & 3 & 0 \end{bmatrix}$$
, (b)  $\begin{bmatrix} 1 & 4 \\ -2 & -1 \\ 3 & 4 \end{bmatrix}$ , (c)  $\begin{bmatrix} 1 & 1 & -2 & 6 \\ 0 & -2 & 4 & 2 \end{bmatrix}$ .

- 2. Let A be an  $n \times n$  matrix. Compare the kernel of A with the kernel of  $A^2$ .
- 3. Is the union of two subspaces a subspace?
- 4. Say something about the image of AB compared to the image of A.
- 5. Prove that every line through the origin in  $\mathbb{R}^3$  is a subspace of  $\mathbb{R}^3$ .
- 6. Challenge. Suppose A is an  $n \times n$  nilpotent matrix, i.e., some positive power of A is zero. Show that the rank of A is at most n/2.

## Things you should know...

- Dot products
  - definition, computation
  - Orthogonality
  - Norms
  - Projection
  - $a \cdot b = ||a|| ||b|| \cos \theta$
- RREF
  - definition, computation
  - zero, one, infinitely many solutions to a system of linear equations
  - rank
- Linear Transformations
  - definition
  - injectivity, surjectivity
  - image, kernel
  - composition
  - matrix multiplication
  - inverting a matrix / linear transformation
- Linear combinations
  - linear independence
  - spanning set
  - bases
  - solving equations
- Subspaces
  - definition
  - identifying subspaces, *e.g.* kernel and image