## Material Covered

An abstract vector space is a set of "vectors" which can be added together and multiplied by scalars in order to yield new vectors. The rules for addition and scalar multiplication have to satisfy a number of axioms in order for the set to count as a vector space. The axioms guarantee that the set will behave "like"  $\mathbb{R}^n$  for some n. Some examples of abstract vector spaces are the  $n \times m$  matrices (denoted by  $M_{n \times m}(\mathbb{R})$ ), continuous infinitely differentiable realvalued functions on  $\mathbb{R}$  (denoted by  $C^{\infty}(\mathbb{R})$ , and polynomials of degree up to n with coefficients in  $\mathbb{R}$  (denoted by  $P_n(\mathbb{R})$ ).

A subspace of a vector space is a subset of the vector space which is "closed" under addition and multiplication by scalars. This means that, for any two vectors v and w in the subspace, and for any scalar c, v + w and cv are both in the subspace. Any subspace of a vector space is a vector space itself.

For any vector space V, a set of vectors  $\{v_1, v_2, \dots, v_n\}$  is said to span V if every vector w in v can be written in the form  $w = c_1v_1 + c_2v_2 + \cdots + c_nv_n$  for some scalars  $c_i$ . A set of vectors  $\{v_1, v_2, \dots, v_n\}$  is said to be linearly independent if the only scalars  $c_i$  for which  $c_1v_1 + c_2v_2 + \cdots + c_nv_n = 0$  are the scalars  $c_1 = c_2 = \cdots = c_n = 0$ . Any subset B of a vector space V is said to be a basis of V if it both spans V and is lineally independent.

A linear transformation (linear map) from one vector space V to another W is a function A such that, for any  $v_1$  and  $v_2$  in V, and any scalar c,  $A(v_1 + v_2) = A(v_1) + A(v_2)$  and  $A(cv_1) = cA(v_1)$ . Differentiation is a linear map from  $C^{\infty}(\mathbb{R})$  to  $C^{\infty}(\mathbb{R})$ . Evaluation at a fixed point is a map from  $C^{\infty}(\mathbb{R})$  to R. Evaluation at two points is a linear map from  $C^{\infty}(\mathbb{R})$  to  $R^2$ . Multiplication by the function  $\sin x$  is a linear map from  $P_n(\mathbb{R})$  to  $C^{\infty}(\mathbb{R})$ .

The dimension of a vector space is defined to be the number of vectors in any basis of that vector space. If S is a linearly independent set of vectors in V, then S will never contain more than dim(V) vectors. If S is a set of vectors that spans V, then S will never contain less than dim(V) vectors.  $\mathbb{R}^n$  is always n-dimensional;  $P^n(\mathbb{R})$  is always (n + 1)-dimensional. Some vector spaces, such as  $C^{\infty}(\mathbb{R})$ , are infinite-dimensional.

If we have a linear map A from V to W, we define the range of A to be the set of all vectors in W which are equal to Av for some v in V. We define the kernel of A to be the set of all vectors v in V for which Av = 0. range(A) is always a subspace of W, and kernel(A) is always a subspace of V.

We call the dimension of the range of A the rank of A, and we call the dimension of the kernel of A the nullity of A. The rank-nullity theorem says that the rank of A plus the nullity of A is equal to the dimension of V (the domain of A). In the case where  $V = \mathbb{R}^n$  and  $W = \mathbb{R}^m$ , this become the standard rank-nullity theorem for matrices.

## **Practice Problems**

- 1. Which of the following are subspaces of the vector space in question? Why or why not?:
  - a) The set of functions f in  $C^{\infty}(\mathbb{R})$  for which  $\int_0^1 f(x) dx = 0$ .
  - b) The set of polynomials in  $P_n(\mathbb{R})$  which are divisible by (x-2).
  - c) The set of invertible matrices in  $M_{n \times n}(\mathbb{R})$ .
  - d) The set  $C^{\infty}(\mathbb{R})$  in the set  $C^{0}(\mathbb{R})$  of continuous functions from  $\mathbb{R}$  to  $\mathbb{R}$ .
  - e) The set of polynomials in  $P_n(\mathbb{R})$  which have degree greater than d (for some d < n).
- 2. Which of the following maps are linear? Why or why not?:

a) The map which sends a polynomial in  $P_n(\mathbb{R})$  to the sum of the coefficients of that polynomial in  $\mathbb{R}$ .

b) The map from  $C^{\infty}(\mathbb{R})$  to itself which sends a function f(x) to f(sin(x)).

c) The map from  $M_{n \times n}(\mathbb{R})$  to  $P_n(\mathbb{R})$  which sends a matrix to its characteristic polynomial.

d) The map from  $C^{\infty}(\mathbb{R})$  to  $\mathbb{R}$  which sends a function f(x) to  $e^{f}(e)$ .

e) The map from  $C^{\infty}(\mathbb{R})$  to  $W_1$  which sends a function f(x) to  $e^f(e)$  ( $W_1$  is the onedimensional "weird" vector space which consists of all real numbers greater than zero and in which addition is multiplication and scalar multiplication is exponentiation).

- 3. Find a basis for each of the following vector spaces:
  - a) The subspace of  $M_{n \times n}(\mathbb{R})$  which consists of all matrices with trace equal to 0.
  - b) The three-dimensional "weird" vector space  $W_3$ .
  - c) The subspace of  $C^{\infty}(\mathbb{R})$  consisting of all functions f for which f''(x) = 0 for all x.
- 4. Let V be the set of functions in  $C^{\infty}(\mathbb{R})$  spanned by  $\{1, \sin x, \cos x, \sin^2 x, \cos^2 x, \sin^3 x, \sin^2 x \cos x, \sin x \cos^2 x, \cos^3 x\}$ . We wish to calculate the dimension of V.
  - a) Prove that V is a subspace of  $C^{\infty}(\mathbb{R})$ .
  - b) Find a linear map A from  $\mathbb{R}^9$  to  $C^{\infty}(\mathbb{R})$  which has range equal to V.
  - c) What is the kernel of A? What is its dimension?
  - d) What does the rank-nullity theorem say about the dimension of V?
- 5. For any two vector spaces V and W, we can define their direct sum  $V \bigoplus W$  to be the vector space of all ordered pairs (v, w) in which v comes from V and w from W. Addition is defined by  $(v_1, w_1) + (v_2, w_2) = (v_1 + v_2, w_1 + w_2)$ , and scalar multiplication by c(v, w) = (cv, cw). For example,  $\mathbb{R}^2 = \mathbb{R} \bigoplus \mathbb{R}$ .

a) If  $\{v_1, \dots, v_n\}$  form a basis of V and  $\{w_1, \dots, w_m\}$  form a basis of W, find a basis of  $V \bigoplus W$ .

- b) If V has dimension n and W has dimension m, what is the dimension of  $V \bigoplus W$ ?
- c) Find a linear map A from V to  $V \bigoplus W$  which has a trivial kernel. What is the range of A?
- d) Find a linear map B from  $V \bigoplus W$  onto W. What is the kernel of B?
- e) What can we say about the map BA from V to W?

## Solutions

1. a) Is a subspace because of properties of integrals.

- b) Is a subspace because is the range of the linear map which multiplies everything by (x-2).
- c) Not a subspace does not contain 0.
- d) Is a subspace because  $C^{\infty}(\mathbb{R})$  and  $C^{0}(\mathbb{R})$  are both vector spaces.

e) Not a subspace - the sum of two polynomials of the same degree can have a smaller degree.

- 2. a) Yes, it is linear, because when you add or scalar multiply polynomials, you add or scale their coefficients .
  - b) Yes, it is linear, because  $(cf + dg)(\sin x) = c(f(\sin x)) + d(g(\sin x))$ .
  - c) No, it is not linear many counterexamples can be found.
  - d) No, it is not linear because sums get sent to products.

e) Yes, it is linear because sums get sent to products in  $\mathbb{R}$ , which are sums in  $W_1$ , same for scalar multiples.

- 3. a) One basis contains  $E_{ij}$  for all  $i \neq j$  together with  $E_{ii} E_{(i+1)(i+1)}$  for  $1 \leq i \leq n-1$ . b) One basis contains  $\begin{bmatrix} 2\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\1 \end{bmatrix}, \text{ and } \begin{bmatrix} 1\\1\\2 \end{bmatrix}$ .
  - c) One basis contains 1 and x.
- 4. a) V is a subspace because it is a set of linear combinations, and the sum or scalar multiple of linear combinations is itself a linear combination.

b) A sends  $e_1$  to 1,  $e_2$  to  $\sin x$ ,  $e_3$  to  $\cos x$ ,  $e_4$  to  $\sin^2 x$ ,  $e_5$  to  $\cos^2 x$ ,  $e_6$  to  $\sin^3 x$ ,  $e_7$  to  $\sin^2 x \cos x$ ,  $e_8$  to  $\sin x \cos^2 x$ , and  $e_9$  to  $\cos^3 x$ 

c) The kernel of A is spanned by  $e_4 + e_5 - e_1$ ,  $e_6 + e_8 - e_2$ , and  $e_7 + e_9 - e_3$ . It has dimension 3.

- d) The dimension of V is 9-3=6.
- 5. a) A basis of  $V \bigoplus W$  is  $\{(v_1, 0), \dots, (v_n, 0), (0, w_1), \dots, (0, w_m)\}$ .
  - b) The dimension of  $V \bigoplus W$  is n + m.
  - c) A sends  $v_i$  to  $(v_i, 0)$ . The range of A is spanned by  $\{(v_1, 0), \dots, (v_n, 0)\}$ .
  - d) B sends  $(v_i, 0)$  to 0, and  $(0, w_j)$  to  $w_j$ . The kernel of B is spanned by  $\{(v_1, 0), \dots, (v_n, 0)\}$ .
  - e) BA sends everything in V to 0.